

# V850E/DG3

32-bit Single-Chip Microcontroller

μPD70F3416

μPD70F3417

All information contained in these materials, including products and product specifications, represents information on the product at the time of publication and is subject to change by Renesas Electronics Corp. without notice. Please review the latest information published by Renesas Electronics Corp. through various means, including the Renesas Electronics Corp. website (<http://www.renesas.com>).

## Notice

1. All information included in this document is current as of the date this document is issued. Such information, however, is subject to change without any prior notice. Before purchasing or using any Renesas Electronics products listed herein, please confirm the latest product information with a Renesas Electronics sales office. Also, please pay regular and careful attention to additional and different information to be disclosed by Renesas Electronics such as that disclosed through our website.
1. Renesas Electronics does not assume any liability for infringement of patents, copyrights, or other intellectual property rights of third parties by or arising from the use of Renesas Electronics products or technical information described in this document. No license, express, implied or otherwise, is granted hereby under any patents, copyrights or other intellectual property rights of Renesas Electronics or others.
2. You should not alter, modify, copy, or otherwise misappropriate any Renesas Electronics product, whether in whole or in part.
3. Descriptions of circuits, software and other related information in this document are provided only to illustrate the operation of semiconductor products and application examples. You are fully responsible for the incorporation of these circuits, software, and information in the design of your equipment. Renesas Electronics assumes no responsibility for any losses incurred by you or third parties arising from the use of these circuits, software, or information.
4. When exporting the products or technology described in this document, you should comply with the applicable export control laws and regulations and follow the procedures required by such laws and regulations. You should not use Renesas Electronics products or the technology described in this document for any purpose relating to military applications or use by the military, including but not limited to the development of weapons of mass destruction. Renesas Electronics products and technology may not be used for or incorporated into any products or systems whose manufacture, use, or sale is prohibited under any applicable domestic or foreign laws or regulations.
5. Renesas Electronics has used reasonable care in preparing the information included in this document, but Renesas Electronics does not warrant that such information is error free. Renesas Electronics assumes no liability whatsoever for any damages incurred by you resulting from errors in or omissions from the information included herein.
6. Renesas Electronics products are classified according to the following three quality grades: "Standard", "High Quality", and "Specific". The recommended applications for each Renesas Electronics product depends on the product's quality grade, as indicated below. You must check the quality grade of each Renesas Electronics product before using it in a particular application. You may not use any Renesas Electronics product for any application categorized as "Specific" without the prior written consent of Renesas Electronics. Further, you may not use any Renesas Electronics product for any application for which it is not intended without the prior written consent of Renesas Electronics. Renesas Electronics shall not be in any way liable for any damages or losses incurred by you or third parties arising from the use of any Renesas Electronics product for an application categorized as "Specific" or for which the product is not intended where you have failed to obtain the prior written consent of Renesas Electronics.

The quality grade of each Renesas Electronics product is “Standard” unless otherwise expressly specified in a Renesas Electronics data sheets or data books, etc.

- “Standard”:
- Computers; office equipment; communications equipment; test and measurement equipment; audio and visual equipment; home electronic appliances; machine tools; personal electronic equipment; and industrial robots.
- “High Quality”:
- Transportation equipment (automobiles, trains, ships, etc.); traffic control systems; anti-disaster systems; anti-crime systems; safety equipment; and medical equipment not specifically designed for life support.
- “Specific”:
- Aircraft; aerospace equipment; submersible repeaters; nuclear reactor control systems; medical equipment or systems for life support (e.g. artificial life support devices or systems), surgical implantations, or healthcare intervention (e.g. excision, etc.), and any other applications or purposes that pose a direct threat to human life.

7. You should use the Renesas Electronics products described in this document within the range specified by Renesas Electronics, especially with respect to the maximum rating, operating supply voltage range, movement power voltage range, heat radiation characteristics, installation and other product characteristics. Renesas Electronics shall have no liability for malfunctions or damages arising out of the use of Renesas Electronics products beyond such specified ranges.
8. Although Renesas Electronics endeavors to improve the quality and reliability of its products, semiconductor products have specific characteristics such as the occurrence of failure at a certain rate and malfunctions under certain use conditions. Further, Renesas Electronics products are not subject to radiation resistance design. Please be sure to implement safety measures to guard them against the possibility of physical injury, and injury or damage caused by fire in the event of the failure of a Renesas Electronics product, such as safety design for hardware and software including but not limited to redundancy, fire control and malfunction prevention, appropriate treatment for aging degradation or any other appropriate measures. Because the evaluation of microcomputer software alone is very difficult, please evaluate the safety of the final products or system manufactured by you.
9. Please contact a Renesas Electronics sales office for details as to environmental matters such as the environmental compatibility of each Renesas Electronics product. Please use Renesas Electronics products in compliance with all applicable laws and regulations that regulate the inclusion or use of controlled substances, including without limitation, the EU RoHS Directive. Renesas Electronics assumes no liability for damages or losses occurring as a result of your noncompliance with applicable laws and regulations.
10. This document may not be reproduced or duplicated, in any form, in whole or in part, without prior written consent of Renesas Electronics.
11. Please contact a Renesas Electronics sales office if you have any questions regarding the information contained in this document or Renesas Electronics products, or if you have any other inquiries.

