
RZ/N2L Group

R01AN7181EJ0100

Rev.1.00

Nov.30.2023

RZ/N2L Industrial Network SOM Kit Application Note: OPC UA Server

Introduction

This document describes sample software for running OPC UA server on RZ/N2L.

Target Device

RZ/N2L

Contents

1. Overview	4
1.1 Abstract	4
1.2 Operating Environment	5
1.2.1 Software Environment	5
1.2.2 Hardware Environment.....	6
2. Hardware configuration.....	7
2.1 Board Settings	7
3. Sample Software	8
3.1 Folder structure	8
3.2 Boot Sequence	9
3.3 OPC UA Stack.....	10
3.3.1 OPC UA.....	10
3.3.2 Information Model.....	10
3.3.3 open62541.....	11
3.3.4 Restrictions.....	11
3.4 Installation of Development Environment.....	12
3.4.1 e ² studio.....	12
3.4.1.1 Install	12
3.4.1.2 Project start-up	16
3.4.2 UaExpert.....	21
3.4.3 Wireshark	21
4. Operation check	22
4.1 Connection	22
4.2 IP Address Settings	22
4.3 Start Project.....	24
4.3.1 Build.....	24
4.3.2 Debug Configurations.....	26
4.3.3 Debug	29
4.4 OPC UA Communication Check	33
5. Appendix	35
5.1 File Generation of open62541	35
5.1.1 Linux environment Setup.....	35
5.1.2 Install CMake.....	37
5.1.3 open62541 File Generation.....	38
5.1.4 Changes in Generated Files.....	42
5.2 FSP Configuration for VSC8531 and SSC port.....	43

List of Abbreviations and Acronyms

In this document, the terms below are defined as follows:

Terms	Description
FSP	Flexible Software Package
SOM Kit	RZ/N2L Industrial Network SOM Kit
OPC UA	Open Platform Communications Unified Architecture
XML	Extensible Markup Language

Related documents

Document Type	Document Title	Document No.
Data Sheet	RZ/N2L Group Datasheet	R01DS0397EJ****
User's Manual	RZ/N2L Group User's Manual: Hardware	R01UH0955EJ****
User's Manual	RZ/N2L Industrial Network SOM Kit User's Manual	R12UT0020ED****
Application Note	RZ/N2L Group TCP/IP lwIP Sample Program Package	R01AN6588EJ****

1. Overview

1.1 Abstract

OPC UA, which enables interoperability of industrial applications, is becoming widely used not only in factory automation but also in various industries.

This document describes the sample software configuration and its usage to realize OPC UA server on RZ/N2L, which are the RZ processor for industrial networks.



Fig 1-1 RZ/N2L Industrial Network SOM Kit

1.2 Operating Environment

1.2.1 Software Environment

The operating environment of this sample software is shown in Table 1-1.

Table 1-1 Operating Environment

Category	Name	Version	Link	Remarks
RZ/N2L OPC UA server sample software	Sample Package	1.0.1		
IDE	e ² studio	23.4.0	https://github.com/renesas/rzn-fsp/releases/download/v1.2.0/setup_rznfsp_v1_2_0_e2s_v2023-04.exe	Included with e ² studio installer
Flexible Software Package	FSP	1.2.0		Included with e ² studio installer
GNU Arm Embedded Toolchain	GCC Toolchain	V9.3.1.20200408 (*1)		Included with e ² studio installer
OPC UA Client Tool	UaExpert	1.7.1	OPC UA Clients - Unified Automation (unified-automation.com)	
Packet analyzer	Wireshark	4.0.7	Wireshark · Download	

(*1). V10.3.1.20210824 is also installed when installing e² studio, but we recommend using V9.3.1.20200408.

1.2.2 Hardware Environment

This sample software is tested under the hardware environment of Table 1-2.

Table 1-2 Hardware Environment

Name	Type Name	Maker	Link	Note
RZ/N2L Industrial Network SOM Kit	YCONNECT-IT-RZN2L	Renesas Electronics	www.renesas.com/yconnect-it-rzn2l	SOM Kit

2. Hardware configuration

This section describes the hardware configuration of executing the sample software.

2.1 Board Settings

When executing the sample software, configure the SOM Kit settings in Fig 2-1.

- SW1: ON
- J2: 2-3 Short: Use SD-RAM as external memory

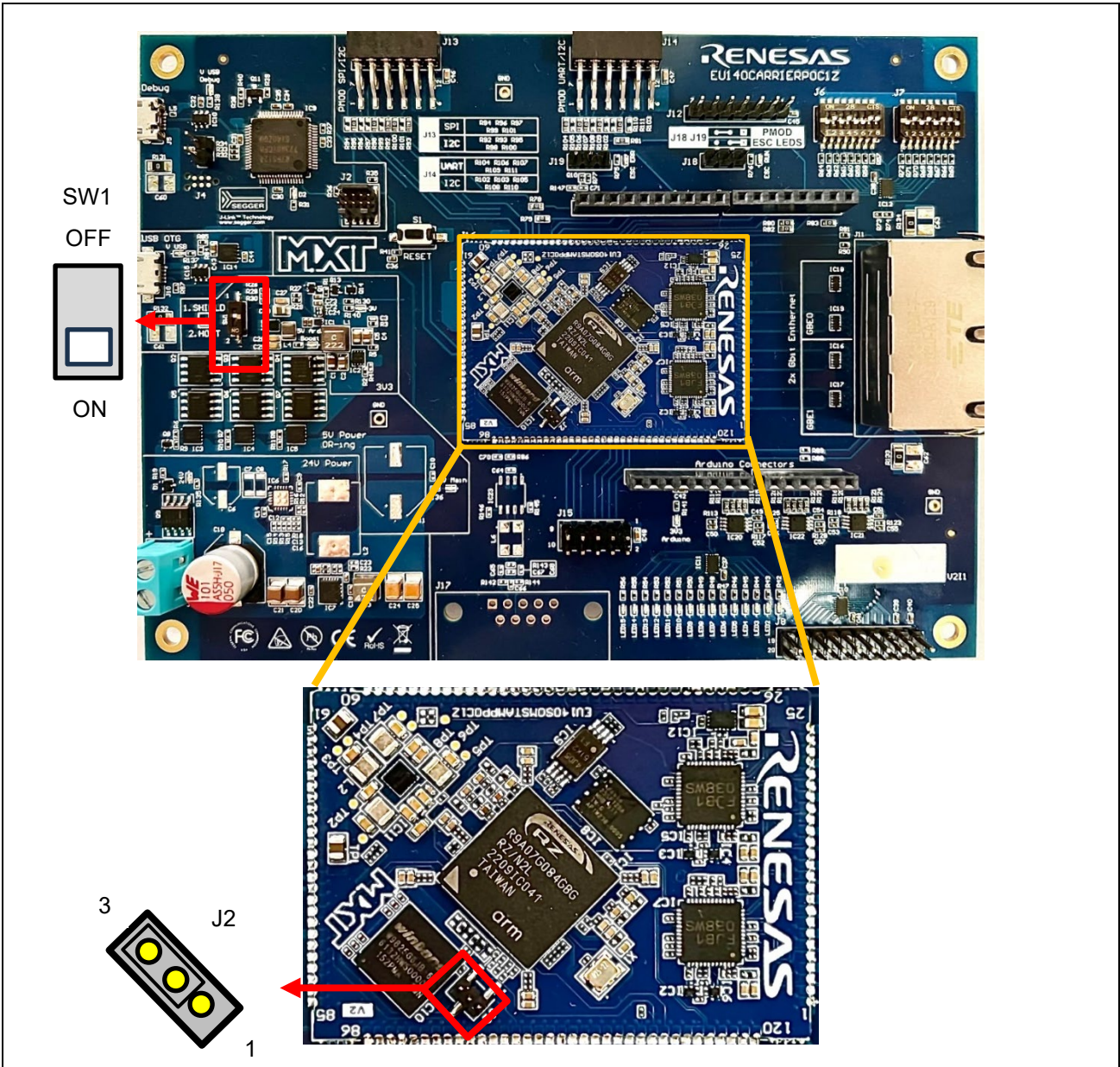


Fig 2-1 Board Configuration

3. Sample Software

This chapter describes the structure and usage of the sample software.

3.1 Folder structure

The folder structure of the sample software is shown below. As a guide, the bolded text indicates folders containing files that users will customize with this sample software.

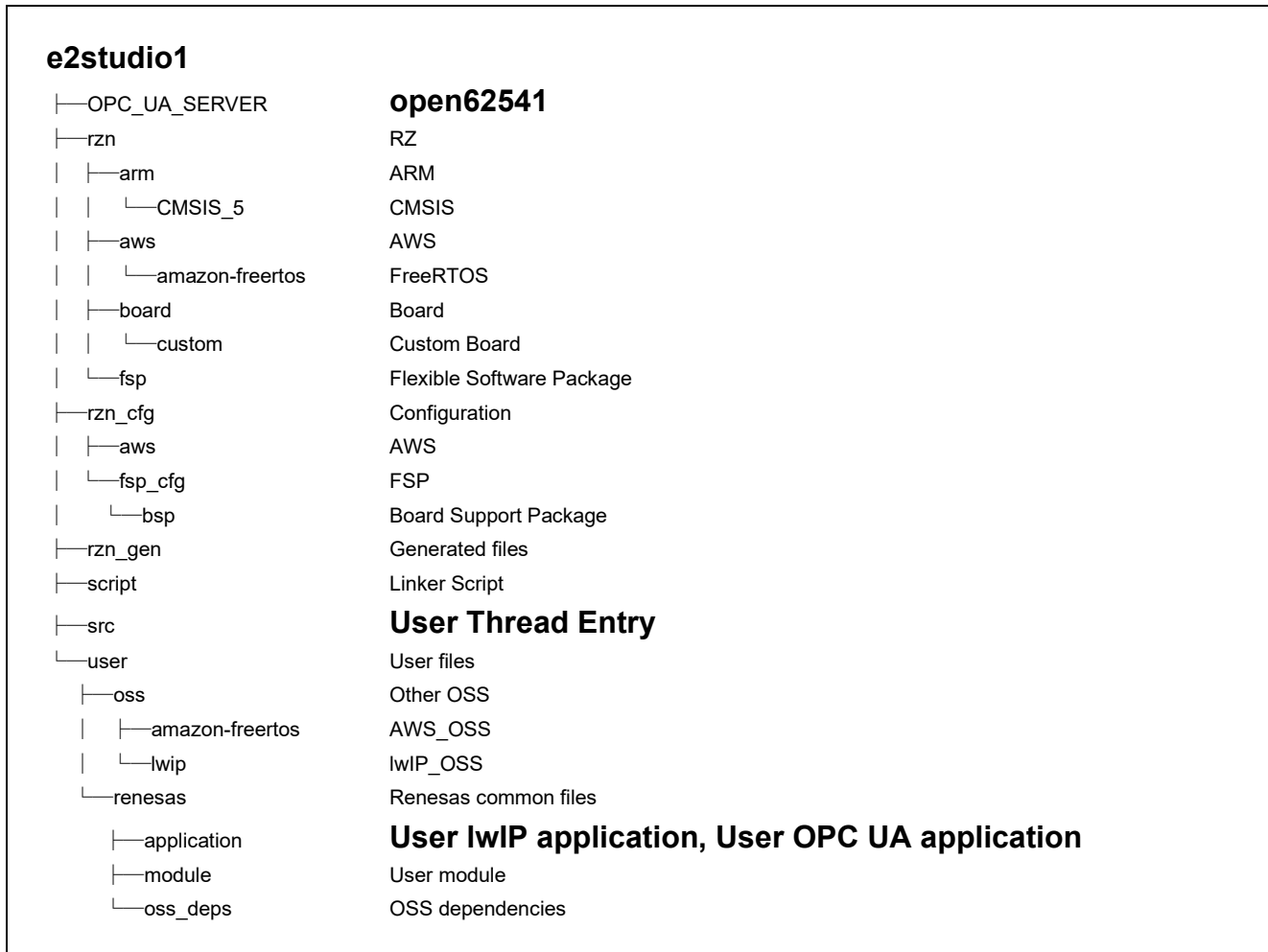


Fig 3-1 Folder Structure

3.2 Boot Sequence

Describes the boot procedure and memory allocation.

The boot mode of this sample software is xSPI0 x1 boot mode. The figure below shows the BSP tag in the Smart Configurator.

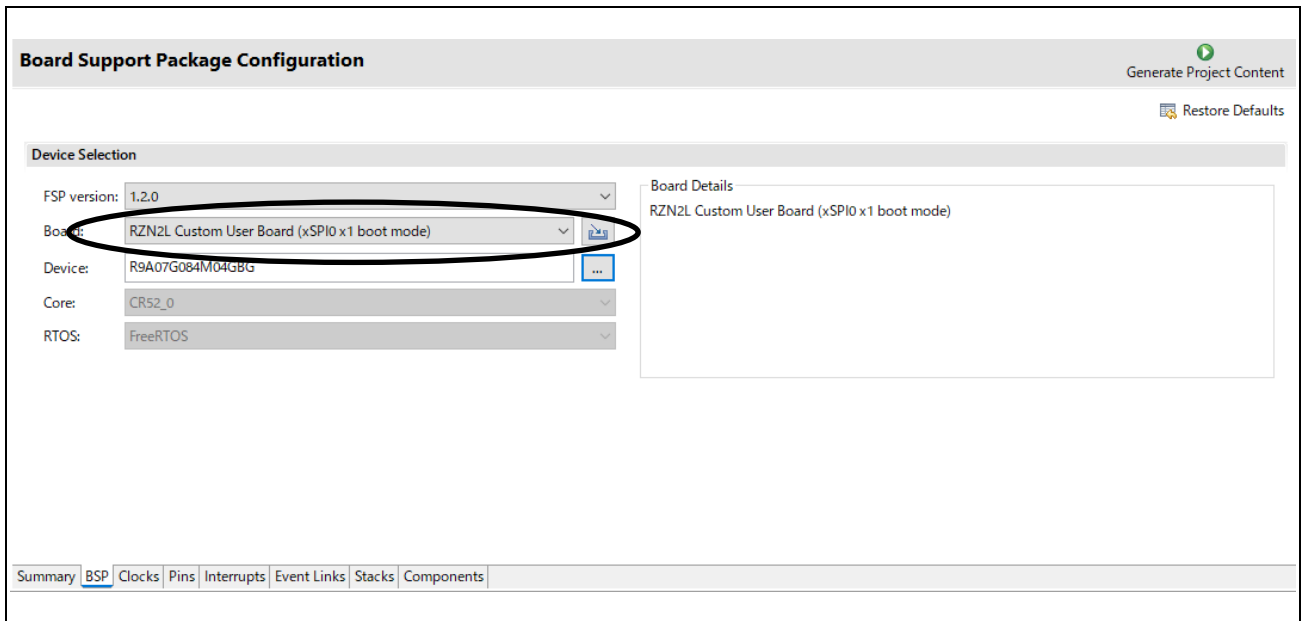


Fig 3-2 Boot mode

After downloading the program to the flash memory, the board operates independently by pressing the RESET button on the SOM Kit or turning the power ON without a debugger connection. You can still connect the debugger for evaluation.

3.3 OPC UA Stack

3.3.1 OPC UA

OPC UA was developed by the OPC Foundation as an open communication standard to realize secure and reliable data exchange for various industries including the industrial automation field. OPC Classic, the predecessor of OPC UA, was Windows-based, but OPC UA is now multi-platform and able to run on various platforms from Windows systems including cloud computing to RTOS for field devices.

This sample software implements the open source open62541 protocol stack on FreeRTOS, which is provided as sample software for RZ/N2L.

3.3.2 Information Model

To achieve interoperability among vendors and industries, OPC UA provides a unified data model called the "Information Model" in xml file format. It includes built-in models commonly used in OPC UA, companion models used by each industry or organization, and vendor-specific models that can be customized by each vendor. (Fig 3-3)

In this sample software, the .xml file of the information model is converted to C language code. For details, please refer to chapter 5.1.

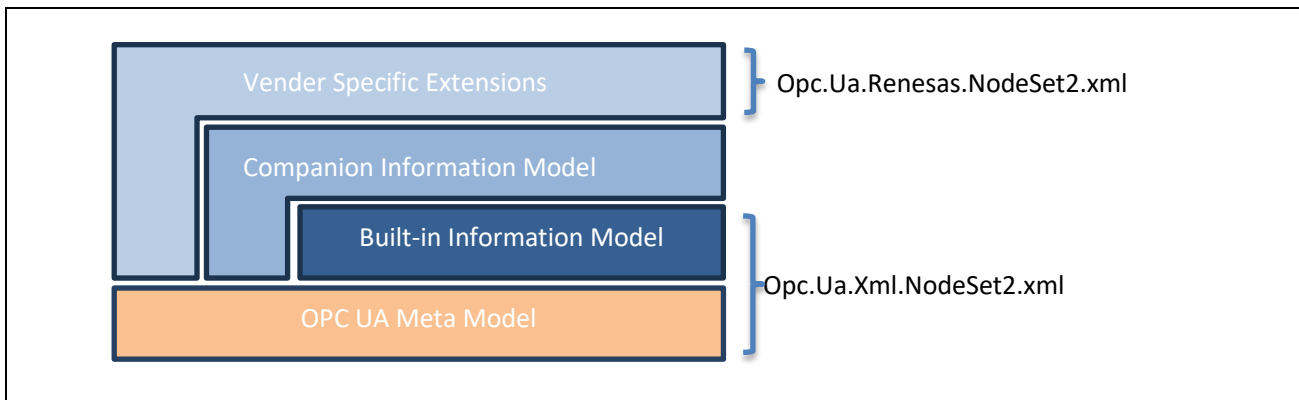


Fig 3-3 Information Model

(1) Opc.Ua.Xml.NodeSet2.xml

It provides the "Meta Model", which is a set of rules for describing the OPC UA information model, and the "Built-in Information Model", which is the basic information model of OPC UA described by the Meta Model.

In this sample software, the following versions are applied.

The OPC UA XML version 1.05.01 ([UA-Nodeset/XML/Opc.Ua.Xml.NodeSet2.xml at d1bb6a22125bd7cd986272b1ee98a18a91d76fff · OPCFoundation/UA-Nodeset · GitHub](https://github.com/OPCFoundation/UA-Nodeset))

(2) Opc.Ua.Renesas.NodeSet2.xml

This is one of the information models made for this sample software. The OPC UA modeler "SiOME" is used for creation. For details, please refer to the following link.

[Siemens OPC UA Modeling Editor \(SiOME\) - ID: 109755133 - Industry Support Siemens](#)

3.3.3 open62541

This sample software adopts the open source open62541 as the protocol stack for the OPC UA server. For more information on open62541, refer to the following Link.

[open62541](#)

(1) Version

Base version of open62541 in this sample software is the following.

Base Version : v1.3.4-564-gb7e5e49f3

(commit b7e5e49f32d00490be74c2eacef892c7fbd0be60)

(2) License

The license terms for the open62541 are MPL v2.0.

Please refer <https://www.mozilla.org/en-US/MPL/2.0/> for more information and comply with the license terms and conditions.

(3) open62541 files

To run open62541 in the environment of freeRTOS + LwIP, the method to generate open62541.c and open62541.h files using CMake as described in the following link is applied

[Building open62541 — open62541 1.3.0-dirty documentation](#)

For more information, please refer to chapter 5.1 in the Appendix.

3.3.4 Restrictions

The released version V1.0.x of this sample software has the following restrictions.

- ✓ Not supported for security certificates.
- ✓ Not supported for NTP client.

3.4 Installation of Development Environment

3.4.1 e² studio

3.4.1.1 Install

Download the version listed in Table 1-1 and install it on your PC. The latest version has a downloadable installer that includes FSP, e² studio, and the GCC toolchain as a single package.

Note) Replace the version in the following figures to be installed version.

- Double-click the downloaded “setup_rz*fsp_v1_2_0_e2s_v2023-04.exe”.