(Note 1) “Renesas Electronics” as used in this document means Renesas Electronics Corporation and also includes its majority-owned subsidiaries.

(Note 2) “Renesas Electronics product(s)” means any product developed or manufactured by or for Renesas Electronics.

## General Precautions in the Handling of MPU/MCU Products

The following usage notes are applicable to all MPU/MCU products from Renesas. For detailed usage notes on the products covered by this manual, refer to the relevant sections of the manual. If the descriptions under General Precautions in the Handling of MPU/MCU Products and in the body of the manual differ from each other, the description in the body of the manual takes precedence.

### 1. Handling of unused Pins

Handle unused pins in accord with the directions given under Handling of Unused Pins in the manual.

- The input pins of CMOS products are generally in the high-impedance state. In operation with an unused pin in the open-circuit state, extra electromagnetic noise is induced in the vicinity of LSI, an associated shoot-through current flows internally, and malfunctions occur due to the false recognition of the pin state as an input signal become possible. Unused pins should be handled as described under Handling of Unused Pins in the manual.

### 2. Processing at power-on

The state of the product is undefined at the moment when power is supplied.

- The states of internal circuits in the LSI are indeterminate and the states of register settings and pins are undefined at the moment when power is supplied.

In a finished product where the reset signal is applied to the external reset pin, the states of pins are not guaranteed from the moment when power is supplied until the reset process is completed.

In a similar way, the states of pins in a product that is reset by an on-chip power-on reset function are not guaranteed from the moment when power is supplied until the power reaches the level at which resetting has been specified.

### 3. Prohibition of access to reserved addresses

Access to reserved addresses is prohibited.

- The reserved addresses are provided for the possible future expansion of functions. Do not access these addresses; the correct operation of LSI is not guaranteed if they are accessed.

### 4. Clock signals

After applying a reset, only release the reset line after the operating clock signal has become stable. When switching the clock signal during program execution, wait until the target clock signal has stabilized.

- When the clock signal is generated with an external resonator (or from an external oscillator) during a reset, ensure that the reset line is only released after full stabilization of the clock signal. Moreover, when switching to a clock signal produced with an external resonator (or by an external oscillator) while program execution is in progress, wait until the target clock signal is stable.

### 5. Differences between products

Before changing from one product to another, i.e. to one with a different part number, confirm that the change will not lead to problems.

- The characteristics of MPU/MCU in the same group but having different part numbers may differ because of the differences in internal memory capacity and layout pattern. When changing to products of different part numbers, implement a system-evaluation test for each of the products.

---

**Table of Contents**

<b>Chapter 1</b>	<b>Overview</b>	7
1.1	General	7
<b>Chapter 2</b>	<b>Pinout Information</b>	9
2.1	Pin Configuration $\mu$ PD70F3417(A), $\mu$ PD70F3416(A)	9
2.2	Pin Group information	10
<b>Chapter 3</b>	<b>Absolute Maximum Ratings</b>	12
3.1	Conditions for Extended Operating Temperature Range: $T_A = -40 \sim 105^\circ\text{C}$	15
<b>Chapter 4</b>	<b>General Characteristics</b>	16
4.1	Requirements for external power supply connections	16
4.2	Capacitance connected to REGC0	16
4.3	Main Oscillator Characteristics	17
4.4	Sub-Oscillator Characteristics	19
4.5	Peripheral PLL Characteristics	20
4.6	Spread Spectrum PLL Characteristics	21
4.7	Ring Oscillator Characteristics	21
4.8	I/O Capacitances	22
<b>Chapter 5</b>	<b>Operation Conditions</b>	23
5.1	CPU Clock	23
5.2	Peripheral Clock	23
<b>Chapter 6</b>	<b>DC Characteristics</b>	25
6.1	General DC Characteristics	25
6.2	Injected Current Characteristics	26
6.3	Pin Group 1	27
6.4	Pin group 2: $\overline{\text{RESET}}$ and FLMD0	29
6.5	Pin Group 3: GPIO and LCD Controller	30
6.6	ADC Input	33
6.7	LCD Common and Segment Lines	35
6.8	Stepper Motor Driver IO	36
6.9	Current Limit Function of I/O buffers	39
6.10	Supply Current	41
<b>Chapter 7</b>	<b>AC Characteristics</b>	43
7.1	AC Test Input/Output Waveform	43
7.2	AC Test Load Condition	43
7.3	Reset	44
7.4	Interrupt Timing	45
7.5	Peripheral Function Characteristics	46
7.5.1	Timer P	46
7.5.2	Timer G	47
7.5.3	UARTA	47
7.5.4	CAN	47

---

7.5.5	CSI B (High Voltage Operation) .....	48
7.5.6	CSIB (Low Voltage Operation) .....	51
7.5.7	I <sup>2</sup> C .....	54
<b>Chapter 8 Analog Functions .....</b>		<b>56</b>
8.1	A/D Converter .....	56
8.2	Power On Clear .....	57
<b>Chapter 9 Memory Characteristics .....</b>		<b>58</b>
9.1	Basic Characteristics .....	58
9.2	Flash Memory Characteristics .....	59
9.3	Special Conditions for End-of-Line Programming .....	60
9.4	Serial Write Operation Characteristics .....	62
<b>Chapter 10 Package .....</b>		<b>63</b>
<b>Appendix A Revision History .....</b>		<b>64</b>

# Chapter 1 Overview

The V850E/DG3 is a product in Renesas V850 family of single-chip microcontrollers designed for Automotive applications.

## 1.1 General

The V850E/DG3 single-chip microcontroller, is a member of Renesas V850 32-bit RISC family, which match the performance gains attainable with RISC-based controllers to the needs of embedded control applications. The V850 CPU offers easy pipeline handling and programming, resulting in compact code size comparable to 16-bit CISC CPUs.

The V850E/DG3 provides an excellent combination of general purpose peripheral functions, like serial communication interfaces (UART, clocked SI), Timers and measurement inputs (A/D converter), with dedicated CAN network support. Control and driver for 6 stepper motors are included.

The device offers power-saving modes to manage the power consumption effectively under varying conditions.

Thus equipped, the V850E/DG3 is ideally suited for automotive applications, like dashboard or body. It is also an excellent choice for other applications where a combination of sophisticated peripheral functions and CAN network support is required.

This specification covers the following devices of the family:

Family Code	Product Code	Package	Internal Flash	Internal RAM
DG3	$\mu$ PD70F3417GC(A)-UEU	LQFP 14 x 14mm	256 kbyte	12 kbytes
	uPD70F3416GC(A)-UEU		128 kbyte	6 kbytes

The following table gives a more detailed overview of the different derivatives and their major features.

Series name		V850E/DG3	
Product Code		μPD70F3417(A)	μPD70F3416(A)
Technology		MF2 (Flash)	MF2 (Flash)
Internal memory	Flash	256kB	128kB
	ROM	None	None
	RAM	12kB	6kB
Operating Clock	Main (internal)	24MHz <sup>a</sup> max.	
	Ring-OSC	240kHz typ.	
	Subclock	32kHz typ.	
I/O ports		72	
Input ports		8	
A/D converter		8 ch	
Timers	TMZ	6 ch	
	TMP	1 ch	
	TMG	2 ch	
	TM0	1 ch	
	WDT	provided	
	Watch	provided	
	Watch calibration	provided	
Serial interfaces	AFCAN	1 ch (with 32 message buffers)	
	UARTA	2 ch (with LIN support)	
Serial interfaces	CSIB	2 ch	
	IIC	1 ch	
Interrupts	External	4	
	Internal	52	
	NMI	2	
Other functions	ROM-correction	6 ch	
	POC	provided	
	Clock supervision	2 ch	
	Sound generator	1 ch	
	Stepper motor C/D	4 ch	
	LCD C/D	40 x 4	
	Auxilliary frequency output	provided	
Operating voltage		3.2V to 5.5V for core functions, ADC and StepperMotor C/D, 3.0V to 5.5V for all other I/O Full operation in range from 3.5V to 5.5V due to POC function (8.2 on page 57)	
Package		100-pin LQFP	