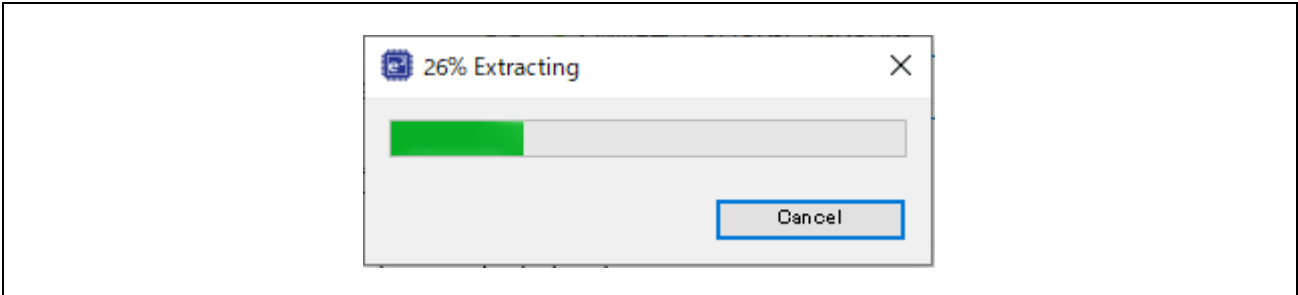


Fig 3-4 e² studio Install (1)

- Select Users

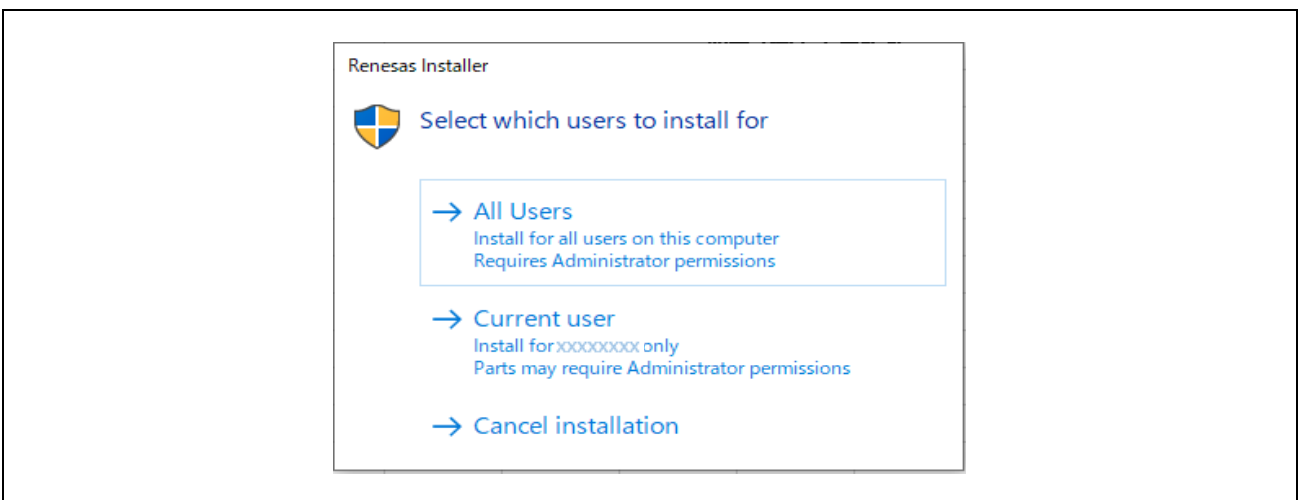


Fig 3-5 e² studio Install (2)

- Select Install Type

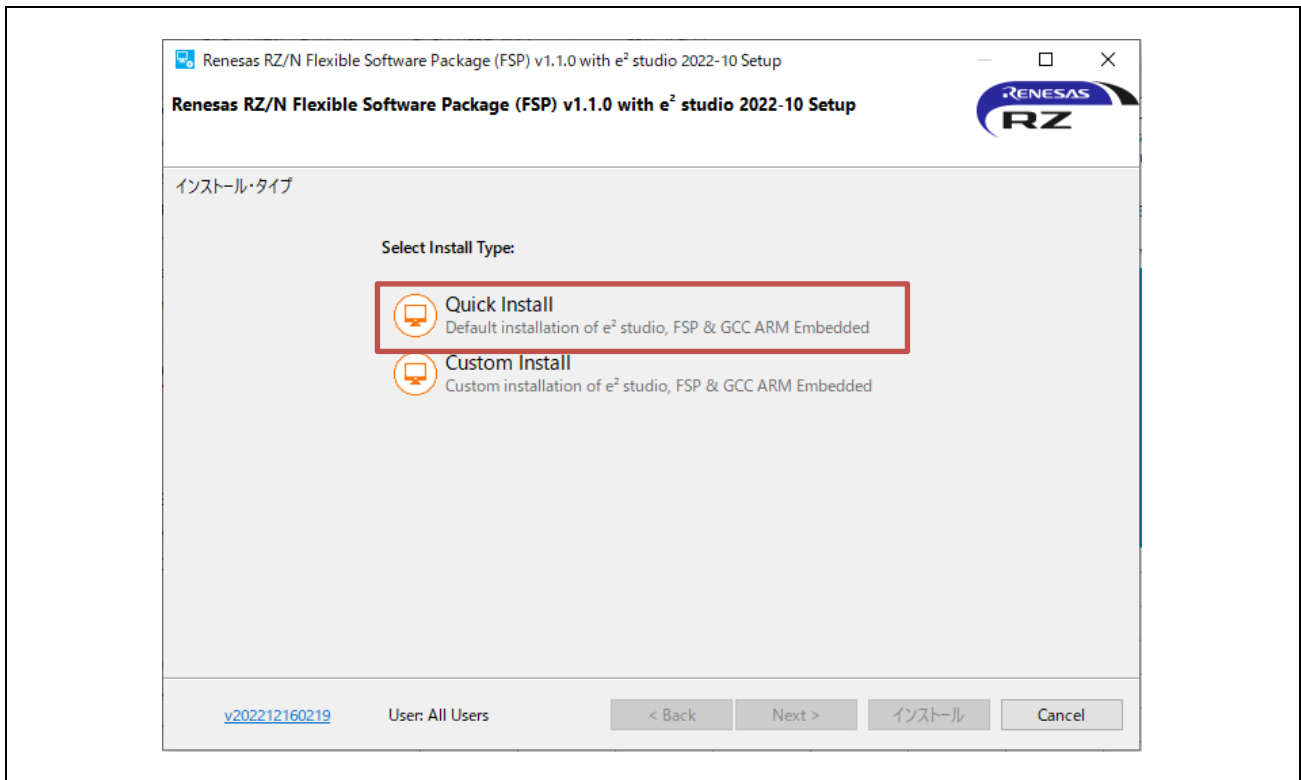


Fig 3-6 e² studio Install (3)

- Select Install folder

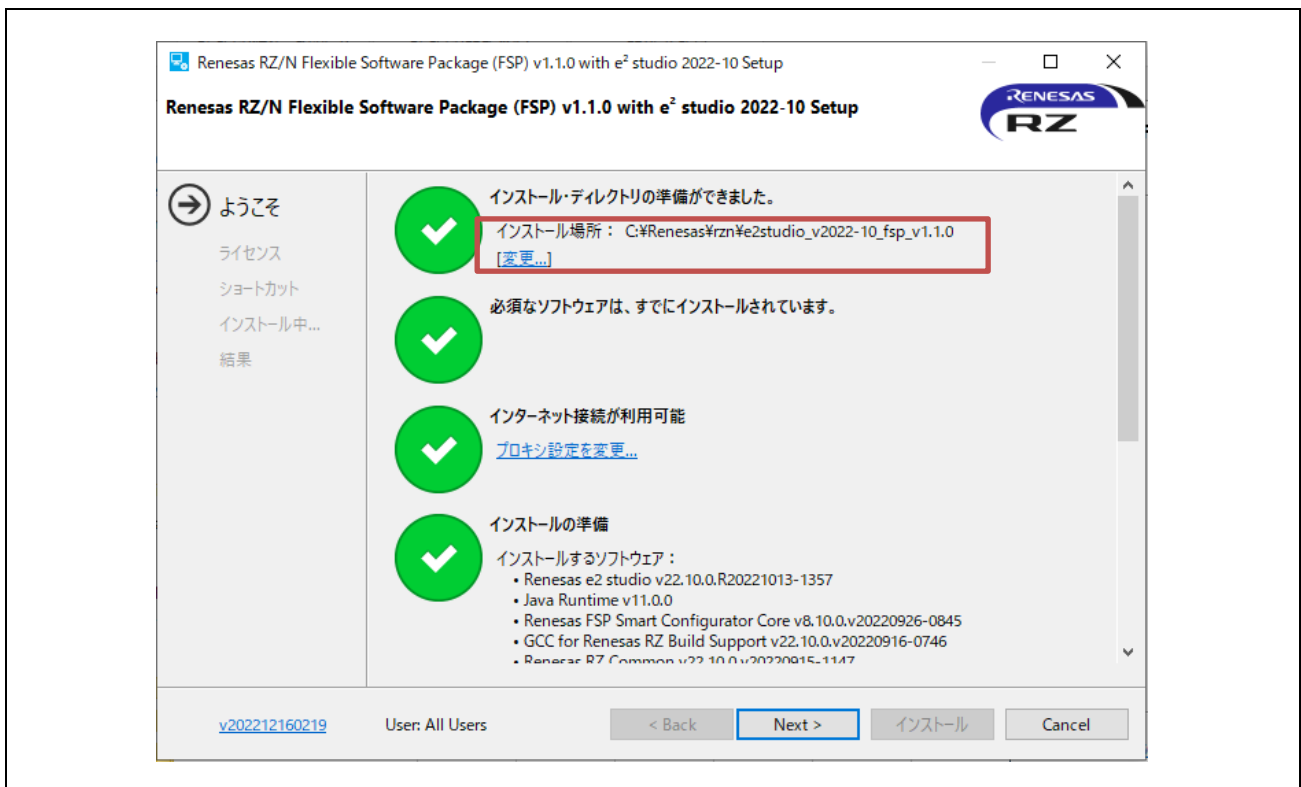


Fig 3-7 e² studio Install (4)

- Check and Click “Next”

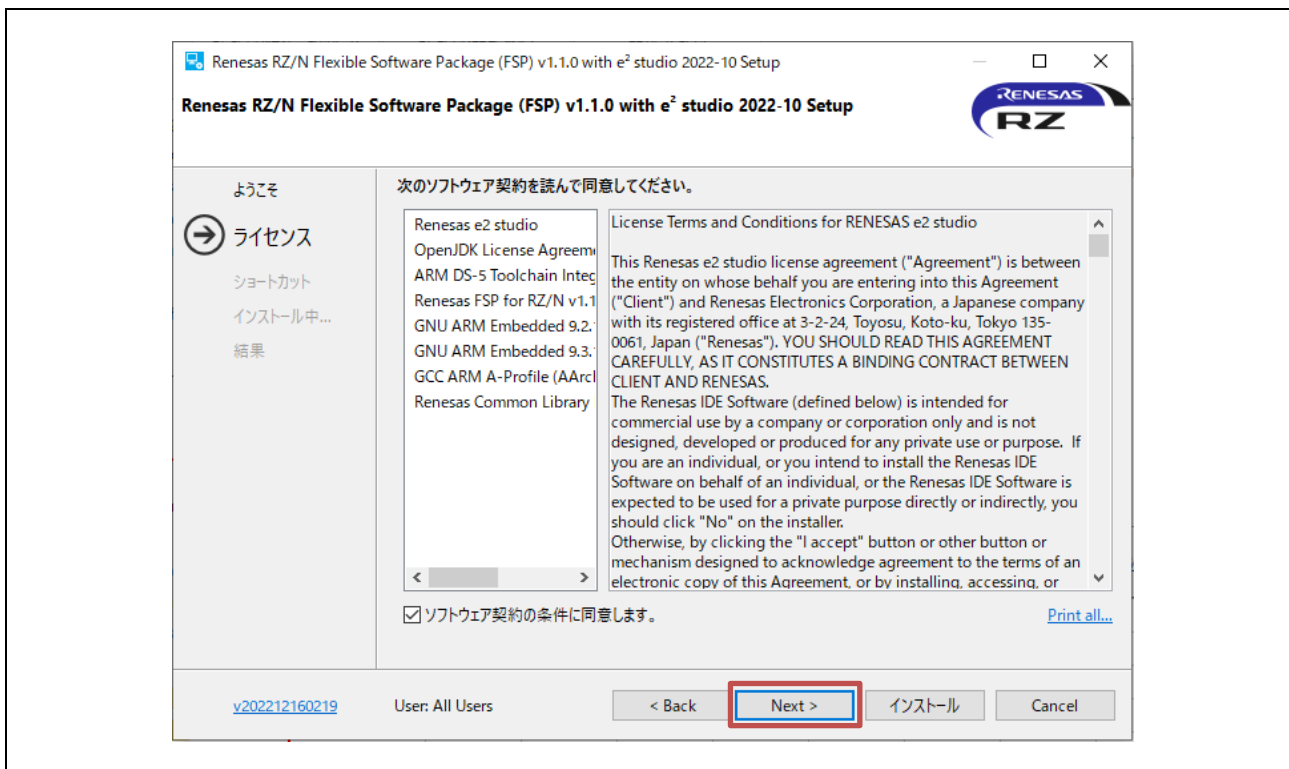


Fig 3-8 e² studio Install (5)

- Click “Install”



Fig 3-9 e² studio Install (6)

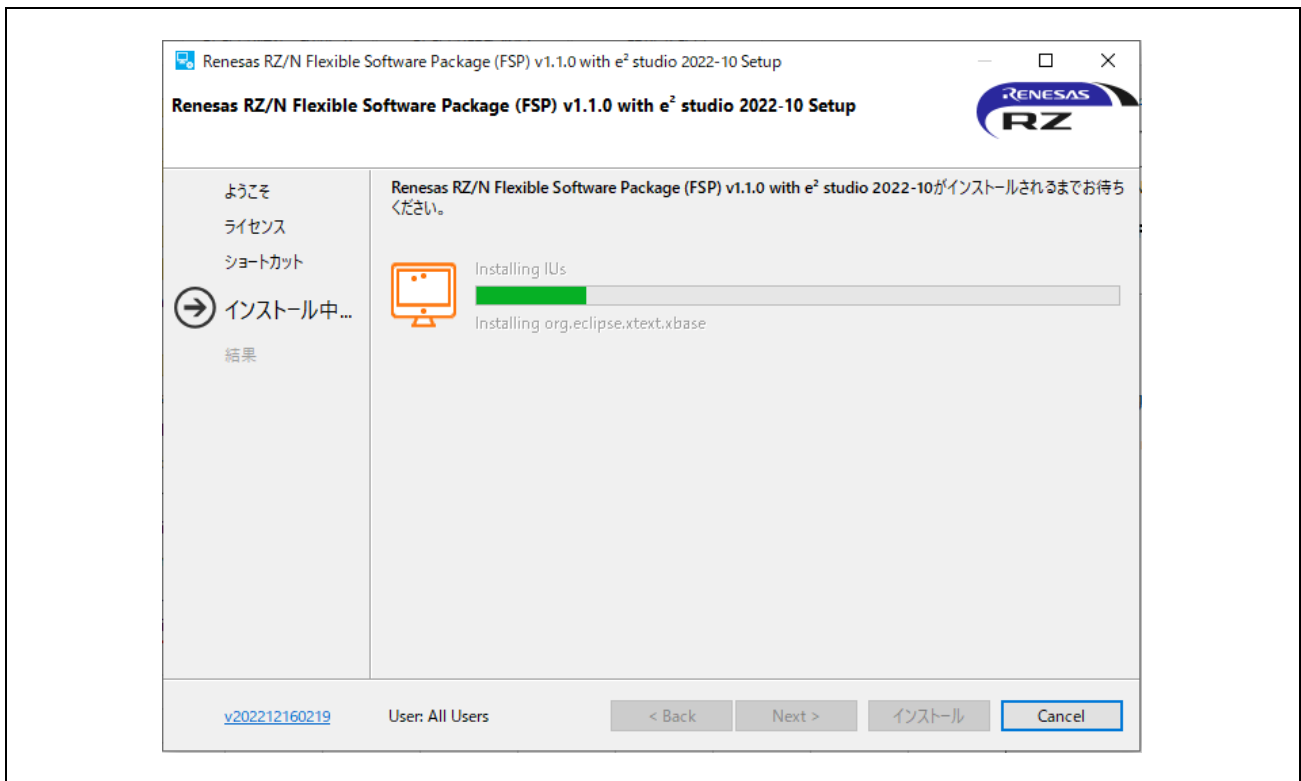


Fig 3-10 e² studio Install (7)

• Click "OK"

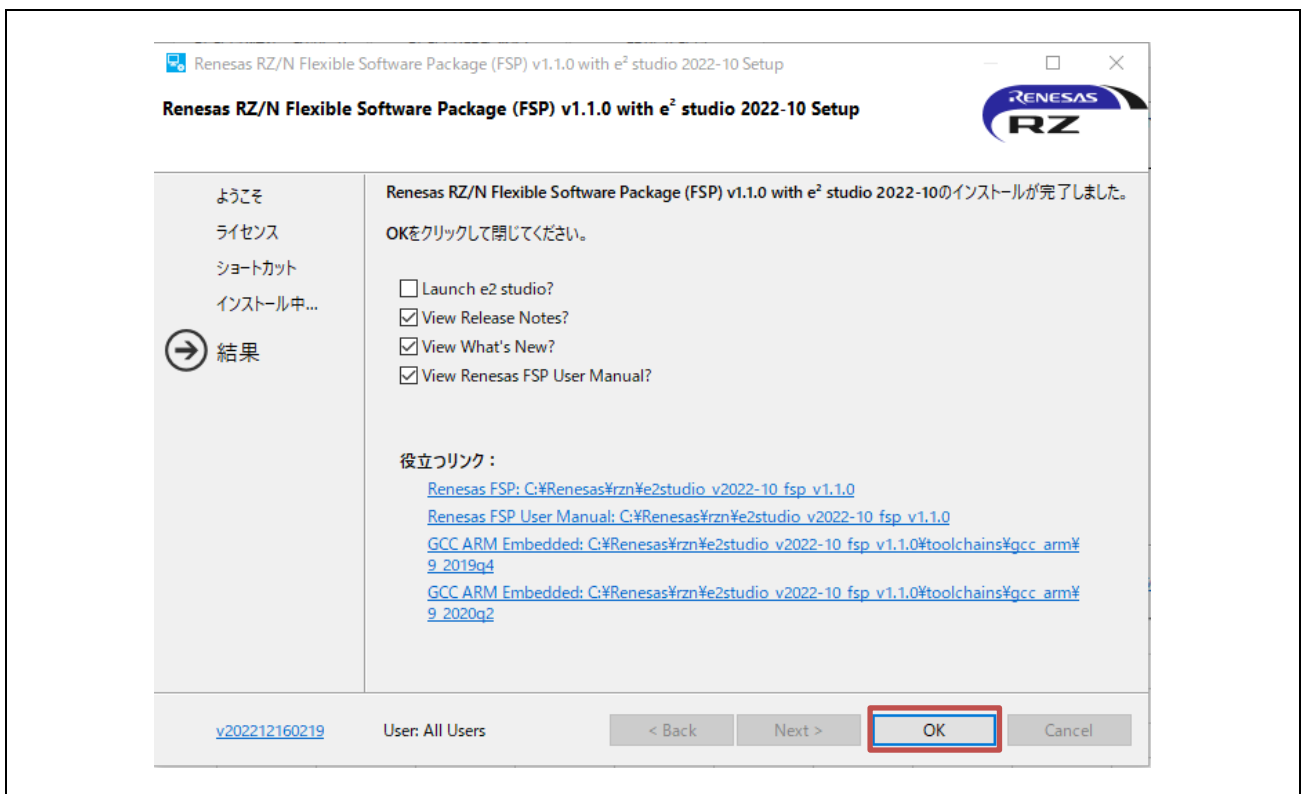


Fig 3-11 e² studio Install (8)

3.4.1.2 Project start-up

(1) Unzip package

First, unzip the archived sample software package and store it in any folder. Because e² studio cannot recognize project properly if file path is too long in the folder hierarchy, place it in shorter path. Also, do not use multi-byte character, such as Japanese, in the folder path.

(2) Execute e² studio

Execute "e2studio.exe" to start e² studio in the following folder (default case) installed:

\\Renesas\rzn\le2studio_v2023-04_fsp_v1.2.0\eclipse\#e2studio.exe

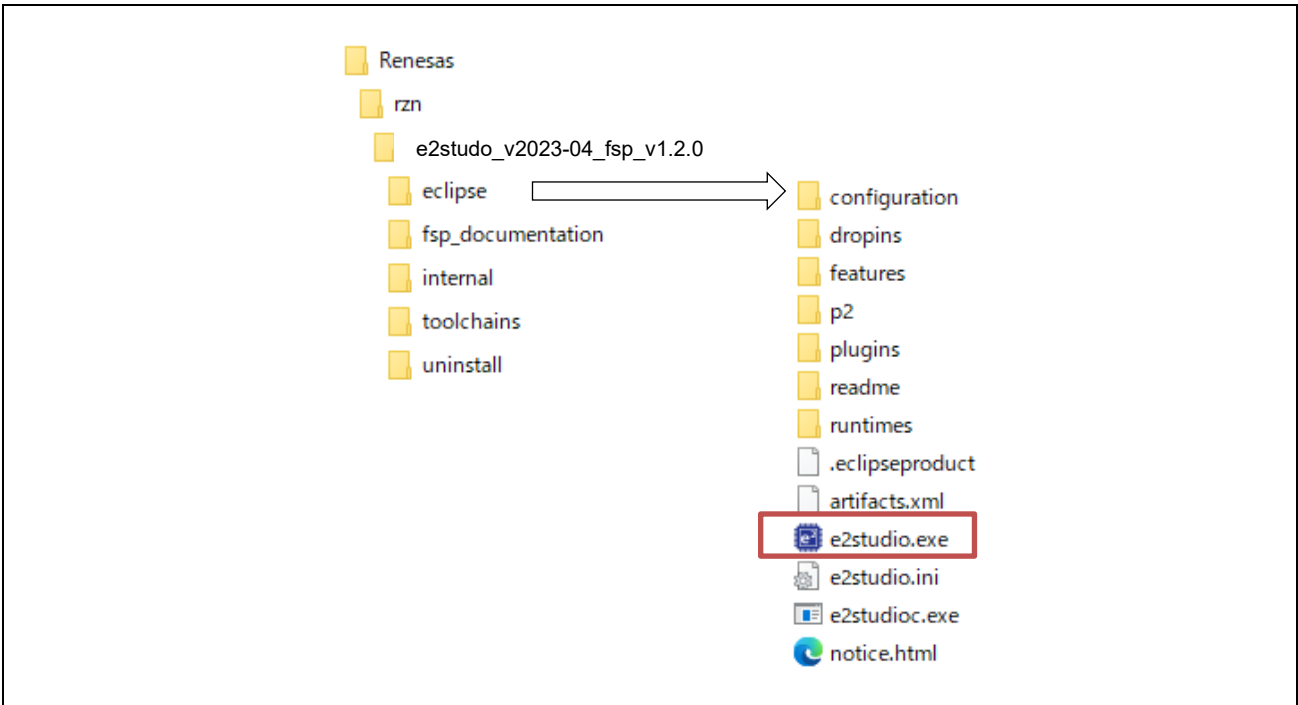


Fig 3-12 Launch project (1)

(3) Import Project

Enter any workspace directory and click “Launch”.