<sup>a)</sup> Operated with spread spectrum PLL



# Chapter 2 Pinout Information

## 2.1 Pin Configuration $\mu$ PD70F3417(A), $\mu$ PD70F3416(A)

- $\mu$ PD70F3417(A)GC
- $\mu$ PD70F3416(A)GC

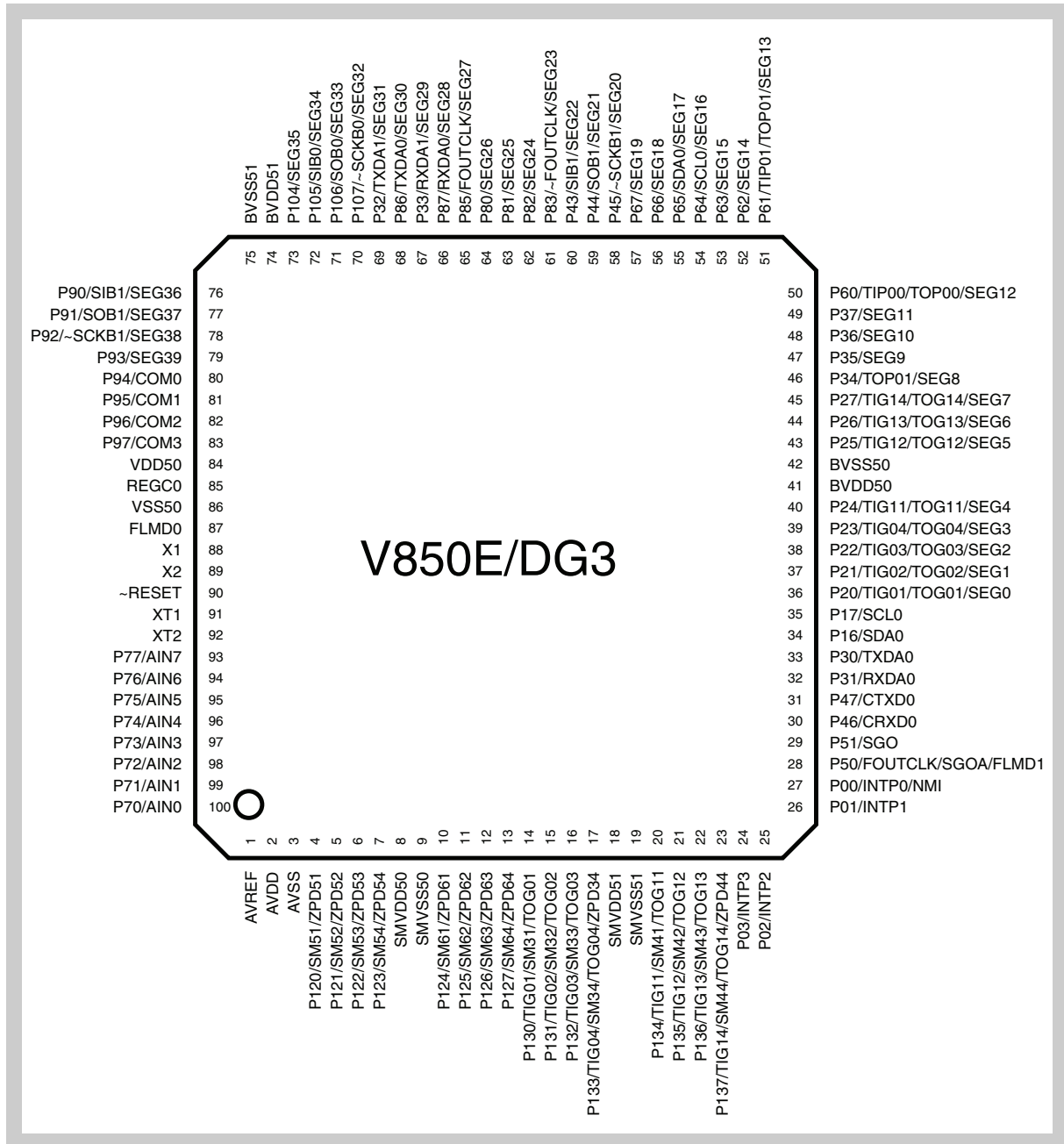


Figure 2-1 Pin Configuration  $\mu$ PD70F3417(A),  $\mu$ PD70F3416(A)

## 2.2 Pin Group information

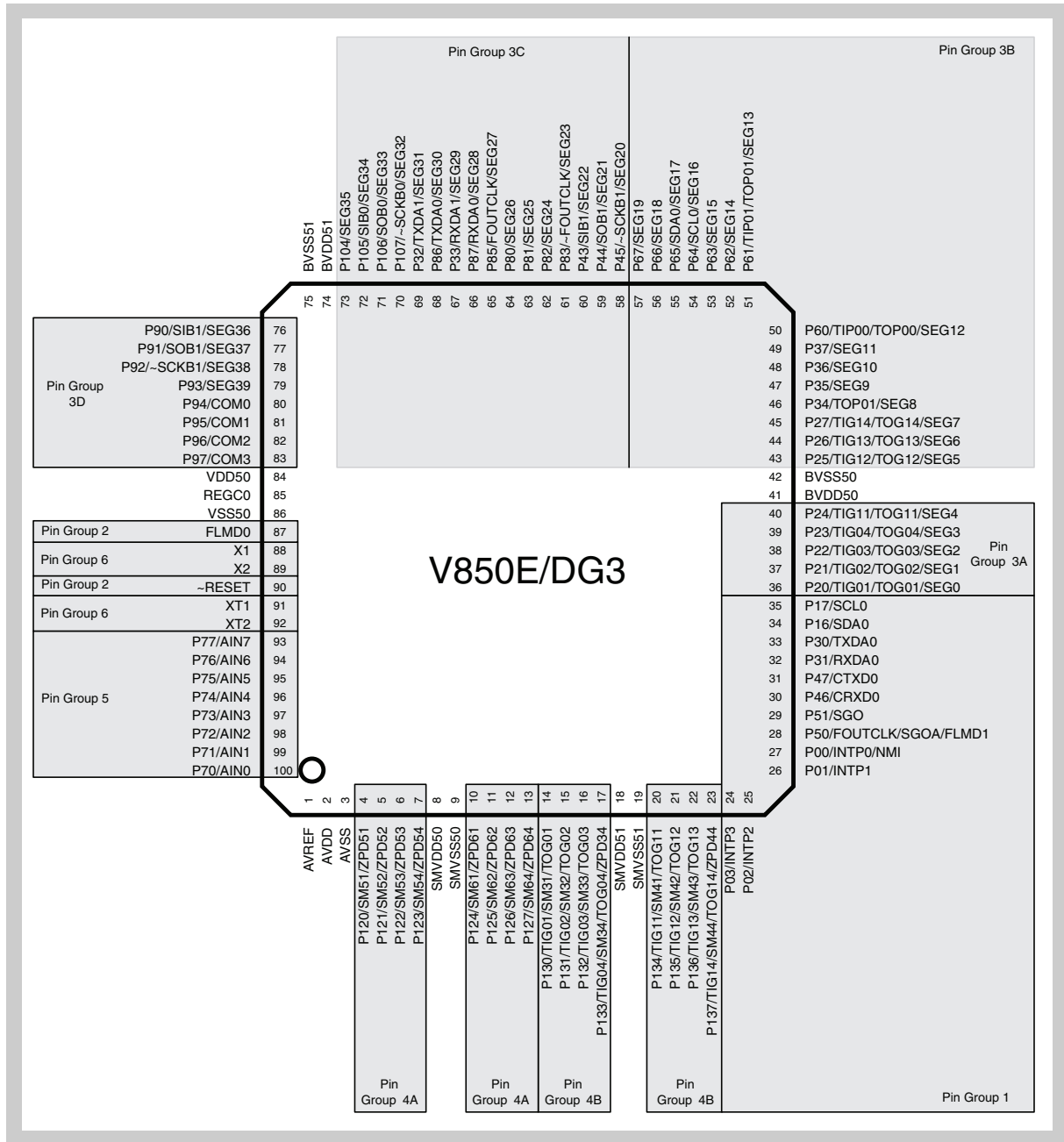


Figure 2-2 Pin Group Information  $\mu$ PD70F3417(A),  $\mu$ PD70F3416(A)

- Pin Groups 1x: GPIO pins supplied by  $BV_{DD5}$   
1: P00-P03, P16-P17, P30-P31, P46-P47, P50-P51
- Pin Group 2: Pins supplied by  $V_{DD50}$   
2: ( $\overline{\text{RESET}}$ , FLMD0)
- Pin Group 3x: GPIO and LCD controller supplied by  $BV_{DD5}$   
3A: P20-P24  
3B: P20-P27, P34-P37, P60-P67  
3C: P32, P43-P45, P80-P83, P85-P87, P104-P107  
3D: P90-P97
- Pin Group 4x: Stepper Motor outputs supplied by  $SMV_{DD5}$   
4A: P120-P127  
4B: P130-P137
- Pin Group 5: ADC Inputs supplied by  $AV_{DD}$   
5: P70-P77
- Pin Group 6: Oscillator function supplied internally  
6: X1, X2, XT1, XT2
- Pin Group 7: Pins used for ZPD (if supported). This group is a subset of Group 4.  
7: P120-P127, P133, P137

## Chapter 3 Absolute Maximum Ratings

**Condition 1:**  $T_A = -40 \dots +85^\circ\text{C}$ ,  
 Operation Modes: RUN, HALT, IDLE  
 Power dissipation:  $< 0.61\text{W}$   
 Duration: 15000 hours  
 $V_{SS5} = 0\text{V}$

**Condition 2:**  $T_A = -40 \dots +85^\circ\text{C}$ ,  
 Operation Modes: WATCH, Sub-WATCH, STOP, Sub-Clock CPU Operation  
 Power dissipation:  $< 0.5\text{W}$   
 Duration: 15 years  
 $V_{SS5} = 0\text{V}$