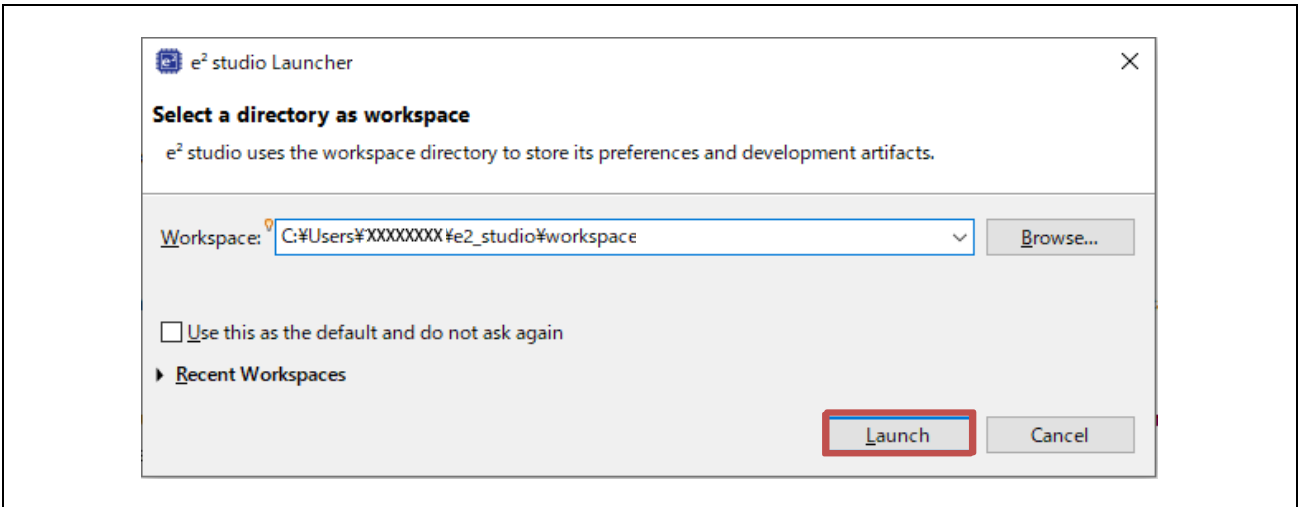


Fig 3-13 Launch project (2)

Select the toolchain “GNU ARM Embedded – 9.3.1.20200408”

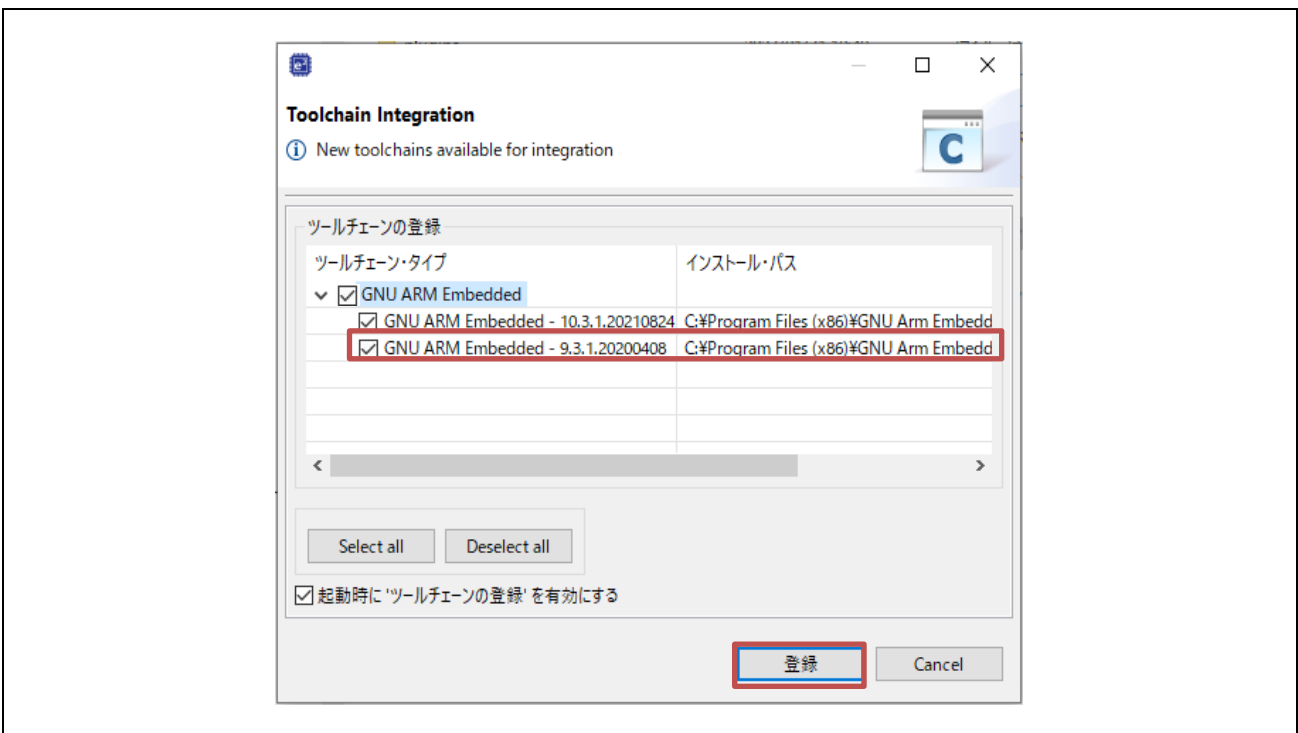


Fig 3-14 Launch project (3)

- Select “Import existing projects”

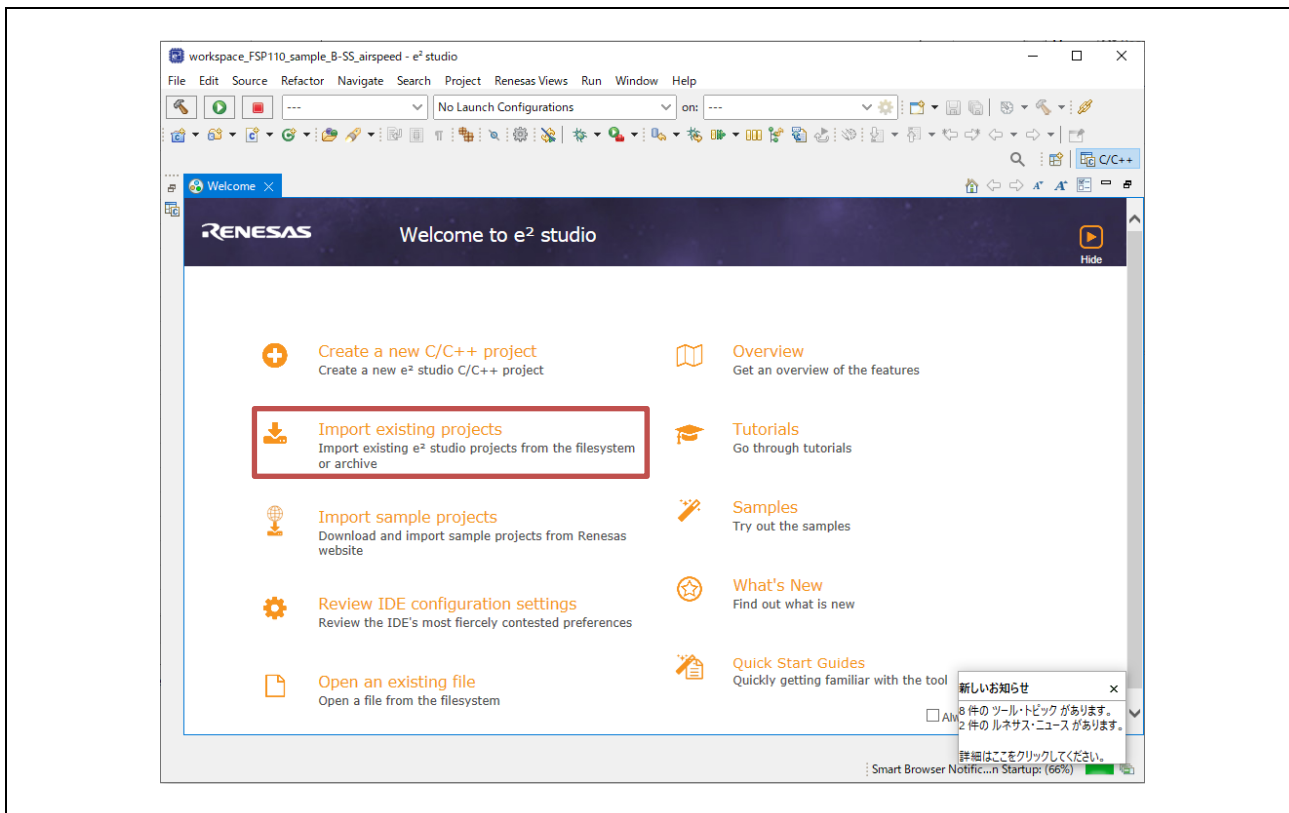


Fig 3-15 Launch project (4)

Click "Browse" at "Select root directory" and enter the project folder to be imported.

Check the "Copy projects into workspace" checkbox to copy the import project.

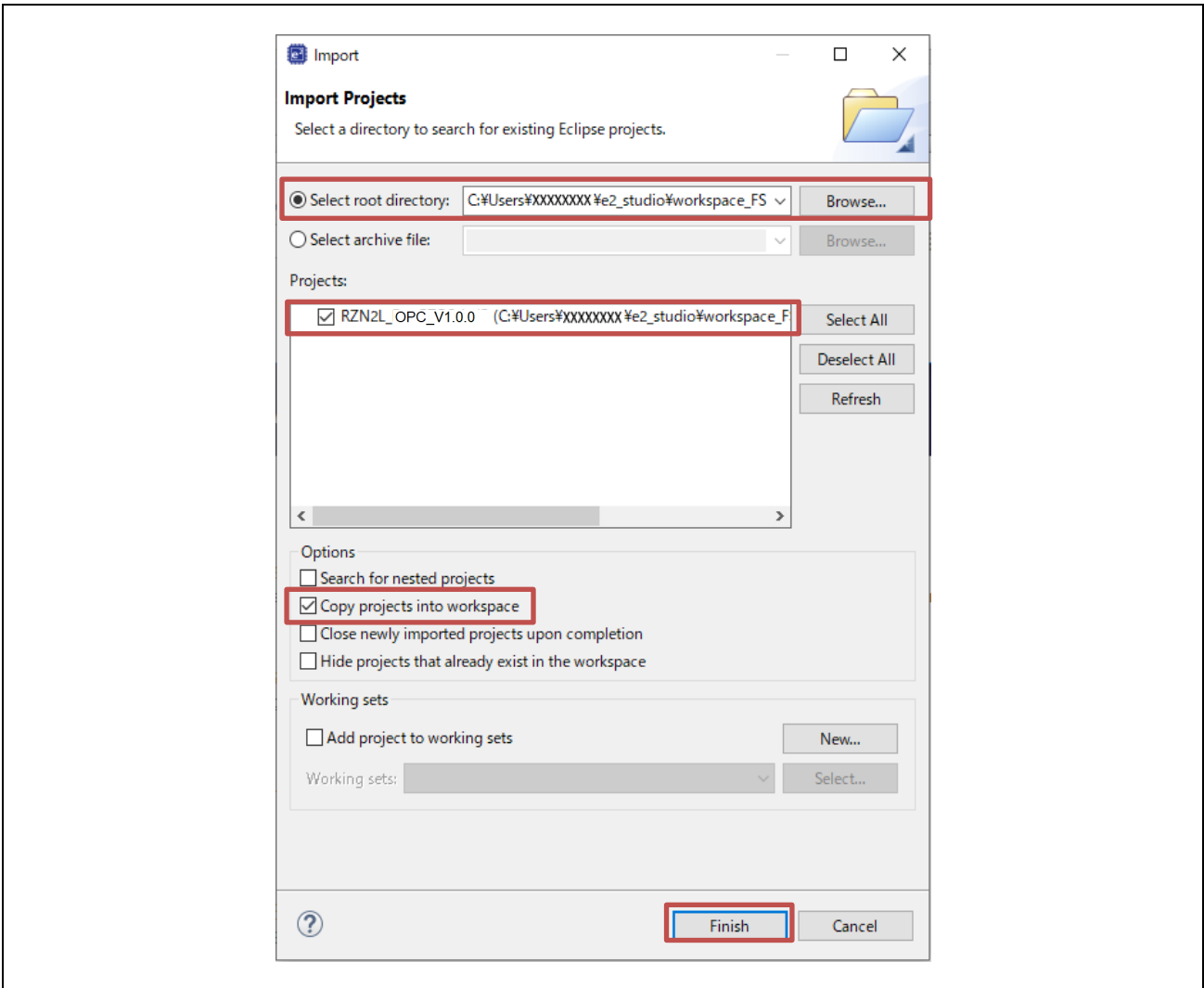


Fig 3-16 Launch project (5)

Click "Finish" in Fig 3-16 to display the following and click "Yes To All".

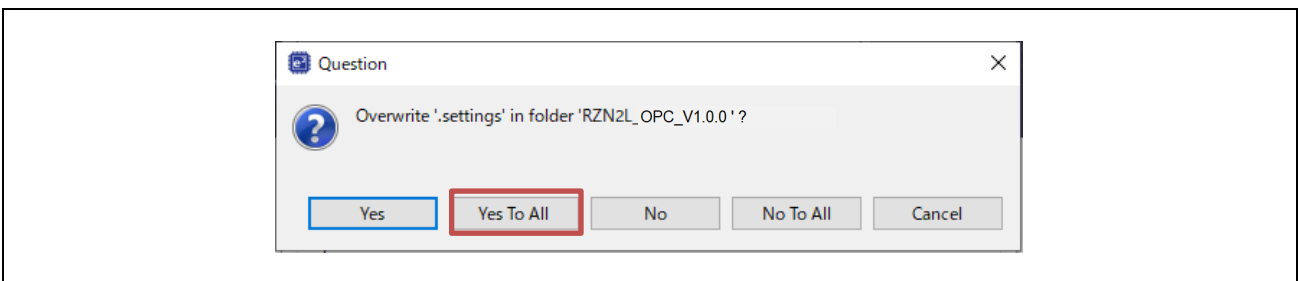


Fig 3-17 Launch project (6)

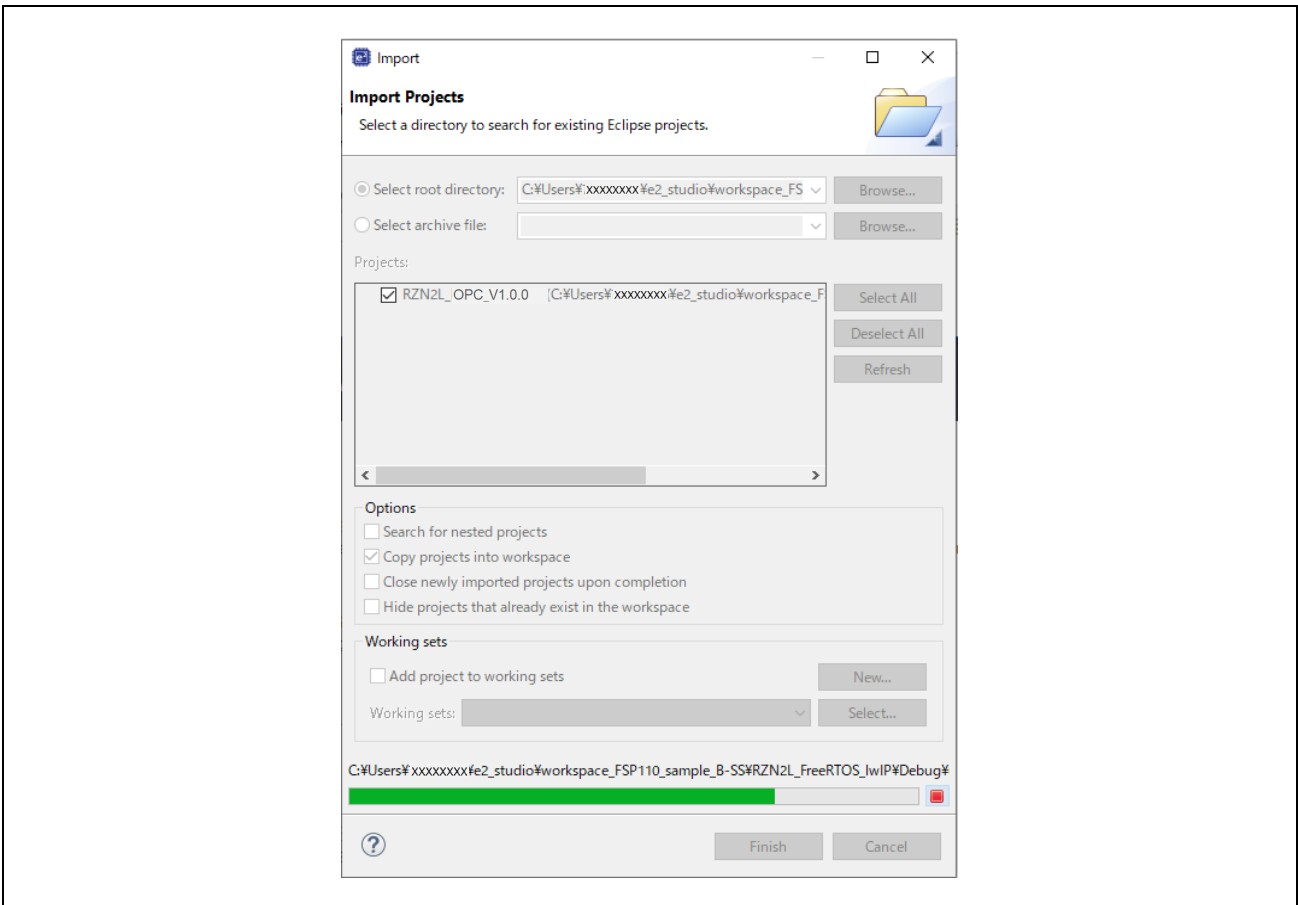


Fig 3-18 Launch project (7)

• When the project import is complete, the following will be displayed. The subsequent sections will be explained in chapter 4.3.1.

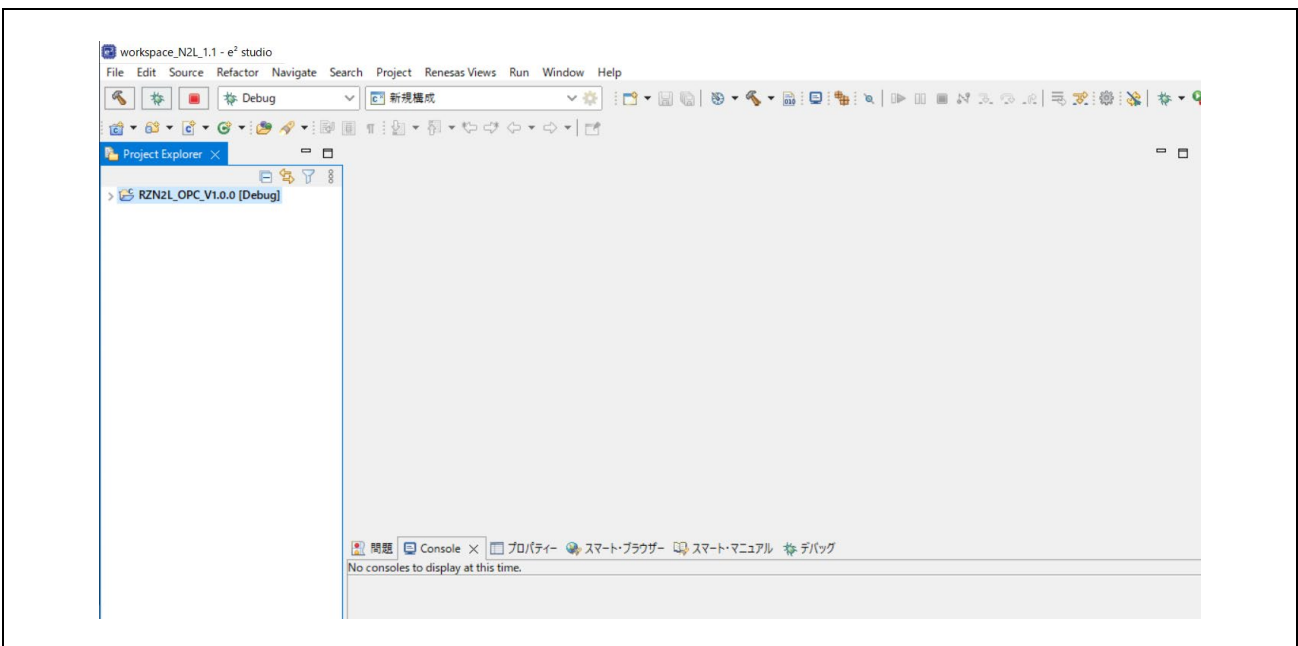


Fig 3-19 Launch project (8)

3.4.2 UaExpert

UaExpert is an OPC UA client tool. In this document, it is used to connect to the OPC UA server to access the object nodes.