**Table 3-1 Absolute maximum ratings voltages**

Parameter		Symbol	Test Conditions	Ratings <sup>a</sup>	Unit
Supply voltage		$V_{DD5}$		-0.5 ~ +6.5	V
		$AV_{DD}$		-0.5 ~ +6.5	V
		$AV_{REF}$		-0.5 ~ +6.5	V
		$BV_{DD5}$		-0.5 ~ +6.5	V
		$SMV_{DD5}$		-0.5 ~ +6.5	V
		$AV_{SS}$		-0.5 ~ +0.5	V
		$BV_{SS5}$		-0.5 ~ +0.5	V
		$SMV_{SS5}$		-0.5 ~ +0.5	V
Input voltage	Group 1	$V_{I1}$	$V_{I1} < BV_{DD5} + 0.5 \text{ V}$	-0.5 ~ + 6.5	V
	Group 2	$V_{I2}$	$V_{I2} < V_{DD5} + 0.5 \text{ V}$	-0.5 ~ + 6.5	V
	Group 4	$V_{I4}$	$V_{I4} < SMV_{DD5} + 0.5 \text{ V}$	-0.5 ~ + 6.5	V
	Group 5, AVREF	$V_{IA}$	$V_{IA} < AV_{DD} + 0.5 \text{ V}$	-0.5 ~ + 6.5	V
Special <sup>b</sup>	X1, X2, XT1, XT2, REGC0	$V_{IS}$		-0.5 ~ + 3.6	V
Output voltage		$V_O$		-0.5 ~ +6.5	V
Operating temperature (ambient)		$T_{OPR}$		-40 ~ +85	$^\circ\text{C}$
Storage temperature		$T_{STGB}$		-40 ~ +150	$^\circ\text{C}$

a) Currents are average current over the given life time. Transient currents are not relevant as long as the average of transient is below the given value.

b) These pins are for special use only and should not be used for other connections than specified. Pins operate with the internal generated core voltage.

**Note** See “Pinout Information” on page 9. for pin to group association.

- $V_{DD5}$  is the supply voltage for the internal voltage regulators applied to pin  $V_{DD50}$ .
- $V_{SS5}$  is the ground for the internal logic applied to pin  $V_{SS50}$ .
- $A_{VDD}$  is the supply for analog part of the A/D converter.
- $A_{VSS}$  is the ground for the analog part of the A/D converter.
- $BV_{DD5}$  is the supply voltage for the I/O buffers applied to pins  $BV_{DD5x}$ .
- $BV_{SS5}$  is the ground for the I/O buffers applied to pins  $BV_{SS5x}$ .
- $SMV_{DD5}$  is the supply voltage for the I/O buffers of the stepper motor drivers applied to pins  $SMV_{DD5x}$ .
- $SMV_{SS5}$  is the ground for the I/O buffers of the stepper motor drivers applied to pins  $SMV_{SS5x}$ .

Table 3-2 Absolute maximum ratings currents

Parameter		Symbol	Test Conditions	Ratings average <sup>a</sup>	Ratings peak <sup>b</sup>	Unit
Output current low	1 pin	$I_{OL1}$	Groups 1, 3A, 3B, 3C, 3D	30	50	mA
	All pins	$I_{OLA1}$	Group 1	50	100	mA
	All pins	$I_{OLA3A}$	Group 3A	50	100	mA
	All pins	$I_{OLA3B}$	Group 3B	50	100	mA
	All pins	$I_{OLA13AB}$	Sum of groups 1, 3A, 3B	100	200	mA
	All pins	$I_{OLA3C}$	Group 3C	50	100	mA
	All pins	$I_{OLA3D}$	Group 3D	50	100	mA
	All pins	$I_{OLA3CD}$	Sum of Groups 3C, 3D	100	200	mA
	1 pin	$I_{OL4}$	Group 4A	45	55	mA
	All pins	$I_{OLA4A}$		200	270	mA
	1 pin	$I_{OL4}$	Group 4B	45	55	mA
	All pins	$I_{OLA4B}$		200	270	mA
	Output current high	1 pin	$I_{OH1}$	Groups 1, 3A, 3B, 3C, 3D	-30	-50
All pins		$I_{OHA1}$	Group 1	-50	-100	mA
All pins		$I_{OHA3A}$	Group 3A	-50	-100	mA
All pins		$I_{OHA3B}$	Group 3B	-50	-100	mA
All pins		$I_{OHA13B}$	Sum of Groups 1, 3A, 3B	-100	-200	mA
All pins		$I_{OHA3C}$	Group 3C	-50	-100	mA
All pins		$I_{OHA3D}$	Group 3D	-50	-100	mA
All pins		$I_{OH3CD}$	Sum of Groups 3C, 3D	-100	-200	mA
1 pin		$I_{OH4A}$	Group 4A	-45	-55	mA
All pins		$I_{OHA4A}$		-200	-270	mA
Output current high	1 pin	$I_{OH4}$	Group 4B	-45	-55	mA
	All pins	$I_{OHA4B}$		-200	-270	mA

a) Currents are averaged current over the given life time. Transient currents are not relevant as long as the average of transient is below the given value.

b) The peak current sets the limit for short term current flows.