Download the version listed in Table 1-1 from the website and install it on your PC. Before downloading, you must register on the Unified Automation website and activate your account. All content is provided free of charge, but by downloading or installing the software from this web page, you automatically accept the Unified Automation Software License Agreement (SLA). For license terms for software and information, please refer to the following link.

<https://www.unified-automation.com/products/sdk-overview/licenses.html#c341>

Please check the above conditions of use before usage.

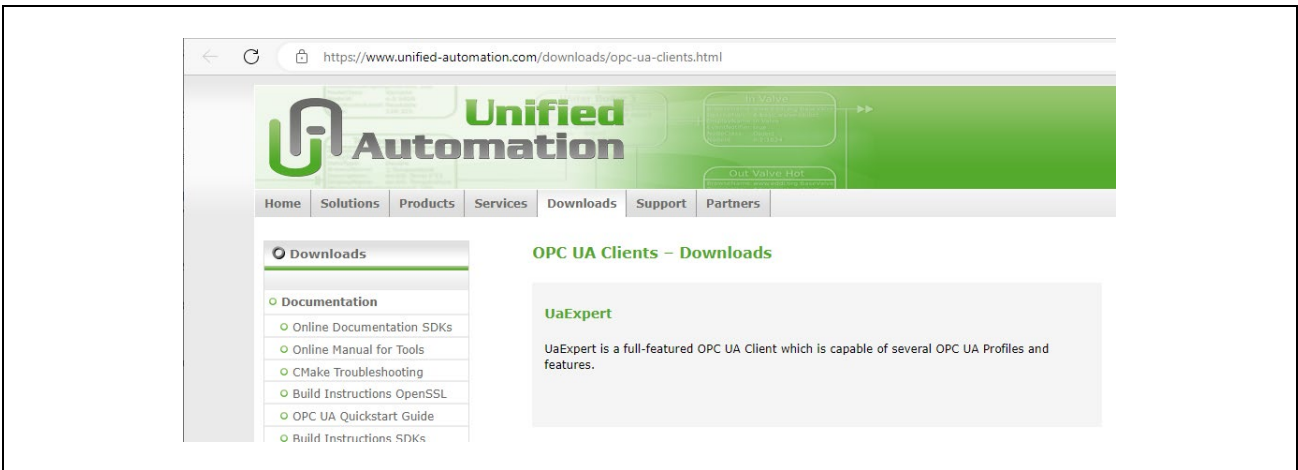


Fig 3-20 UaExpert

3.4.3 Wireshark

Wireshark is a free network protocol analyzer. Download and install Wireshark from the link in Table 1-1.

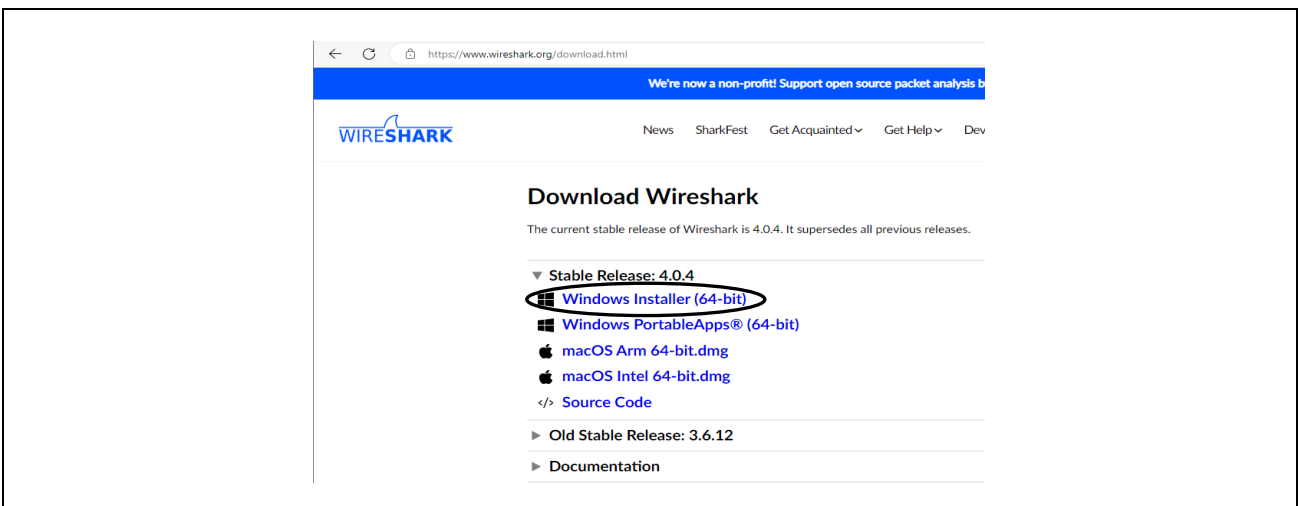


Fig 3-21 download Wireshark

4. Operation check

4.1 Connection

Fig 4-1 shows a connection diagram when running the sample software. Connect PC and SOM Kit with Ethernet cable and USB micro cable.

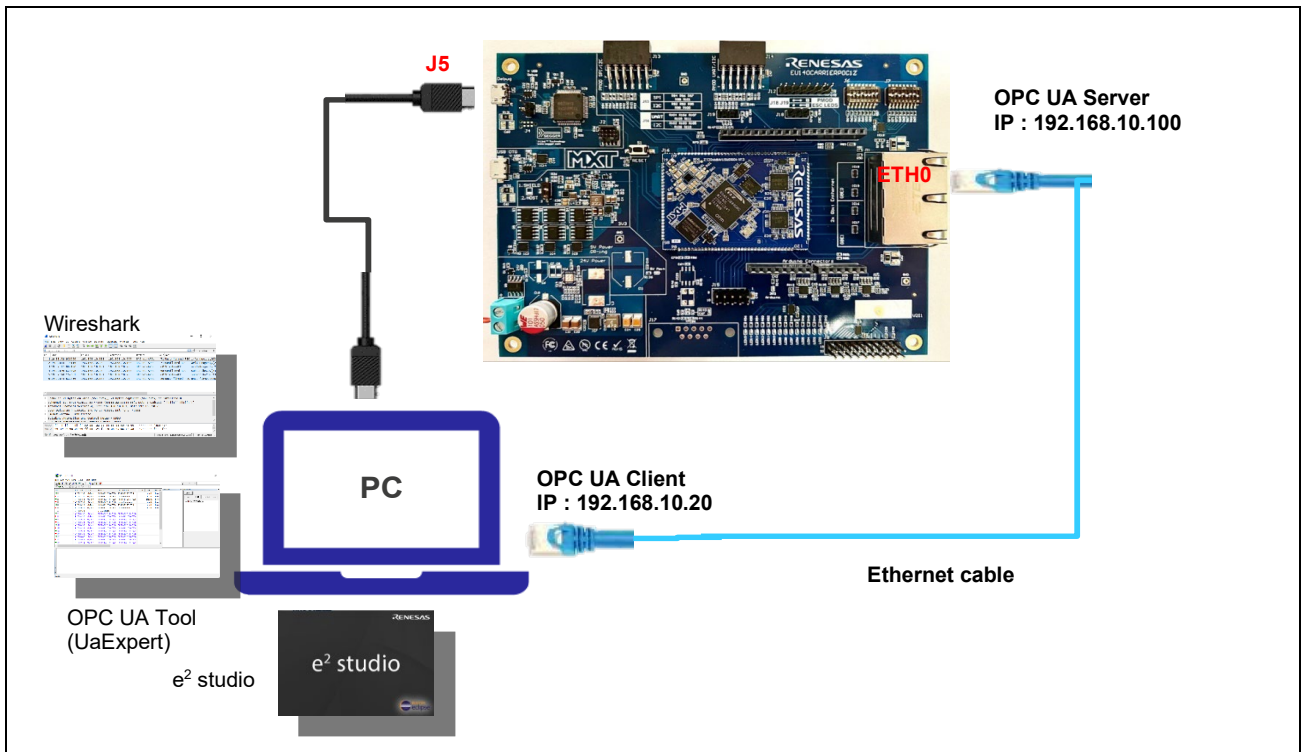


Fig 4-1 OPC UA Server Hardware Diagram

4.2 IP Address Settings

Set the address of the Ethernet on the PC that serves as the OPC UA Client.

Click on settings  in Windows Start .

Settings > Network and Internet > Change adapter options > Ethernet

> Properties > Internet Protocol Version 4 (TCP/IPv4) > Properties

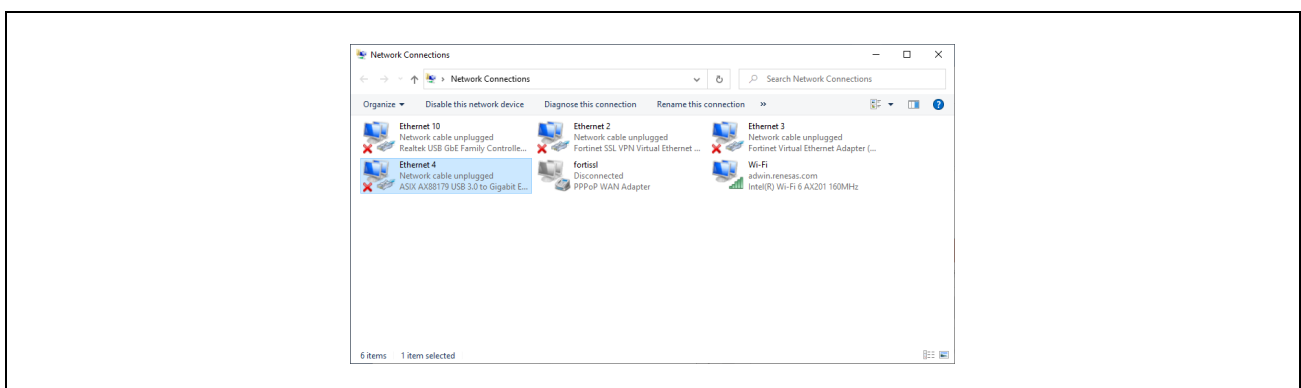


Fig 4-2 network connection

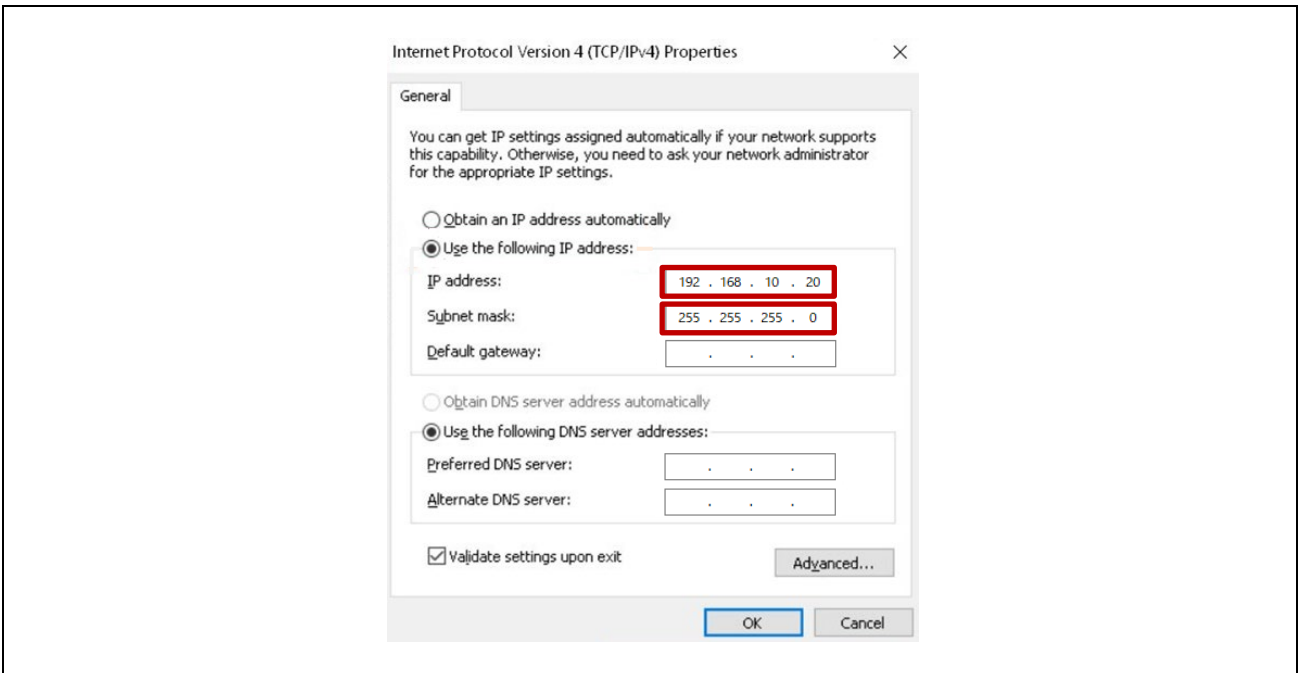


Fig 4-3 TCP/IPv4 properties

The IP address of the SOM Kit set in the OPC UA server sample software is 192.168.10.100. The IP address of the PC needs to be set to 192.168.10.XXX. In this document, 192.168.10.20 is used.

4.3 Start Project

First, import the project as described in section 3.4.1.2.

4.3.1 Build

Select the project name in the Project Explorer window and click "Clean..." in the Project menu.

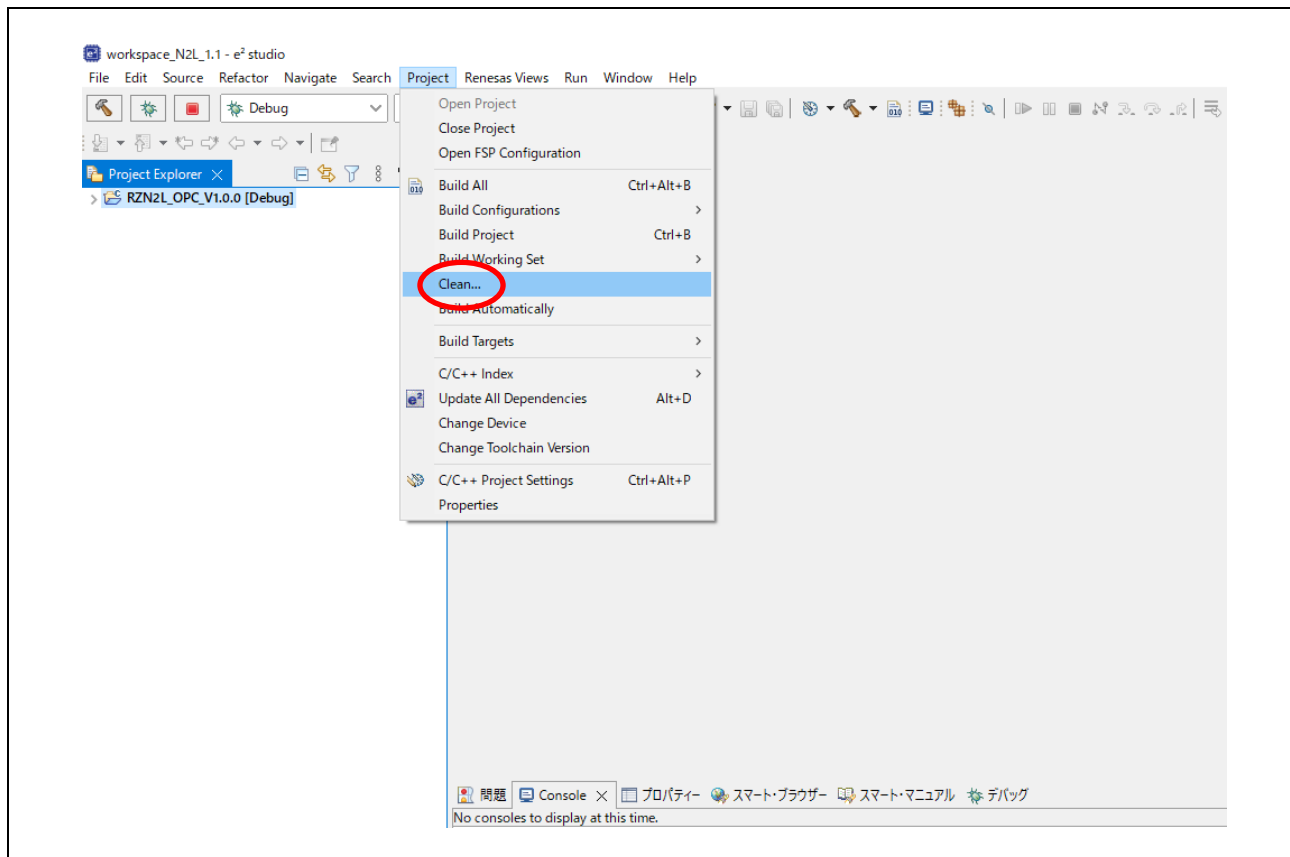


Fig 4-4 Open project Clean...

Enable the followings in the pop-up dialog and click "Clean" to start all builds.

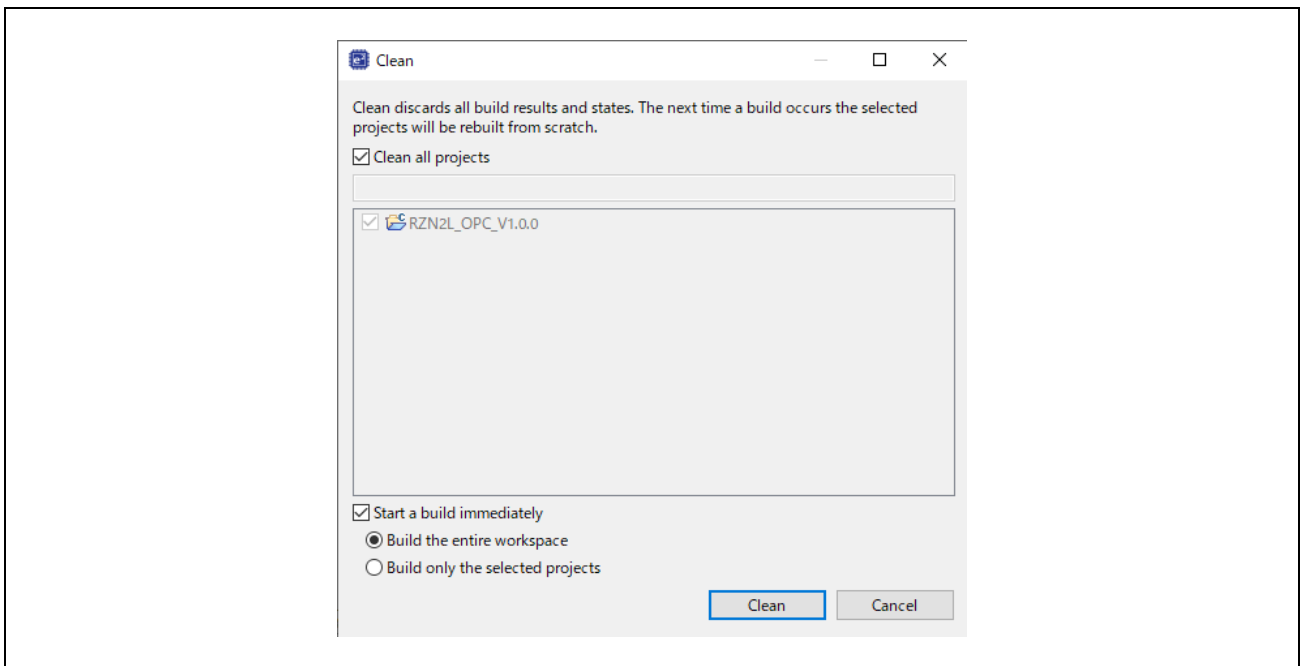


Fig 4-5 clean and rebuild

4.3.2 Debug Configurations

After confirming that the build result is 0 errors, select the project name in the Project Explorer window and click “Debug Configurations...” in the Run menu. Ignore the warning message that appears.

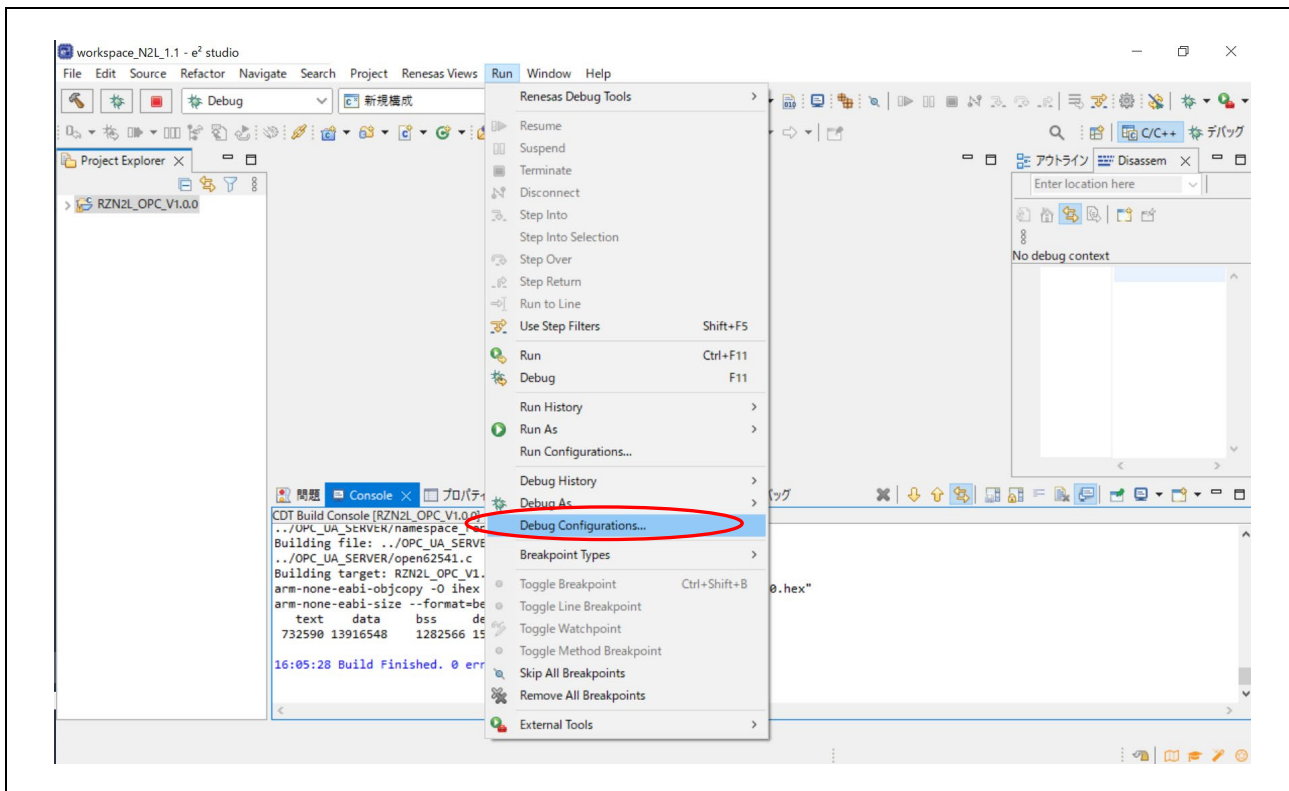


Fig 4-6 Open Debug Configurations...

Operations when starting the debugger for the first time after importing a project

Only when importing a project and launching the debugger for the first time, the following operations should be performed.

- Create RZ***_OPC_V*** Debug[local]
- Select Target Device
- Debut Tool Settings

See the following explanation for details.

a. Create RZ***_OPC_V*** Debug[local]

Double click on Renesas GDB Hardware Debugging to generate RZ***_OPC_V*** Debug[local]

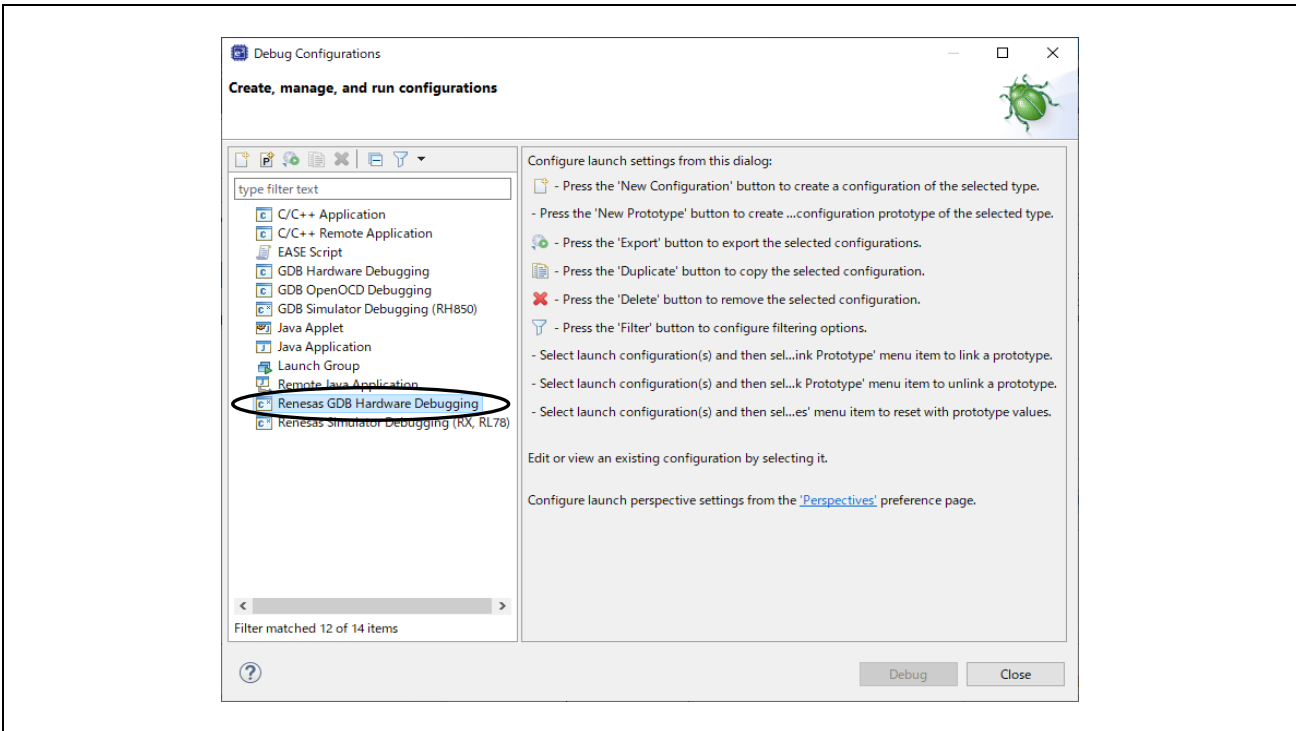


Fig 4-7 Debug Configurations(1)

b. Select Target Device

Click on the Debugger tag in the displayed dialog and select Target Device.

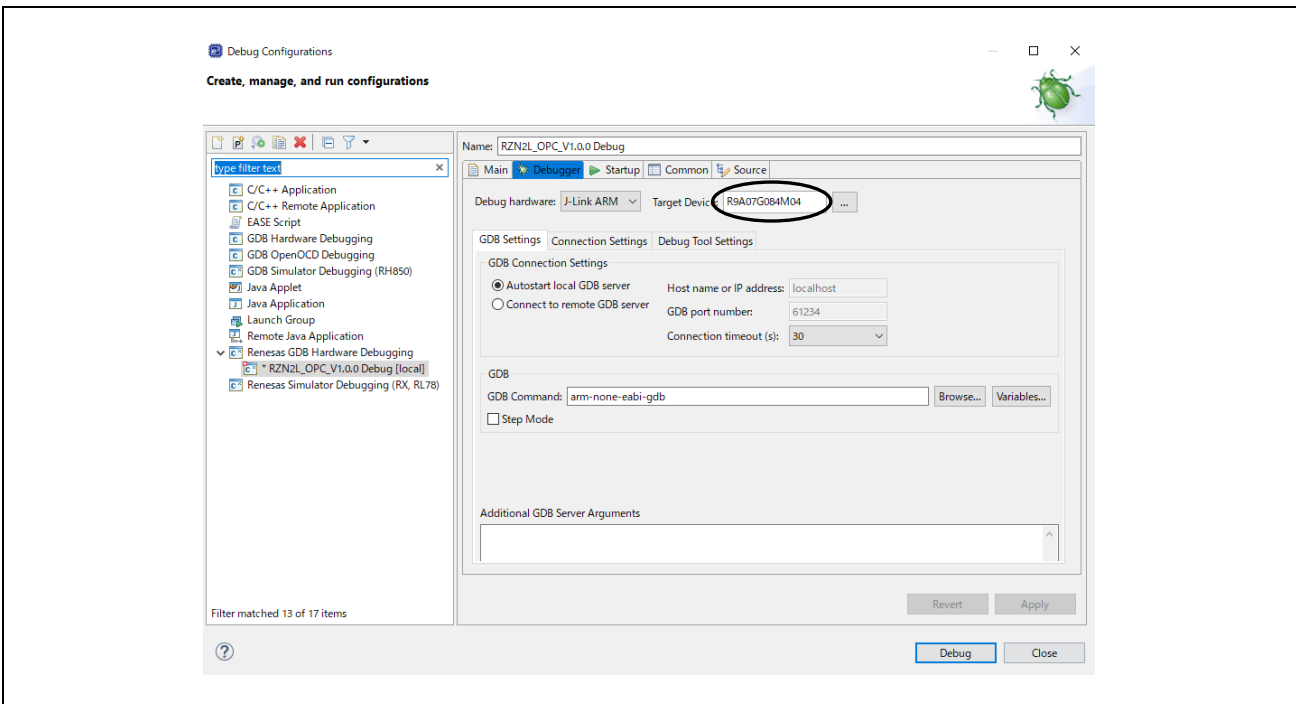


Fig 4-8 Debug Configurations(2)

RZ/N2L : Select R9A07G084M04 and click OK.

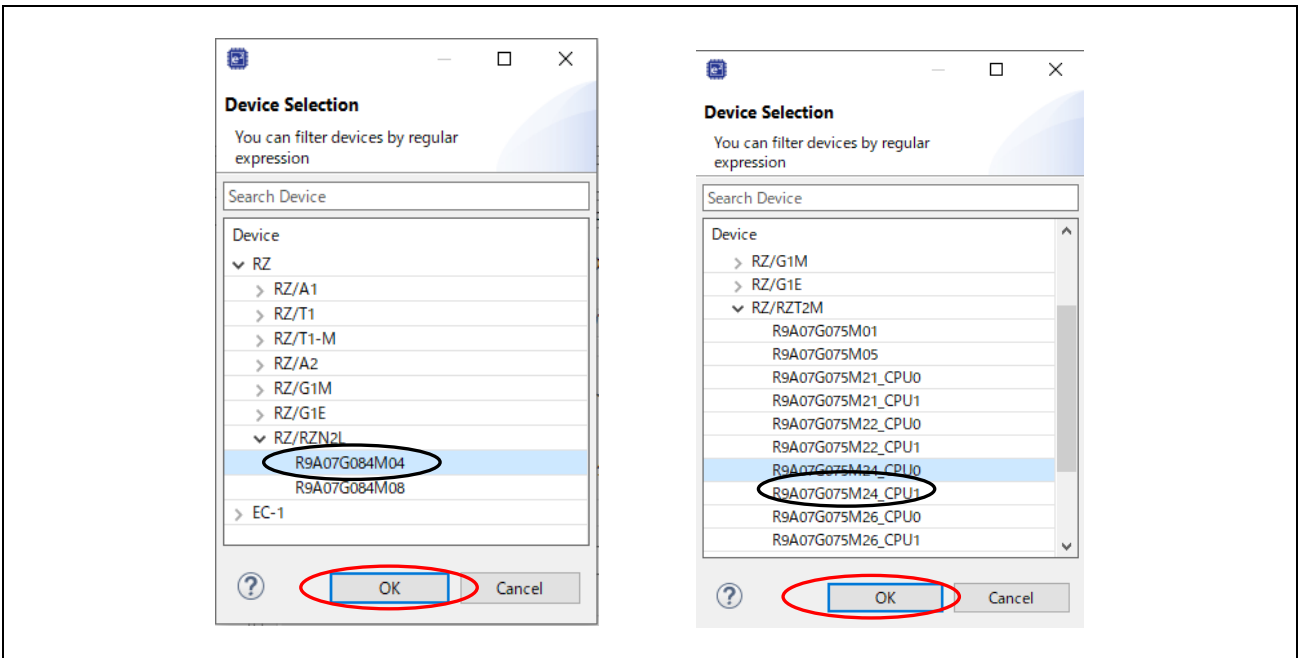


Fig 4-9 Debug Configurations(3)

c. Debug Tool Settings

Click the Debut Tool Settings tag and write 400 at Operating Frequency [MHz].

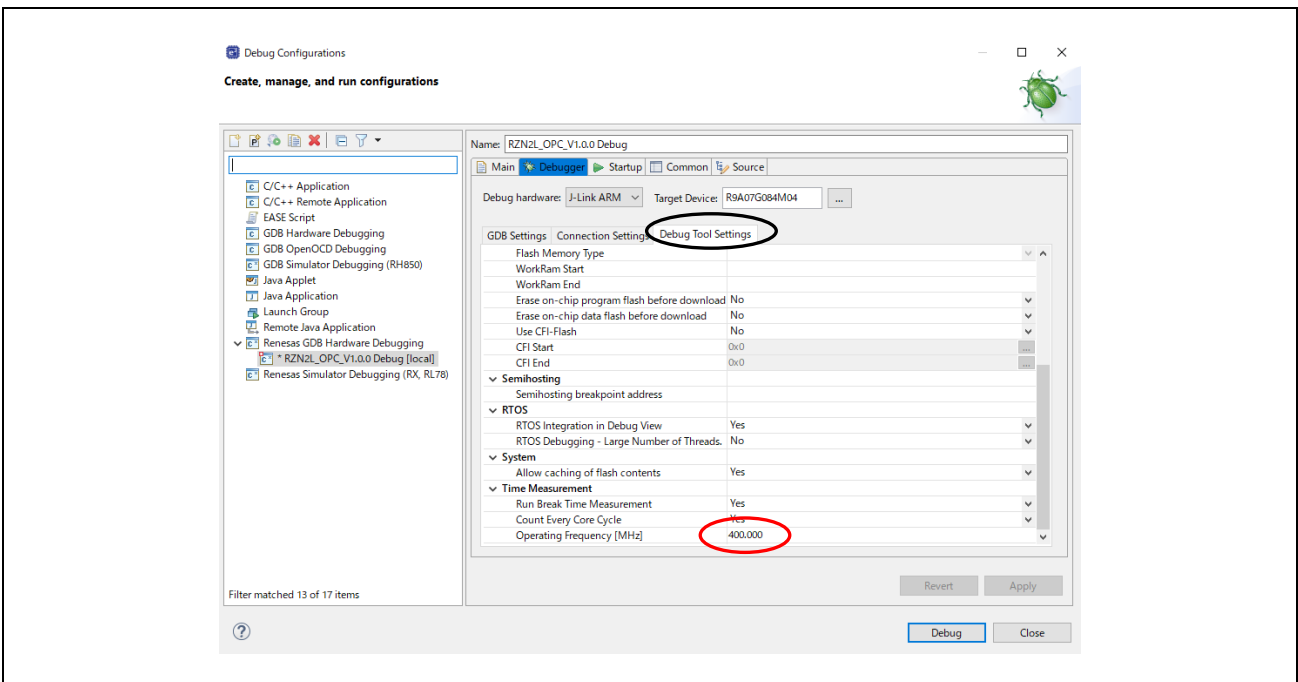


Fig 4-10 Debug Configurations(4)

d. Run Command Setting

Click the Startup and Add the Run Commands: "source rzn2l_xspi0_x1_boot.cfg".

Click on "Debug" to start the download. Continue to Fig 4-14 for instructions.

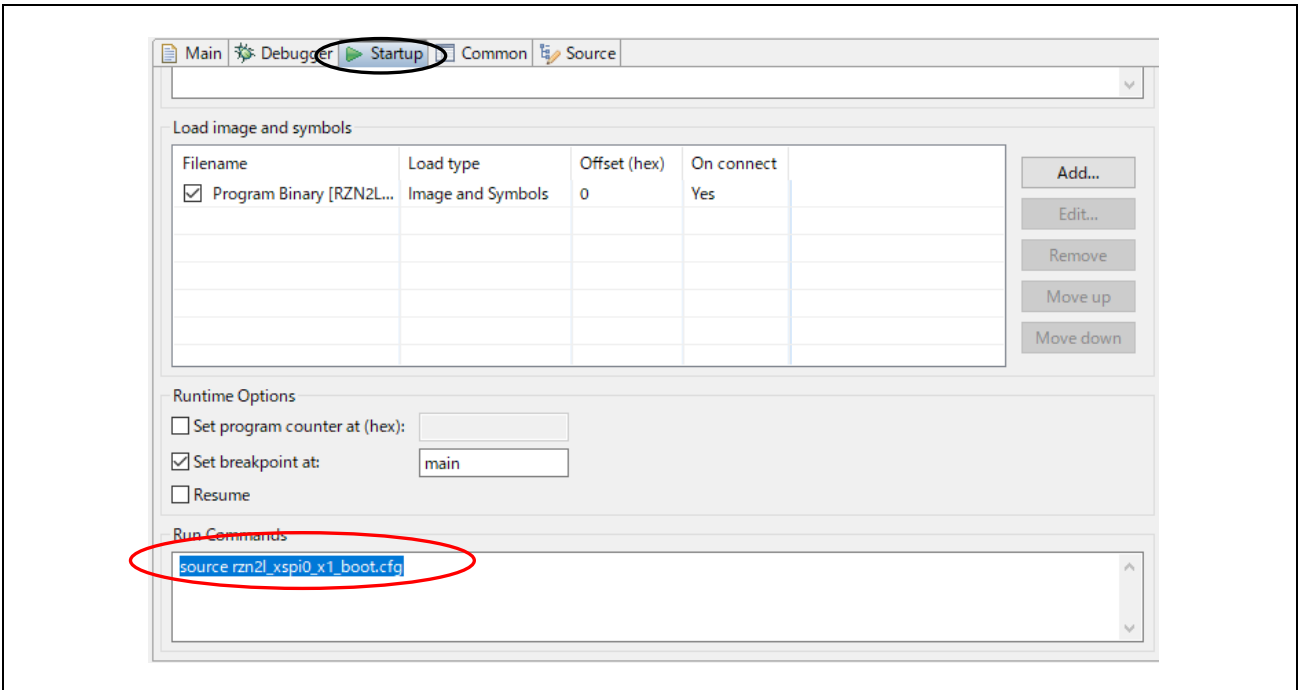


Fig 4-11 Debug Configurations(4)

4.3.3 Debug

The download procedure after completing the build is shown below.

At the second and subsequent debugger launches, click the Run menu with the project name selected in the C/C++ view. Place the cursor on "Debug As" and click on "Renesas GDB Hardware Debugging".

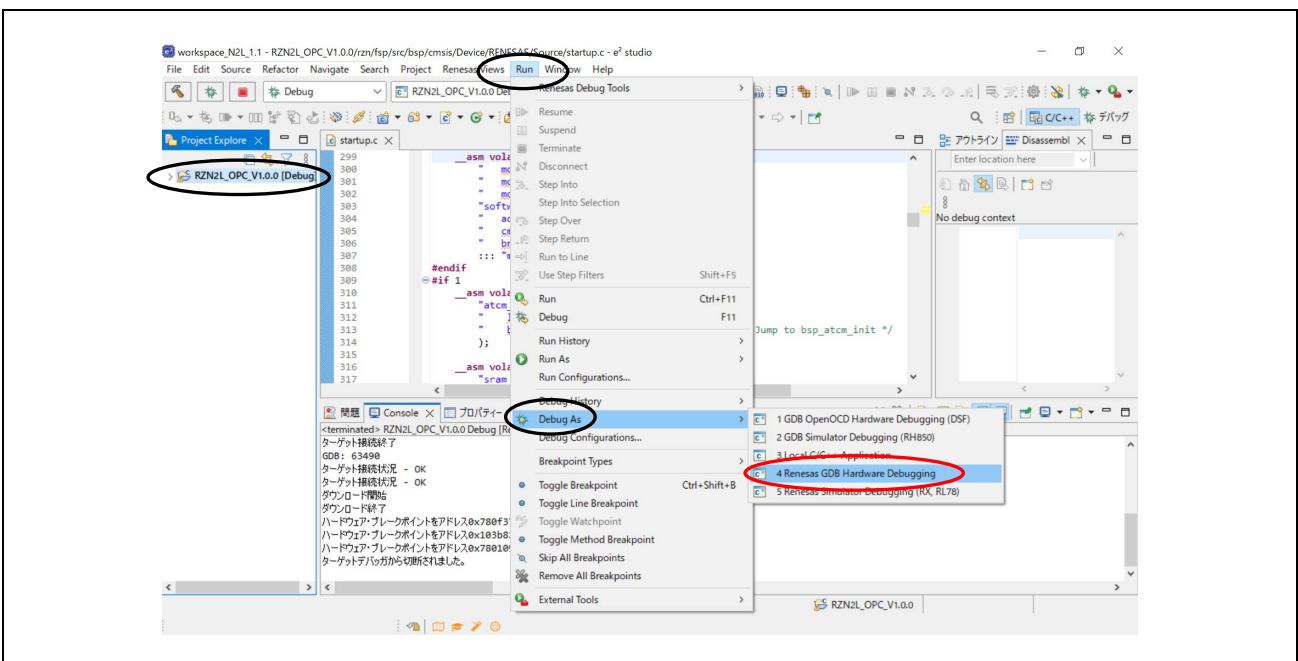


Fig 4-12 Run menu Debug As

Download the program to the flash memory. (It will take a few minutes.)