### 3.1 Conditions for Extended Operating Temperature Range: $T_A = -40 \sim 105^\circ\text{C}$

- Caution**
1. For any device's operation within the extended operating temperature range ( $T_A = -40 \dots +105^\circ\text{C}$ ), the device's total power consumption must be reduced. The following tables of this chapter describe additional device conditions securing the requested decrease of the device's power consumption.
  2. In case any device may operate within the extended operating temperature range ( $T_A = -40 \dots +105^\circ\text{C}$ ) all of the below mentioned conditions must never be exceeded at any time.
  3. All of the below mentioned device conditions must be applied in addition to any other parameter that is described within this document

**Condition 1:**  $T_A = -40 \dots +105^\circ\text{C}$ ,  
 Operation Modes: RUN, HALT, IDLE  
 Power dissipation:  $< 0.52\text{W}$   
 Duration: 15000 hours  
 $V_{SS5} = 0\text{V}$

**Condition 2:**  $T_A = -40 \dots +105^\circ\text{C}$ ,  
 Operation Modes: WATCH, Sub-WATCH, STOP, Sub-Clock CPU Operation  
 Power dissipation:  $< 0.5\text{W}$   
 Duration: 15 years  
 $V_{SS5} = 0\text{V}$

**Table 3-3 Absolute maximum ratings currents  $105^\circ\text{C}$**

Parameter		Symbol	Test Conditions		Ratings average	Unit
Output current low	All pins	$I_{OLA}$	Sum of Groups 1, 3, 5	$f_{\text{sys}} = 16\text{MHz}$	100	mA
Output current high		$I_{OHA}$			-100	mA
Number of active stepper motor driver					4	

## Chapter 4 General Characteristics

### 4.1 Requirements for external power supply connections

The user has to ensure a low resistive connection of

- all VSS pins on the PCB. This specification denotes this as:

$$V_{SS5} = BV_{SS5} = SMV_{SS5} = AV_{SS} = 0 \text{ V}$$

in the further text.

- the  $V_{DD50}$  pin.
- all  $BV_{DD5x}$  pins.
- all  $SMV_{DD5x}$  pins.

### 4.2 Capacitance connected to REGC0

The Device requires to connect a capacitor with the following parameters to the pin REGC0. The pin REGC0 must not be connected externally.

Table 4-1 External Capacitance Requirement

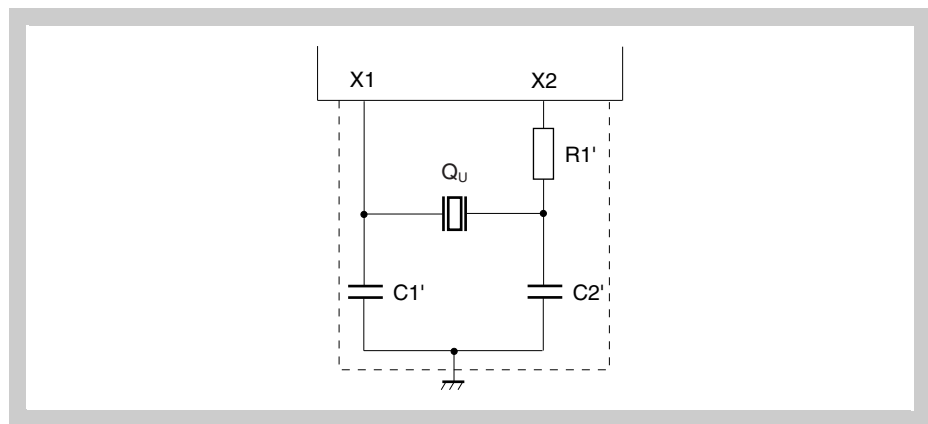
Parameter	Symbol	Test Conditions	Min.	Typ	Max.	Unit
Capacitance	$C_{REG}$		3.3	4.7	10	$\mu\text{F}$
ESR of capacitance	$C_{ESR}$	F0 = 100kHz			0.6	$\Omega$



### 4.3 Main Oscillator Characteristics

**Conditions**  $T_A = -40 \sim +85^\circ\text{C}$ ,  
 $BV_{DD5} = 3.0 \text{ V} \sim 5.5 \text{ V}$ ,  
 $AV_{DD} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  $SMV_{DD5} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  
 $V_{DD5} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  
 $V_{SS5} = BV_{SS5} = SMV_{SS5} = AV_{SS} = 0 \text{ V}$

- Note**
1. Refer to "Power On Clear" on page 57 for further functional restriction.
  2. A ceramic or crystal resonator has to be connected to the main clock input pins as shown in Figure 4-1.
  3. External clock supply is not possible in user mode due to oscillator circuit limitation.