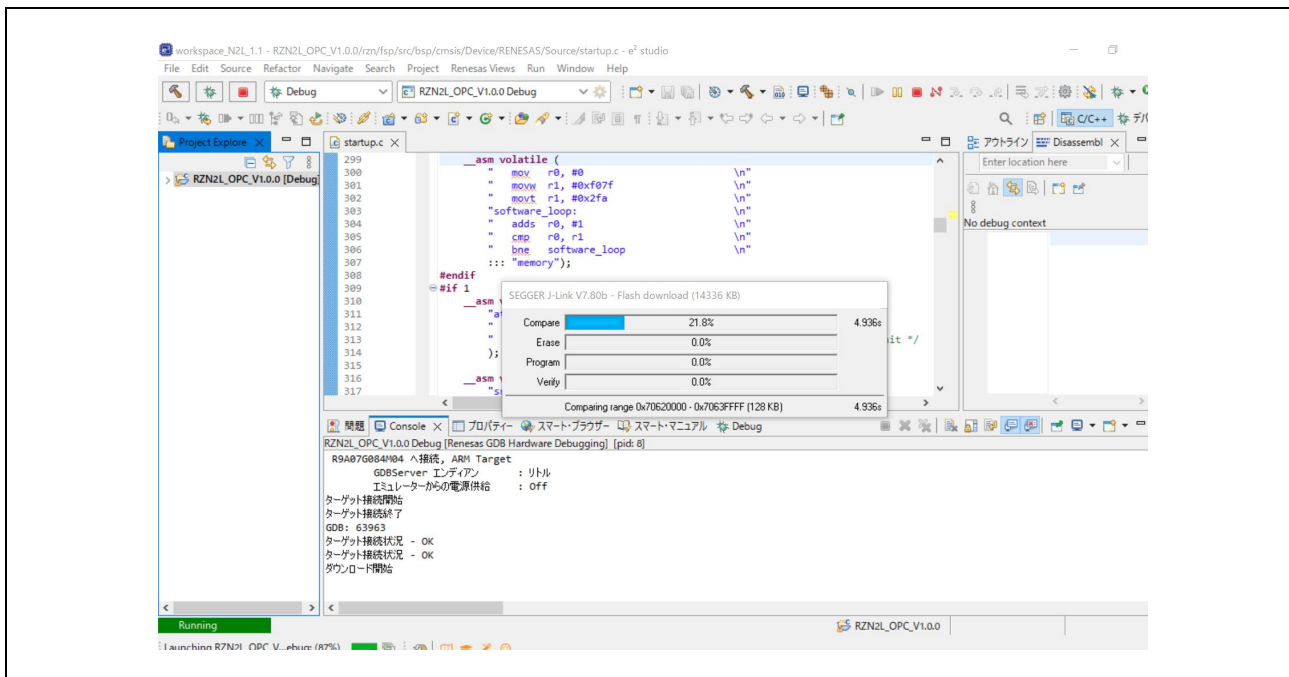


Fig 4-13 Download

Click Switch to change to debug view.

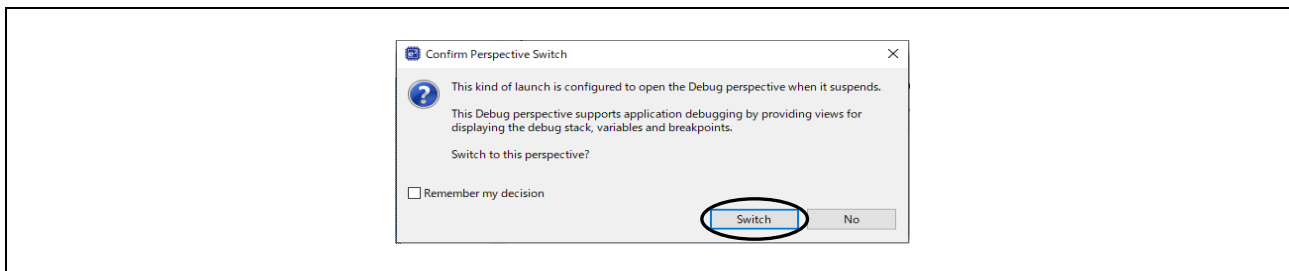


Fig 4-14 Perspective Switch

The CPU automatically extracts the loader program included in the download data to the BTCM. After extraction, it breaks in system_init() at the beginning of the initialization on the loader program.

- In case of operating the SOM Kit alone without using the debugger, turn off the board power supply, disconnect the debugger cable, and then turn on the board power supply again.

When using the debugger, **click the "reset" icon and then "resume"** after switching to the Debug screen.

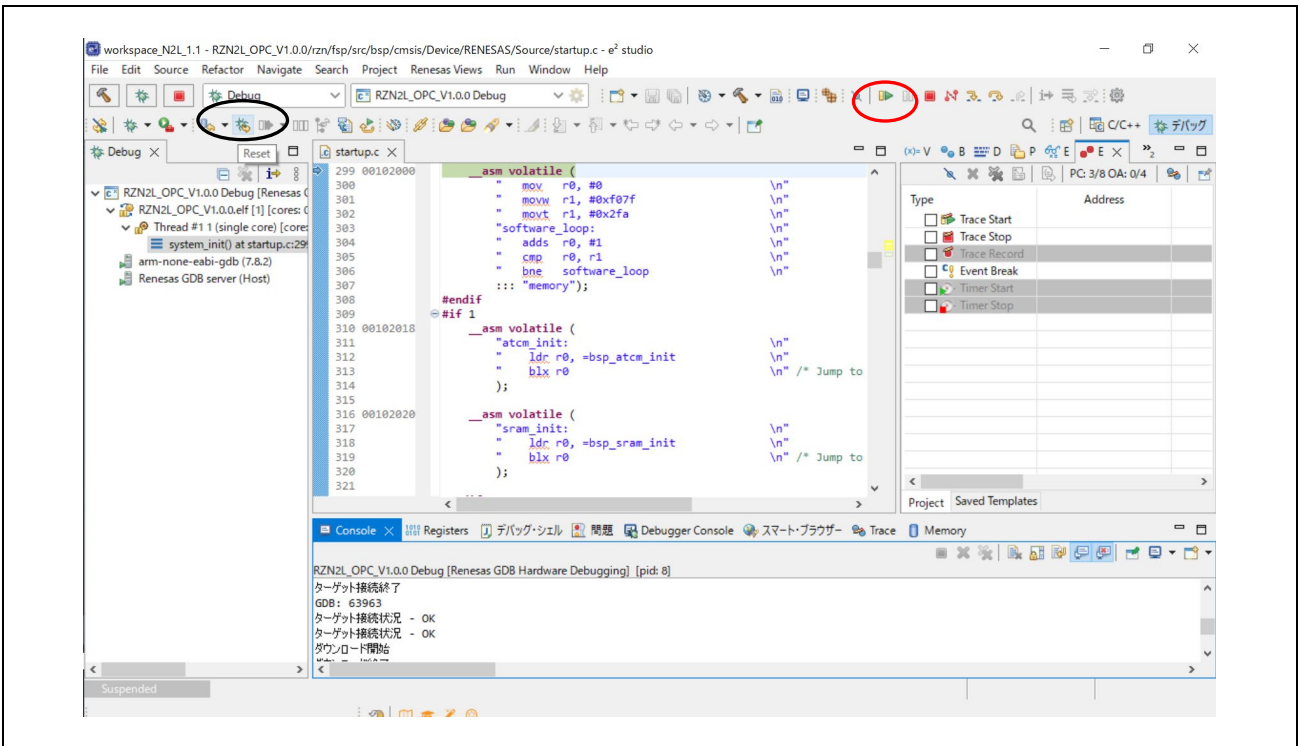


Fig 4-15 Break at system_init()

After completing initialization, the loader program stops at the beginning of main(). Then, click "resume" to return to the running state.

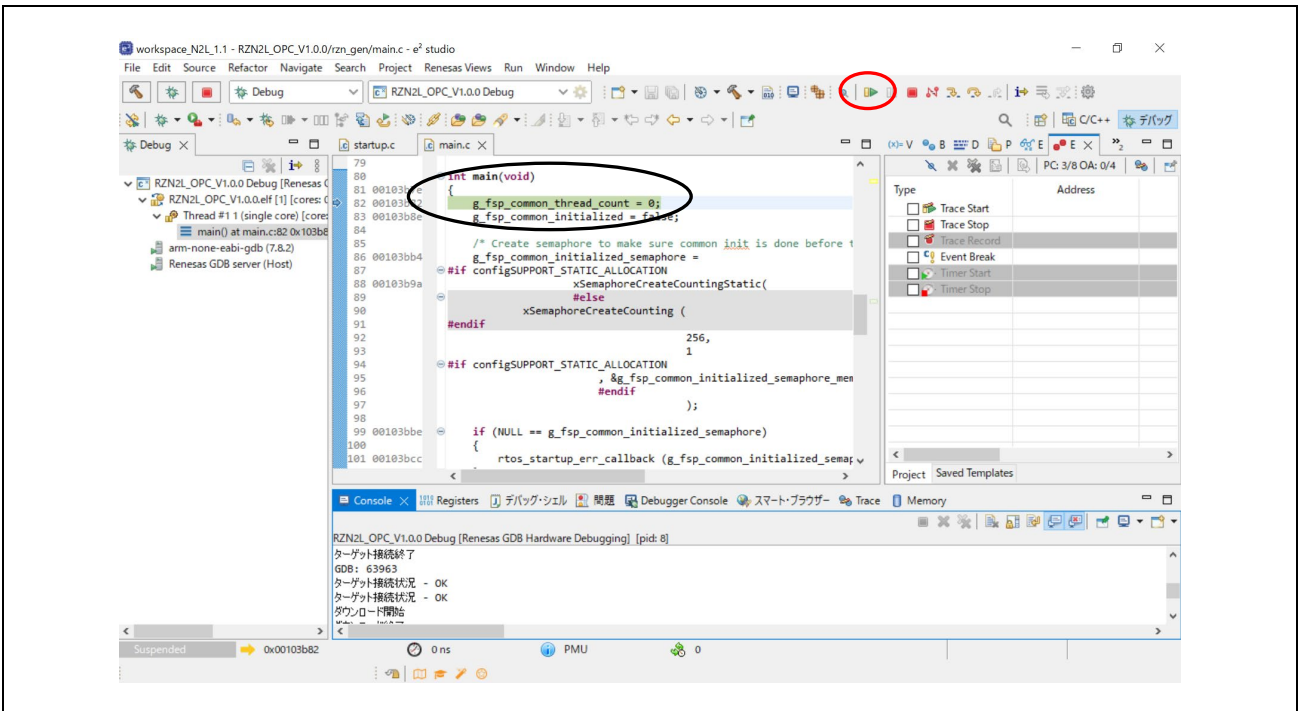



Fig 4-16 Break at main()

4.4 OPC UA Communication Check

- Launch UaExpert

Open Windows Start menu and  click UaExpert

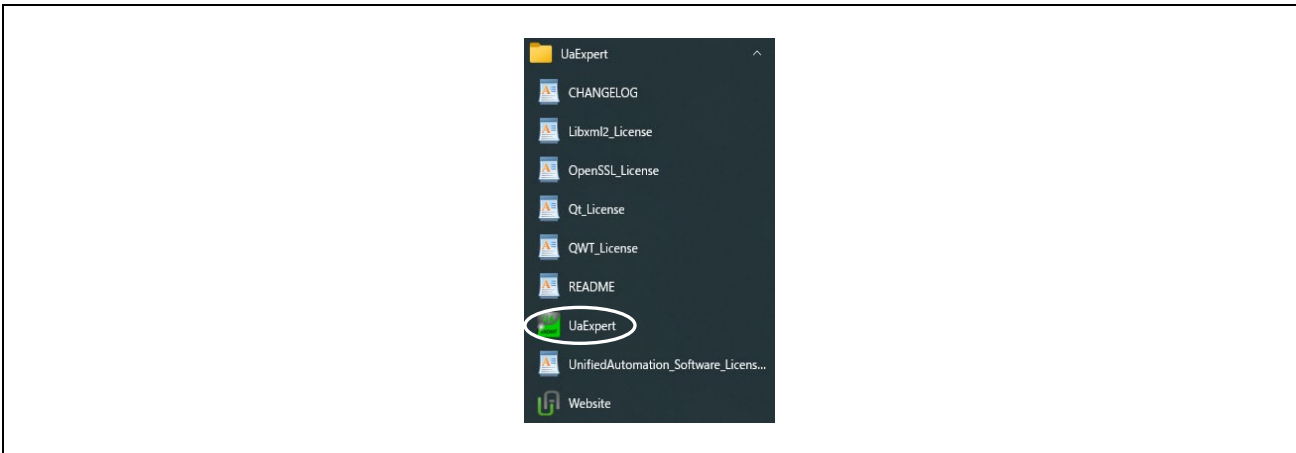


Fig 4-17 Launch UaExpert

- Add OPC UA server

Click  on the tool bar in UaExpert.

Open the Advanced tab, set the "Endpoint Url" to "opc.tcp://192.168.10.100:4840", select "Anonymous". Check "Connect Automatically" and then click OK at the end.

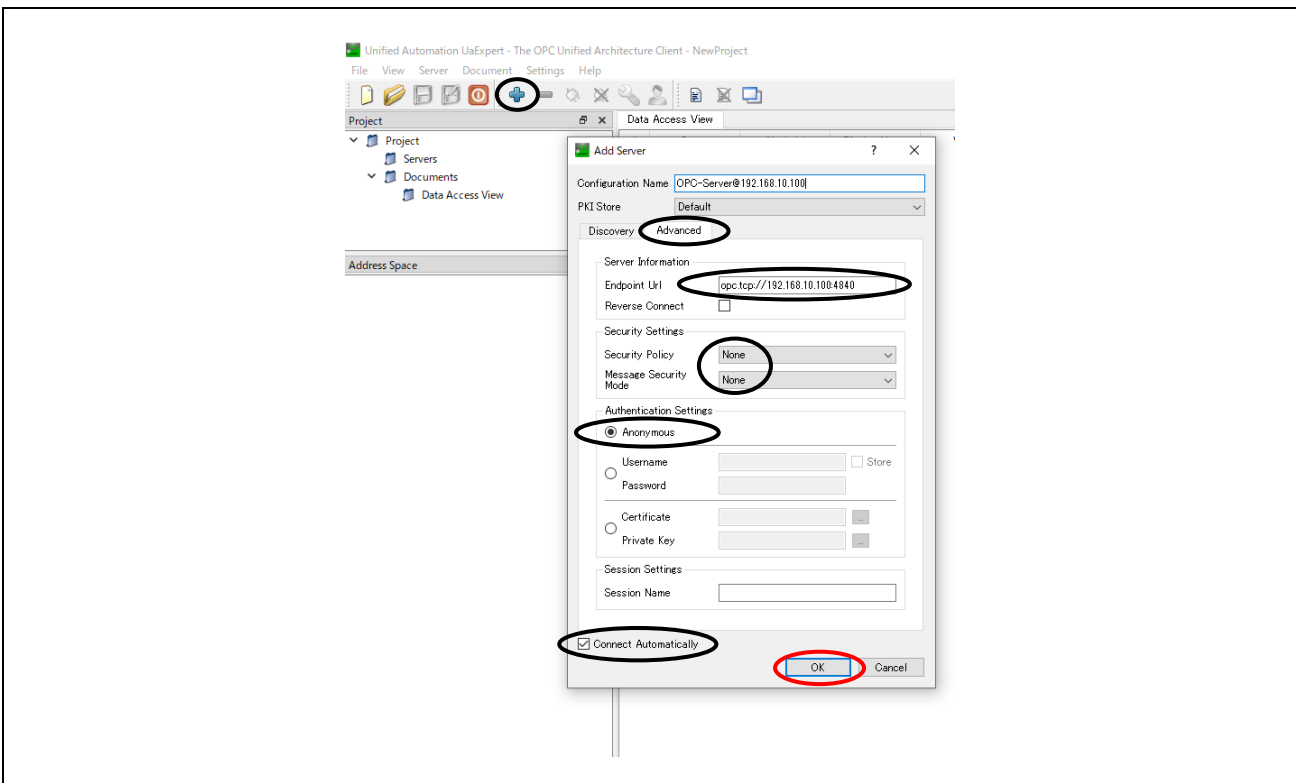


Fig 4-18 UaExpert Add server

When the OPC UA server is connected, an indicator icon is displayed in the “Project” window to show that the server is connected. “Renasas” displayed under the Object tree in the “Address Space” window is an object of OPC UA server.

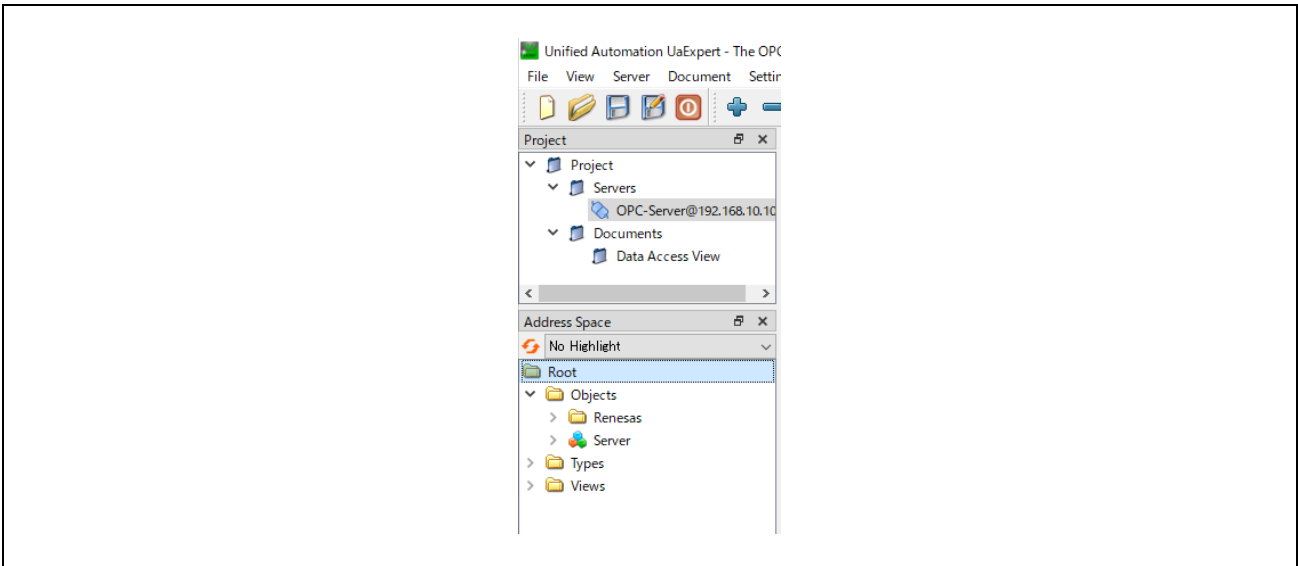


Fig 4-19 UaExpert OPC UA server connection

As shown in the following figure, drag and drop the *Root>Objects>Renasas>AnalogData* node in the “Address Space” window to the “Data Access View” window to change the value in the Value column.

The value repeatedly changes in the range of -5.0 ~ 5.0.

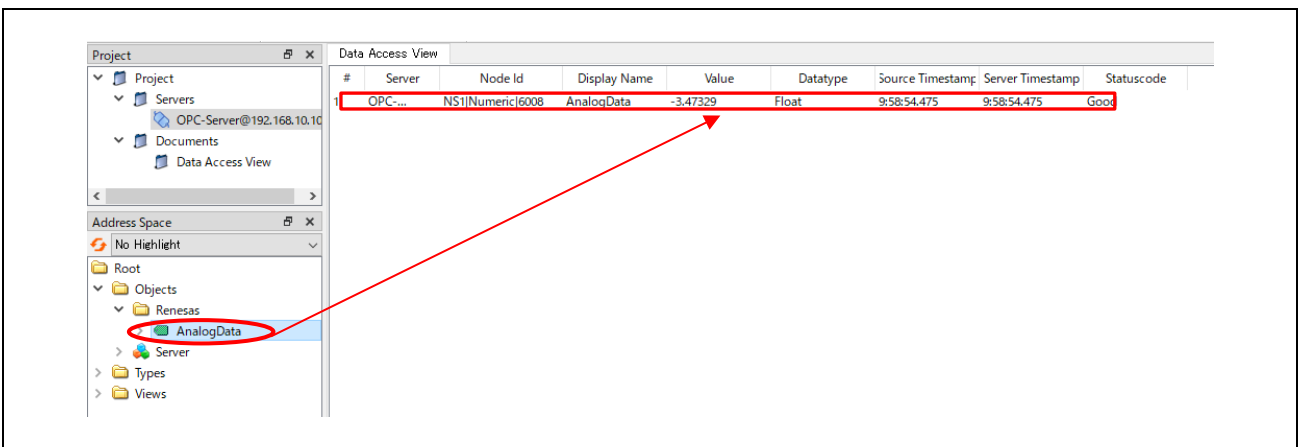


Fig 4-20 AnalogData value reading

5. Appendix

5.1 File Generation of open62541

The open source open62541 is used for the OPC UA stack of this sample software. To run open62541 in a freeRTOS + LWIP environment, the following link recommends an approach to generate open62541.c and open62541.h using CMake, which is also used in this sample software.

[Building open62541 — open62541 1.3.0-dirty documentation](#)

This chapter describes the procedure for generating open62541 and Renesas sample information models as files for e² studio execution in a Windows 10 environment. Here Window 10 version 1903 or later (OS Build 19044.2965) is used, in which WSL2 is executable.

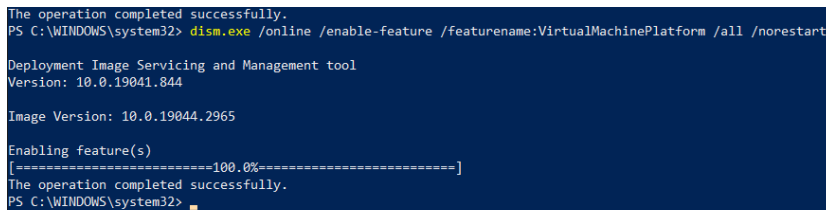
5.1.1 Linux environment Setup

Set up a Linux environment to run CMake. In this document, we will run CMake on a Linux (Ubuntu 18.04) environment installed using WSL2 with reference to the following linked pages.

(Reference) [Manual installation steps for older versions of WSL | Microsoft Learn](#)

- 1) Launch PowerShell as Administrator. Search PowerShell > right-click > Run as Administrator
- 2) Enter the following command to enable the Windows Subsystem for Linux.

```
dism.exe /online /enable-feature /featurename:Microsoft-Windows-Subsystem-Linux /all /norestart
```



```
The operation completed successfully.
PS C:\WINDOWS\system32> dism.exe /online /enable-feature /featurename:VirtualMachinePlatform /all /norestart
Deployment Image Servicing and Management tool
Version: 10.0.19041.844

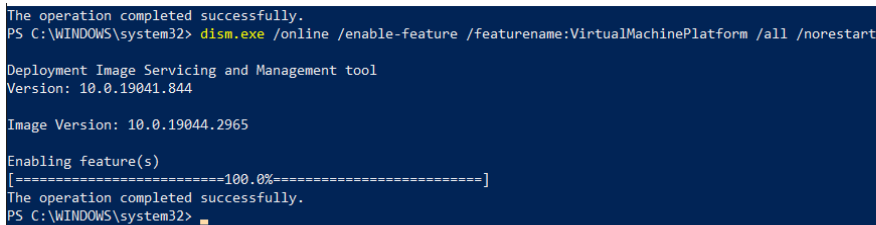
Image Version: 10.0.19044.2965

Enabling feature(s)
[=====100.0%=====]
The operation completed successfully.
PS C:\WINDOWS\system32> █
```

Fig 5-1 Microsoft-Windows-Subsystem-Linux

- 3) Enter the following command to enable the virtual machine platform feature:

```
dism.exe /online /enable-feature /featurename:VirtualMachinePlatform /all /norestart
```



```
The operation completed successfully.
PS C:\WINDOWS\system32> dism.exe /online /enable-feature /featurename:VirtualMachinePlatform /all /norestart
Deployment Image Servicing and Management tool
Version: 10.0.19041.844

Image Version: 10.0.19044.2965

Enabling feature(s)
[=====100.0%=====]
The operation completed successfully.
PS C:\WINDOWS\system32> █
```

Fig 5-2 VirtualMachinePlatform

- 4) Restart your PC and complete the WSL installation.
- 5) Download and run the WSL2 Linux kernel update package for x64 machines below.

[WSL2 Linux kernel update package for x64 machines](#)

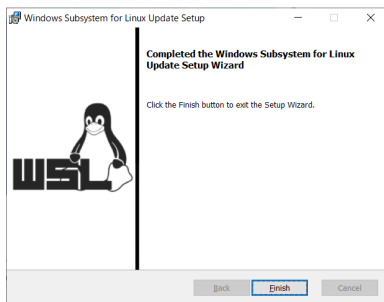


Fig 5-3 wsl_update_x64.msi

- 6) Run the following command to set WSL 2 as the default version.

```
wsl --set-default-version 2
```

- 7) Download Linux distribution. Here download Ubuntu 18.04 below.

[Ubuntu 18.04](#)

- 8) Go to the folder containing the downloaded file and execute the following command.

```
Add-AppxPackage . \Ubuntu_1804.2019.522.0_x64.appx
```

- 9) Double-click Ubuntu_1804.2019.522.0_x64.appx to install.



Fig 5-4 Ubuntu Install

- 10) Set the Linux username and password.

(Reference) [Set up a WSL development environment | Microsoft Learn](#)

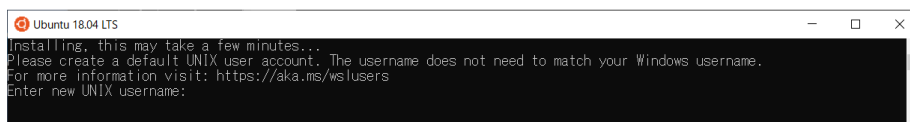


Fig 5-5 UNIX username

5.1.2 Install CMake

11) Execute the following Linux command to update apt-get

```
sudo apt-get update
```

```

v@v@IPN-9CG3013V10:~$ sudo apt-get update
Hit:1 http://archive.ubuntu.com/ubuntu bionic InRelease
Get:2 http://archive.ubuntu.com/ubuntu bionic-updates InRelease [88.7 kB]
Get:3 http://security.ubuntu.com/ubuntu bionic-security InRelease [88.7 kB]
Get:4 http://archive.ubuntu.com/ubuntu bionic-backports InRelease [83.3 kB]
Get:5 http://archive.ubuntu.com/ubuntu bionic/universe amd64 Packages [8570 kB]
Get:6 http://security.ubuntu.com/ubuntu bionic-security/main amd64 Packages [2717 kB]
Get:7 http://archive.ubuntu.com/ubuntu bionic/universe Translation-en [4941 kB]
Get:8 http://security.ubuntu.com/ubuntu bionic-security/main Translation-en [467 kB]
Get:9 http://security.ubuntu.com/ubuntu bionic-security/restricted amd64 Packages [1317 kB]
Get:10 http://security.ubuntu.com/ubuntu bionic-security/restricted Translation-en [182 kB]
Get:11 http://archive.ubuntu.com/ubuntu bionic/multiverse amd64 Packages [151 kB]
Get:12 http://security.ubuntu.com/ubuntu bionic-security/universe amd64 Packages [1303 kB]
Get:13 http://archive.ubuntu.com/ubuntu bionic/multiverse Translation-en [108 kB]
Get:14 http://archive.ubuntu.com/ubuntu bionic-updates/main amd64 Packages [3045 kB]
Get:15 http://security.ubuntu.com/ubuntu bionic-security/universe Translation-en [308 kB]
Get:16 http://security.ubuntu.com/ubuntu bionic-security/multiverse amd64 Packages [19.8 kB]
Get:17 http://archive.ubuntu.com/ubuntu bionic-updates/main Translation-en [553 kB]
Get:18 http://security.ubuntu.com/ubuntu bionic-security/multiverse Translation-en [3928 B]
Get:19 http://archive.ubuntu.com/ubuntu bionic-updates/restricted amd64 Packages [1347 kB]
Get:20 http://archive.ubuntu.com/ubuntu bionic-updates/restricted Translation-en [187 kB]
Get:21 http://archive.ubuntu.com/ubuntu bionic-updates/universe amd64 Packages [1914 kB]
Get:22 http://archive.ubuntu.com/ubuntu bionic-updates/universe Translation-en [420 kB]
Get:23 http://archive.ubuntu.com/ubuntu bionic-updates/multiverse amd64 Packages [25.6 kB]
Get:24 http://archive.ubuntu.com/ubuntu bionic-updates/multiverse Translation-en [6088 B]
Get:25 http://archive.ubuntu.com/ubuntu bionic-backports/main amd64 Packages [53.3 kB]
Get:26 http://archive.ubuntu.com/ubuntu bionic-backports/main Translation-en [14.6 kB]
Get:27 http://archive.ubuntu.com/ubuntu bionic-backports/universe amd64 Packages [18.2 kB]
Get:28 http://archive.ubuntu.com/ubuntu bionic-backports/universe Translation-en [8668 B]
Fetched 27.9 MB in 21s (1338 kB/s)
Reading package lists... Done

```

Fig 5-6 apt-get update

12) Execute the following Linux command

```
sudo apt-get install git build-essential gcc pkg-config cmake python
```

```

v@v@IPN-9CG3013V10:~$ sudo apt-get install git build-essential gcc pkg-config cmake python
Reading package lists... Done
Building dependency tree
Reading state information... Done
The following package was automatically installed and is no longer required:
  libfreetype6
Use 'sudo apt autoremove' to remove it.
The following additional packages will be installed:
  binutils binutils-common binutils-x86-64-linux-gnu cmake-data cpp cpp-7 dpkg-dev fakeroot g++ g++-7 gcc-7 gcc-7-base
  gcc-8-base libalgorithm-diff-perl libalgorithm-diff-xs-perl libalgorithm-merge-perl libarchive13 libasan4 libatomic1
  libbinutils libc-dev-bin libc6 libc6-dev libc6-i386 libcilkrts5 libdpkg-perl libfakeroot libfile-fcntllock-perl
  libgcc-7-dev libgcc1 libgomp1 libisl19 libitm1 libjansson4 liblsan0 libmpx3 libmpx2 libpython-stdlib
  libpython2.7-minimal libpython2.7-stdlib libquadmath0 librtmp1 libssl1.1 libstdc++-7-dev libstdc++6 libsubunit0
  libsubunit1 libsubunit2 libsubunit3 libsubunit4 libsubunit5 libsubunit6 libsubunit7 libsubunit8 libsubunit9 libsubunit10
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  libsubunit997 libsubunit998 libsubunit999 libsubunit1000
Suggested packages:
  binutils-doc cmake-doc ninja-build cpp-doc gcc-7-locales debian-keyring g++-multilib g++-7-multilib gcc-7-doc
  libstdc++6-7-dbg gcc-multilib autoconf automake libtool flex bison gdb gcc-doc gcc-7-multilib libgcc1-dbg
  libgomp1-dbg libitm1-dbg libatomic1-dbg libasan4-dbg liblsan0-dbg libubsan0-dbg libsubunit5-dbg libmpx2-dbg
  libquadmath0-dbg git-daemon-run | git-daemon-sysvinit git-doc git-el git-email git-gui gitk gitweb
  git-cvs git-mediawiki git-svn lrzip glibc-doc bzip libstdc++-7-doc make-doc python-doc python-tk python2.7-doc
  binfmt-support
The following NEW packages will be installed:
  binutils binutils-common binutils-x86-64-linux-gnu build-essential cmake cmake-data cpp cpp-7 dpkg-dev fakeroot g++
  g++-7 gcc-7 gcc-7-base

```

Fig 5-7 install

When the following screen appears during the process, select OK.

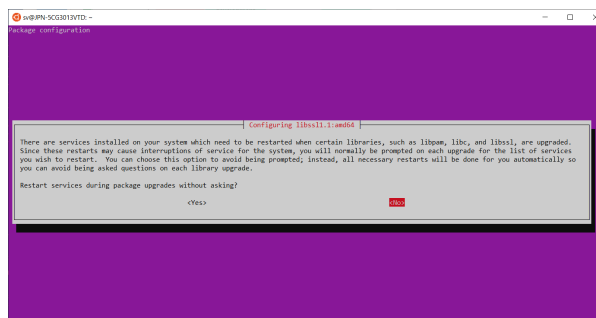


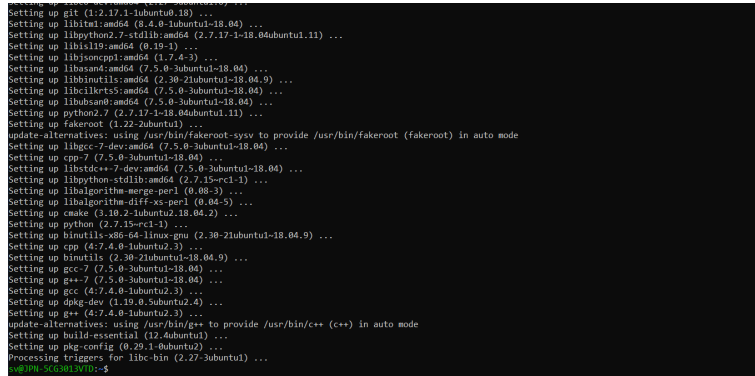
Fig 5-8 restart

13) Execute each of the following commands.

```

sudo apt-get install cmake-curses-gui           # Needed for CMAKE GUI
sudo apt-get install libmbedtls-dev            # For encryption
sudo apt-get install liburcu-dev              # For multithreading
sudo apt-get install check                    # For unit tests
sudo apt-get install python-sphinx graphviz   # For doc generation
sudo apt-get install python-sphinx-rtd-theme # For doc's style

```



```

Setting up git (1:2.17.1-1ubuntu0.18) ...
Setting up libitm1:amd64 (8.4.0-1ubuntu1-18.04) ...
Setting up libpython2.7-stdlib:amd64 (2.7.17-1-18.04ubuntu1.11) ...
Setting up libisl15:amd64 (0.19-3) ...
Setting up libjsoncpp1:amd64 (1.7.4-3) ...
Setting up libasan4:amd64 (7.5.0-3ubuntu1-18.04) ...
Setting up libbinutils:amd64 (2.30-21ubuntu1-18.04.9) ...
Setting up libcompiler-rt5:amd64 (7.5.0-3ubuntu1-18.04) ...
Setting up libubsan0:amd64 (7.5.0-3ubuntu1-18.04) ...
Setting up python2.7 (2.7.17-1-18.04ubuntu1.11) ...
Setting up fakeroot (1:2.20-2ubuntu1) ...
update-alternatives: using /usr/bin/fakeroot-sysv to provide /usr/bin/fakeroot (fakeroot) in auto mode
Setting up libgcc-7-dev:amd64 (7.5.0-3ubuntu1-18.04) ...
Setting up cpp-7 (7.5.0-3ubuntu1-18.04) ...
Setting up libstdc++7-dev:amd64 (7.5.0-3ubuntu1-18.04) ...
Setting up libpython-stlib:amd64 (2.7.15-rc1-1) ...
Setting up libalgorithm-merge-perl (0.08-3) ...
Setting up libalgorithm-diff-xs-perl (0.04-5) ...
Setting up cmake (3.10.2-1ubuntu2.18.04.2) ...
Setting up python (2.7.15-rc1-1) ...
Setting up binutils-x86_64-linux-gnu (2.30-21ubuntu1-18.04.9) ...
Setting up cpp (4:7.4.0-1ubuntu2.3) ...
Setting up binutils (2.30-21ubuntu1-18.04.9) ...
Setting up gcc-7 (7.5.0-3ubuntu1-18.04) ...
Setting up g++-7 (7.5.0-3ubuntu1-18.04) ...
Setting up gcc (4:7.4.0-1ubuntu2.3) ...
Setting up g++-dev (4:7.4.0-1ubuntu2.4) ...
Setting up g++ (4:7.4.0-1ubuntu2.3) ...
update-alternatives: using /usr/bin/g++ to provide /usr/bin/c++ (c++) in auto mode
Setting up build-essential (12-0ubuntu1) ...
Setting up pkg-config (0.29.1-0ubuntu2) ...
Processing triggers for libc-bin (2.27-3ubuntu1) ...

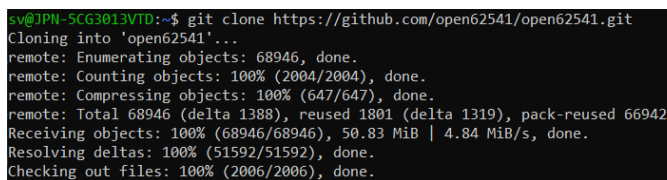
```

Fig 5-9 install

5.1.3 open62541 File Generation

14) Clone open62541 to any folder

```
git clone https://github.com/open62541/open62541.git
```



```

sv@JPN-5CG3013VTD:~$ git clone https://github.com/open62541/open62541.git
Cloning into 'open62541'...
remote: Enumerating objects: 68946, done.
remote: Counting objects: 100% (2004/2004), done.
remote: Compressing objects: 100% (647/647), done.
remote: Total 68946 (delta 1388), reused 1801 (delta 1319), pack-reused 66942
Receiving objects: 100% (68946/68946), 50.83 MiB | 4.84 MiB/s, done.
Resolving deltas: 100% (51592/51592), done.
Checking out files: 100% (2006/2006), done.

```

Fig 5-10 git clone

15) Go to /open62541 directory and check out the specific version (here, version v1.3.4-564-gb7e5e49f3).

```

cd open62541/
git log -1
git checkout b7e5e49f32d00490be74c2eacef892c7fbd0be60
git submodule init
git submodule update

```

```

sv@JPN-5CG3013VTD:~$ cd open62541
sv@JPN-5CG3013VTD:~/open62541$ git log -1
commit 6287f135945e397b1a738490689f5b504db6dc25 (HEAD -> master, origin/master, origin/HEAD)
Merge: 258d6add84 aa8d96ee45
Author: Julius Pfroemer <jpfr@users.noreply.github.com>
Date: Fri Jul 14 12:13:36 2023 +0200

    Merge pull request #5877 from open62541/1.4

    Merge 1.4 to master
sv@JPN-5CG3013VTD:~/open62541$ git checkout b7e5e49f32d00490be74c2eacef892c7fbd0be60
Checking out files: 100% (3359/3358), done.
Note: checking out 'b7e5e49f32d00490be74c2eacef892c7fbd0be60'.

You are in 'detached HEAD' state. You can look around, make experimental
changes and commit them, and you can discard any commits you make in this
state without impacting any branches by performing another checkout.

If you want to create a new branch to retain commits you create, you may
do so (now or later) by using -b with the checkout command again. Example:

    git checkout -b <new-branch-name>

HEAD is now at b7e5e49f3 [ci skip] Pack with inline submodules
sv@JPN-5CG3013VTD:~/open62541$ git submodule init
Submodule 'deps/mqtt-c' (https://github.com/LiamBindle/MQTT-C.git) registered for path 'deps/mqtt-c'
sv@JPN-5CG3013VTD:~/open62541$ git submodule update
Cloning into '/home/sv/open62541/deps/mqtt-c'...
Submodule path 'deps/mqtt-c': checked out 'f69ce1e7fd54f3b1834c9c9137ce0ec5d703cb4d'
sv@JPN-5CG3013VTD:~/open62541$ git log -1
commit b7e5e49f32d00490be74c2eacef892c7fbd0be60 (HEAD, origin/pack/v1.3.4)
Author: github-actions[bot] <41898282+github-actions[bot]@users.noreply.github.com>
Date: Mon Nov 14 12:28:23 2022 +0000

    [ci skip] Pack with inline submodules
    
```

Fig 5-11 git submodule

16) Open the Linux folder from File Explorer. Confirm that CMakeLists.txt is present in /home/(username)/open62541 directory. Copy the following four patch files obtained by unzipping patch_open62541.zip attached to the sample software to this directory.

- CMakeLists.txt.patch*
- Opc.Ua.NodeSet2.Reduced.xml.patch*
- Opc.Ua.Renesas.NodeSet2.xml*
- patch.sh*

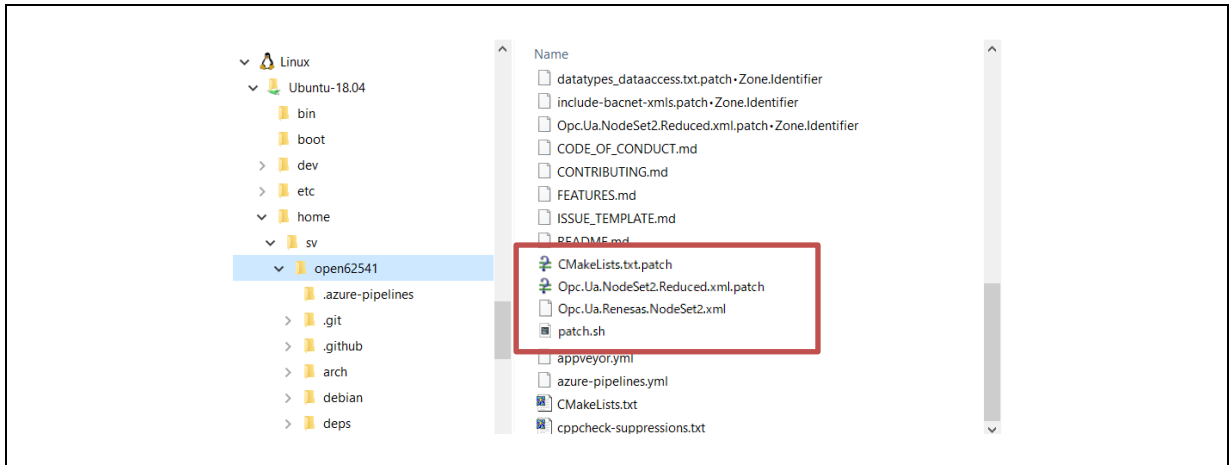


Fig 5-12 Copy patch files

17) Execute following command in /open62541 directory

```
bash patch.sh
```

```

xxxxx@JPN-5CG3013VTD:~/open62541$ bash patch.sh
patching file CMakeLists.txt
patching file tools/schema/Opc.Ua.NodeSet2.Reduced.xml
    
```

Fig 5-13 patch command

- 18) Compile the library according to the standard procedures of the cmake project. Create /open62541/build directory and run cmake . (Some items will be Failed, but there is no problem. (Some items will be Failed, but that is not a problem.)

```
mkdir build && cd build
```

```
cmake ..
```

```

saxxx @RZ/N2L/SOM/~/home/saxxx/tst/open62541/build$ cmake ..
-- The C compiler identification is GNU 9.4.0
-- Check for working C compiler: /usr/bin/cc
-- Check for working C compiler: /usr/bin/cc -- works
-- Detecting C compiler ABI info
-- Detecting C compiler ABI info - done
-- Detecting C compile features
-- Detecting C compile features - done
-- Found Python3: /usr/bin/python3.8 (found version "3.8.10") found components: Interpreter
-- Found Git: /usr/bin/git (found version "2.29.1")
-- open62541 Version: v1.8.4-1-ab7e49f3-dirty
-- CMAKE_BUILD_TYPE not given; setting to 'Debug'
-- The selected architecture is: posix
-- Test CC flag -std=c99
-- Performing Test flag_supported
-- Performing Test flag_supported - Success
-- Test CC flag -pipe
-- Performing Test flag_supported
-- Performing Test flag_supported - Success
-- Test CC flag -Wall
-- Performing Test flag_supported
-- Performing Test flag_supported - Success

```

Fig 5-14 cmake

- 19) Execute the following command to start the ccmake setting window.

```
ccmake ..
```

- 20) Change the settings as follows, and after executing [c] to configure, close it by [q] to quit without generating.

```

Page 1 of 1
BUILD_SHARED_LIBS OFF
CLANG_FORMAT_EXE CLANG_FORMAT_EXE-NOTFOUND
CMAKE_BUILD_TYPE Debug
CMAKE_INSTALL_PREFIX /usr/local
UA_ARCHITECTURE freertosLWIP
UA_ARCH_FREERTOS_USE_OWN_MEMOR OFF
UA_BUILD_EXAMPLES OFF
UA_BUILD_TOOLS OFF
UA_BUILD_UNIT_TESTS OFF
UA_ENABLE_AMALGAMATION ON
UA_ENABLE_DA ON
UA_ENABLE_DIAGNOSTICS OFF
UA_ENABLE_DISCOVERY OFF
UA_ENABLE_ENCRYPTION OFF
UA_ENABLE_ENCRYPTION_TPM2 OFF
UA_ENABLE_HISTORIZING OFF
UA_ENABLE_JSON_ENCODING ON
UA_ENABLE_METHODCALLS ON
UA_ENABLE_PUBSUB OFF
UA_ENABLE_PUBSUB_DeltaFrames OFF
UA_ENABLE_PUBSUB_ETH_UADP OFF
UA_ENABLE_PUBSUB_INFORMATIONNO OFF
UA_ENABLE_PUBSUB_INFORMATIONNO OFF
UA_ENABLE_SUBSCRIPTIONS ON
UA_ENABLE_SUBSCRIPTIONS_EVENTS ON
UA_FORCE_ERROR ON
UA_LOGLEVEL 500
UA_MULTITHREADING 0
UA_NAMESPACE_ZERO REDUCED

BUILD_SHARED_LIBS: Enable building of shared libraries (dll/so)
Press [enter] to edit option Press [d] to delete an entry
Press [c] to configure Press [g] to generate and exit
Press [h] for help Press [q] to quit without generating
Press [t] to toggle advanced mode (Currently Off)

```

Fig 5-15 ccmake

- 21) Execute the following command to make in the /open62541/build directory. The make process will finish with an error, but it does not matter.

```
make -j
```



```

Configuring done
Generating done
-- Build Files have been written to: //home/xxxxxx/tst/open62541/build
Scanning dependencies of target open62541-generator-types
Scanning dependencies of target open62541-generator-statuscode
Scanning dependencies of target open62541-generator-transport
[ 48%] Generating src_generated/open62541/types_generated.c, src_generated/open62541/types_generated.h, src_generated/open62541/types_generated_handling.h
[ 88%] Generating src_generated/open62541/nodeids.h
[100%] Generating src_generated/open62541/transport_generated.c, src_generated/open62541/transport_generated.h, src_generated/open62541/transport_generated_handling.h
[100%] Generating src_generated/open62541/statuscodes.h, src_generated/open62541/statuscodes.c
[100%] Built target open62541-generator-statuscode
[100%] Built target open62541-generator-transport
[100%] Built target open62541-generator-types
Scanning dependencies of target open62541-generator-namespace
[200%] Generating src_generated/open62541/namespace0_generated.c, src_generated/open62541/namespace0_generated.h
NFO: main: Preprocessing //home/xxxxxx/tst/open62541/tools/schema/OpC_Ua_NodeSet2_Reduced.xml
NFO: main: Preprocessing //home/xxxxxx/tst/open62541/tools/schema/OpC_Ua_NodeSet2_EventMinimal.xml
NFO: main: Preprocessing //home/xxxxxx/tst/open62541/tools/schema/OpC_Ua_NodeSet2_Part8_Subset.xml
NFO: main: Skipping Nodeset since it is already loaded: //home/mashiko/tst/open62541/tools/schema/OpC_Ua_NodeSet2_EventMinimal.xml
NFO: main: Skipping Nodeset since it is already loaded: //home/mashiko/tst/open62541/tools/schema/OpC_Ua_NodeSet2_Part8_Subset.xml
NFO: main: Generating Code for Backend: open62541
NFO: main: Namespace generation code successfully printed
[200%] Built target open62541-generator-namespace
Scanning dependencies of target open62541-namespace-source
Scanning dependencies of target open62541-namespace-header
[230%] Generating src_generated/open62541/namespace_renesas_generated.c, src_generated/open62541/namespace_renesas_generated.h
[230%] Generating open62541.h
Starting namespace file //home/xxxxxx/tst/open62541/build/open62541.h
    
```

Fig 5-16 make

22) Confirm that the following files are generated in /opn62541/build and /src_generated/open62541 directories.

- *open62541.c*
- *open62541.h*
- *namespace_renesas_generated.c*
- *namespace_renesas_generated.h*

```

xxxxxx@IPN-50G3013WM: /opc/open62541/build$ ls -l
total 6048
-rw-r--r-- 1 39687 Sep  4 16:21 CMakeCache.txt
drwxr-xr-x 1 4096 Sep  4 16:47 CMakeFiles
-rw-r--r-- 1 3948 Sep  4 16:19 CPackConfig.cmake
-rw-r--r-- 1 4412 Sep  4 16:19 CPackSourceConfig.cmake
-rw-r--r-- 1 15516 Sep  4 16:47 Makefile
drwxr-xr-x 1 4096 Sep  4 16:47 arch
drwxr-xr-x 1 4096 Sep  4 16:22 bin
-rw-r--r-- 1 5361 Sep  4 16:22 cmake_install.cmake
-rw-r--r-- 1 1008 Sep  4 16:47 compile_commands.json
drwxr-xr-x 1 4096 Sep  4 16:47 doc
drwxr-xr-x 1 4096 Sep  4 16:47 doc_src
-rw-r--r-- 1 4379734 Sep  4 16:22 open62541.c
-rw-r--r-- 1 1687445 Sep  4 16:4 open62541.h
-rw-r--r-- 1 2133 Sep  4 16:21 open62541Config.cmake
-rw-r--r-- 1 1382 Sep  4 16:02 open62541ConfigVersion.cmake
-rw-r--r-- 1 28898 Sep  4 16:02 open62541Macros.cmake
-rw-r--r-- 1 2303 Sep  4 16:22 open62541Targets.cmake
drwxr-xr-x 1 4096 Sep  4 16:47 src_generated
drwxr-xr-x 1 4096 Sep  4 16:02 tools
xxxxxx@IPN-50G3013WM: /opc/open62541/build$ ls -l src_generated/open62541
total 3036
-rw-r--r-- 1 4470 Sep  4 16:21 config.h
-rw-r--r-- 1 1531307 Sep  4 16:22 namespace0_generated.c
-rw-r--r-- 1 1423 Sep  4 16:22 namespace0_generated.h
-rw-r--r-- 1 15600 Sep  4 16:22 namespace_renesas_generated.c
-rw-r--r-- 1 412 Sep  4 16:22 namespace_renesas_generated.h
-rw-r--r-- 1 975379 Sep  4 16:22 nodeids.h
-rw-r--r-- 1 18357 Sep  4 16:22 statuscodes.c
-rw-r--r-- 1 32740 Sep  4 16:22 statuscodes.h
-rw-r--r-- 1 9621 Sep  4 16:22 transport_generated.c
-rw-r--r-- 1 3204 Sep  4 16:22 transport_generated.h
-rw-r--r-- 1 8308 Sep  4 16:22 transport_generated_handling.h
-rw-r--r-- 1 245684 Sep  4 16:22 types_generated.c
-rw-r--r-- 1 53299 Sep  4 16:22 types_generated.h
-rw-r--r-- 1 177739 Sep  4 16:22 types_generated_handling.h
xxxxxx@IPN-50G3013WM: /opc/open62541/build$
    
```

Fig 5-17 Generated Files

23) Create a folder in the IDE project and import the generated files into the project as shown in the figure. Where OPC_UA_SERVER is the file created under the e² studio project.

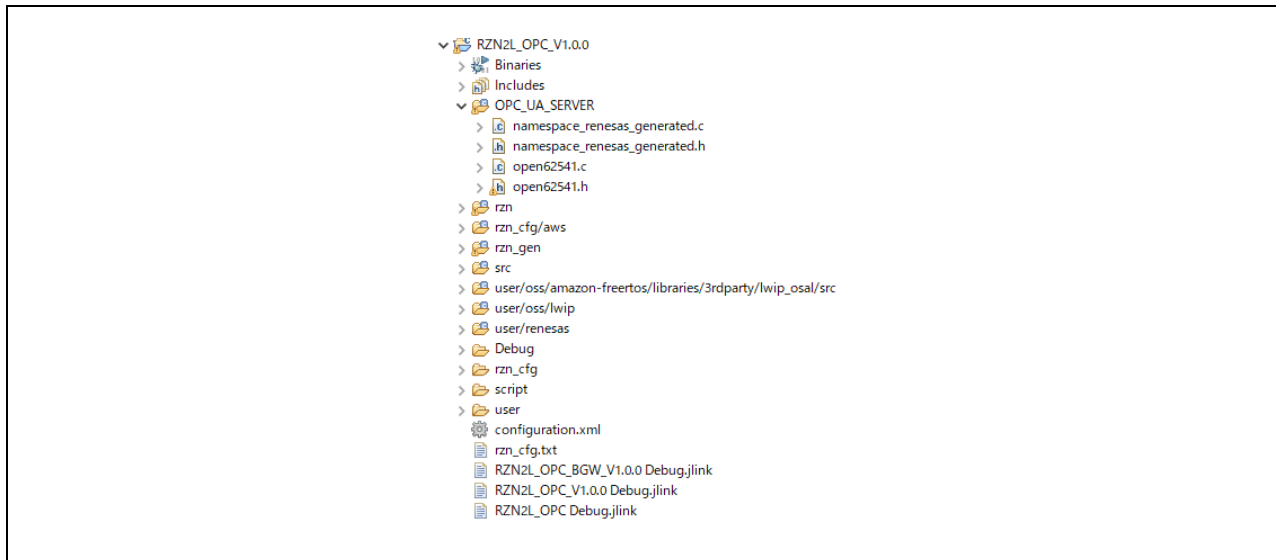


Fig 5-18 Import

5.1.4 Changes in Generated Files

Several changes have been made to the open62541.c, h file generated by this procedure. The changes are shown in Fig 5-19 and Fig 5-20.

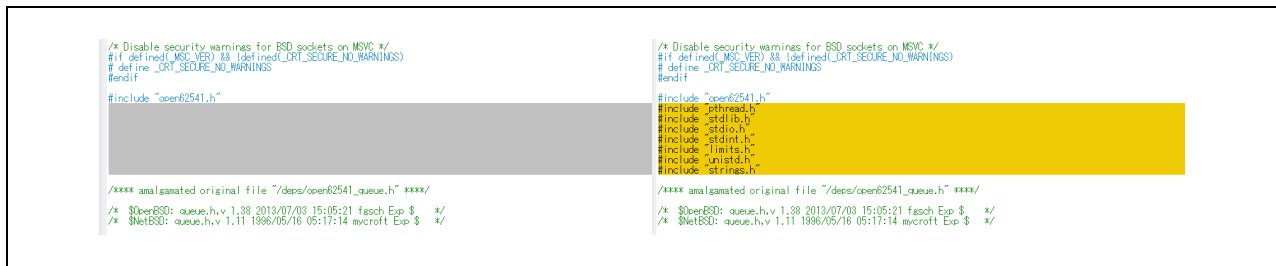


Fig 5-19 Difference in open62541.c

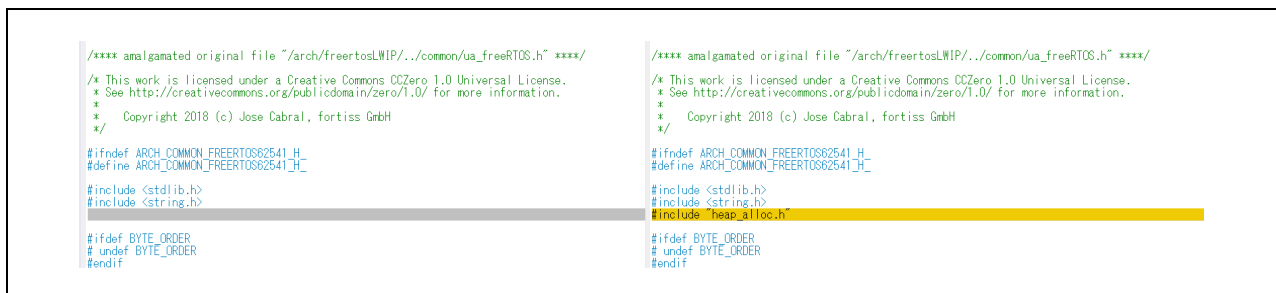


Fig 5-20 Difference in open62541.h

5.2 FSP Configuration for VSC8531 and SSC port

RZ/N2L Industrial Network SOM Kit has VSC8531 as PHY chip.

If reconfiguring by latest FSP, FSP configuration and source code needs to change from default.

In addition, since interrupts are used for IO control, SSC port driver also needs to change.

(1) Regenerate source files by latest FSP

Remove the following four folders. After that, open the project according to section 5.

- When using e2studio, \project\rzn2l_som\ecat_IO\e2studio
- When using EWARM, \project\rzn2l_som\ecat_IO\ewarm

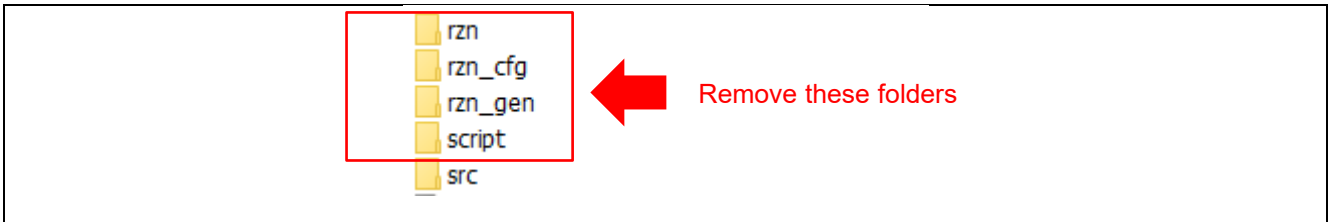


Figure 5-1 Remove folder generated by FSP

(2) Change ethernet driver configuration for VSC8531

Configure g_ether_phy0 Ethernet Driver on r_ether_phy for VSC8531 as shown in Figure 5-2. Configuration value for VSC8531 shows in Table 5-1.

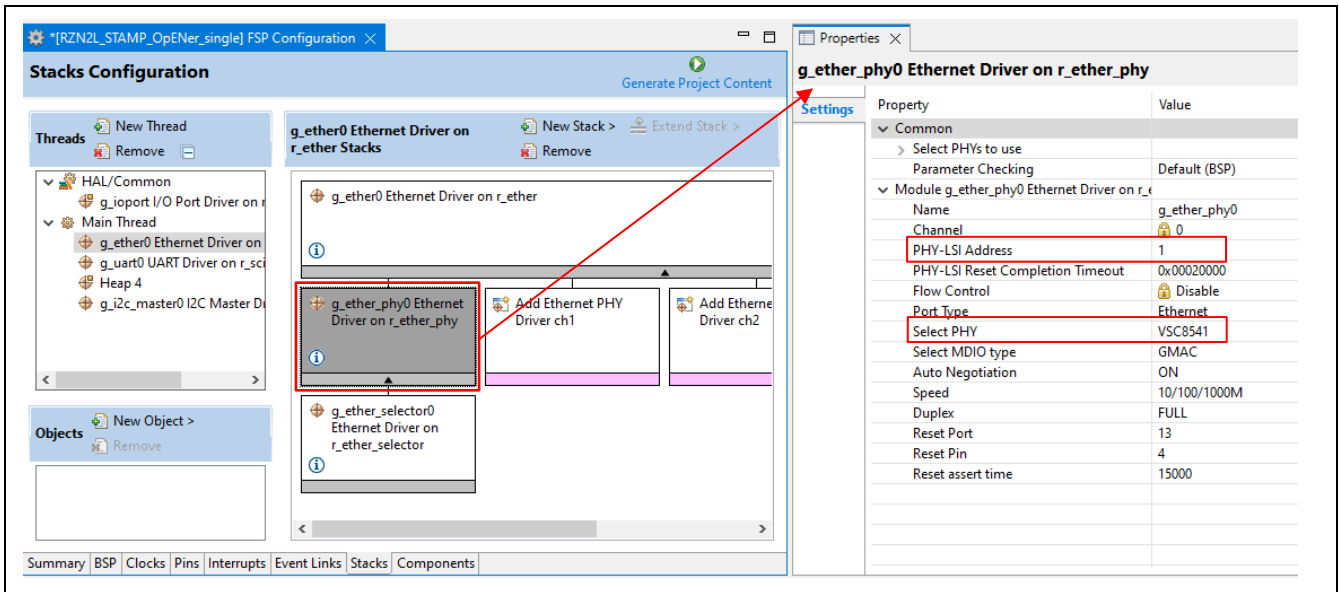


Figure 5-2 Ethernet Driver Configuration for VSC8531 (e.g. ETH0)

Table 5-1 FSP Configuration Value for VSC8531

Items	Default value	Config value for VSC8531	
		ETH0	ETH1
PHY-LSI Address	0	0	1
Select PHY	Default	VSC8541	VSC8541

(3) Add initialization code for VSC8531

The following code for VSC8531 initialization should be added to “ether_phy_targets_initialize_vsc8541” function in rzn/fsp/src/r_ether_phy/r_ether_phy.c.

The inclusion of “board_som.h” is also required for code activation.

```
#include "board_som.h"

                                ~~ Omission ~~

void ether_phy_targets_initialize_vsc8541 (ether_phy_instance_ctrl_t * p_instance_ctrl)
{
                                ~~ Omission ~~

    /* LED Behavior */
    reg = ether_phy_read(p_instance_ctrl, ETHER_PHY_REG_LED_BEHAVIOR);
    reg &= ~(1U << ETHER_PHY_REG_LED0_FEATURE_DISABLE_OFFSET);
    reg |= 1U << ETHER_PHY_REG_LED1_FEATURE_DISABLE_OFFSET;
    ether_phy_write(p_instance_ctrl, ETHER_PHY_REG_LED_BEHAVIOR, reg);
    #if defined(BOARD_RZN2L_SOM_KIT) /* for VSC8531 */
    /* select extended page 2 register */
    ether_phy_write(p_instance_ctrl, ETHER_PHY_REG_EXTEND_GPIO_PAGE, 0x02);

    /* read WoL and MAC Interface Control */
    reg = ether_phy_read(p_instance_ctrl, 0x1b);

    /* set control to slow */
    reg &= 0xFF9F;
    ether_phy_write(p_instance_ctrl, 0x1b, reg);

    /* Configure RX_CLK delay and TX_CLK delay to 2.0ns */
    ether_phy_write(p_instance_ctrl, ETHER_PHY_REG_EXPAGE2_RGMII_CTRL, 0x0044);

    /* select extended page 0 register */
    ether_phy_write(p_instance_ctrl, ETHER_PHY_REG_EXTEND_GPIO_PAGE, 0x00);
    #endif
}                                /* End of function ether_phy_targets_initialize() */
```

Revision History

Rev.	Date	Description	
		Page	Summary
1.00	Nov/30/2023	-	First Edition

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A strong electrical field, when exposed to a CMOS device, can cause destruction of the gate oxide and ultimately degrade the device operation. Steps must be taken to stop the generation of static electricity as much as possible, and quickly dissipate it when it occurs. Environmental control must be adequate. When it is dry, a humidifier should be used. This is recommended to avoid using insulators that can easily build up static electricity. Semiconductor devices must be stored and transported in an anti-static container, static shielding bag or conductive material. All test and measurement tools including work benches and floors must be grounded. The operator must also be grounded using a wrist strap. Semiconductor devices must not be touched with bare hands. Similar precautions must be taken for printed circuit boards with mounted semiconductor devices.

2. Processing at power-on

The state of the product is undefined at the time when power is supplied. The states of internal circuits in the LSI are indeterminate and the states of register settings and pins are undefined at the time when power is supplied. In a finished product where the reset signal is applied to the external reset pin, the states of pins are not guaranteed from the time when power is supplied until the reset process is completed. In a similar way, the states of pins in a product that is reset by an on-chip power-on reset function are not guaranteed from the time when power is supplied until the power reaches the level at which resetting is specified.

3. Input of signal during power-off state

Do not input signals or an I/O pull-up power supply while the device is powered off. The current injection that results from input of such a signal or I/O pull-up power supply may cause malfunction and the abnormal current that passes in the device at this time may cause degradation of internal elements. Follow the guideline for input signal during power-off state as described in your product documentation.

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5. Clock signals

After applying a reset, only release the reset line after the operating clock signal becomes stable. When switching the clock signal during program execution, wait until the target clock signal is stabilized. When the clock signal is generated with an external resonator or from an external oscillator during a reset, ensure that the reset line is only released after full stabilization of the clock signal. Additionally, when switching to a clock signal produced with an external resonator or by an external oscillator while program execution is in progress, wait until the target clock signal is stable.

6. Voltage application waveform at input pin

Waveform distortion due to input noise or a reflected wave may cause malfunction. If the input of the CMOS device stays in the area between V_{IL} (Max.) and V_{IH} (Min.) due to noise, for example, the device may malfunction. Take care to prevent chattering noise from entering the device when the input level is fixed, and also in the transition period when the input level passes through the area between V_{IL} (Max.) and V_{IH} (Min.).

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(Rev.5.0-1 October 2020)

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