**Figure 4-1** Recommended Main Oscillator Circuit

**Note** Values of  $C_1$ ,  $C_2$  and  $R$  depend on the used crystal or resonator and must be specified in cooperation with crystal/resonator manufacturer.

- Caution**
1. External clock input is prohibited.
  2. When using the main system clock oscillator, wire as shown in above figure. This will avoid an adverse effect from wiring capacitance.
    - Keep the wiring length as short as possible.
    - Do not cross the wiring with other signal lines.
    - Do not route this circuit close to a signal line with high fluctuating current flow.
    - Always make the ground point of the oscillator capacitor the same potential as  $V_{SS}$ .
    - Do not ground the capacitor to a ground pattern with high current flow.
    - Do not fetch signals from the oscillator.

**Table 4-2 Main Oscillator Characteristics**

Parameter	Symbol	Test Conditions	MIN.	TYP.	MAX.	Unit
Oscillation stabilization time	$T_{OST}$	OSC MODE			16 <sup>a</sup>	ms
X1, X2 Oscillator Frequency	$f_{OSC}$		3.6	4.0	4.4	MHz

a)  $T_{OST}$  depends on the external crystal. Shorter timing might be found by evaluation.

**Remark** This value is valid for crystal operation only.

**Table 4-3 Main Oscillator Characteristics - Crystal Type NDK LN-G8-1404**

Parameter	Symbol	Test Conditions	MIN.	TYP.	MAX.	Unit
Oscillation stabilization time	$T_{OST}$	OSC MODE			10 <sup>a</sup>	ms
X1, X2 Oscillator Frequency	$f_{OSC}$		3.6	4.0	4.4	MHz

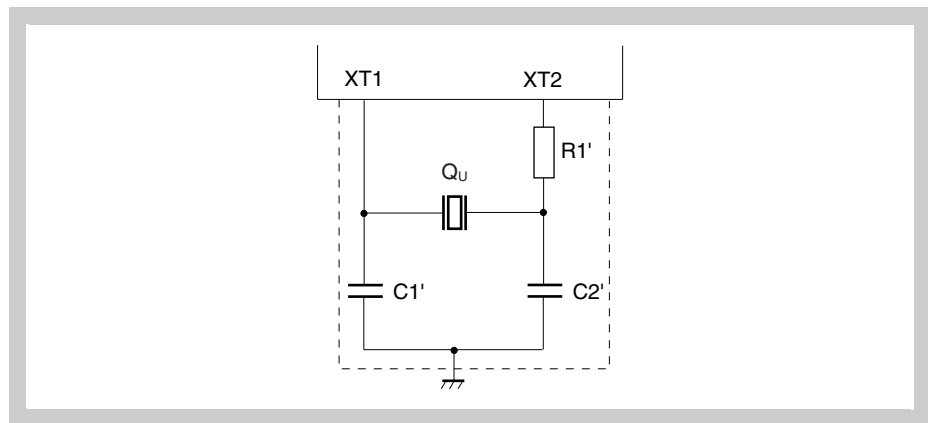
a) The given oscillation stabilization time is valid exclusively in case the below mentioned crystal-type from the manufacturer NDK is used for the main-oscillator operation. Beside the application of this specific crystal type, the PCB-design and capacitance configuration must ensure proper operation of the crystal enabling a load capacitance of about  $CL=12$  pF. This parameter has to be verified by a dedicated crystal-evaluation based on the final PCB.

NDK Spec. No.: LN-G8-1404  
 Holder: AT-51GW  
 Frequency: 4.000 MHz

## 4.4 Sub-Oscillator Characteristics

**Conditions**  $T_A = -40 \sim +85^\circ\text{C}$ ,  
 $BV_{DD5} = 3.0 \text{ V} \sim 5.5 \text{ V}$ ,  
 $AV_{DD} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  $SMV_{DD5} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  
 $V_{DD5} = 3.2 \text{ V} \sim 5.5 \text{ V}$ , (see “Power On Clear” on page 57 for further functional restriction),  
 $V_{SS5} = BV_{SS5} = SMV_{SS5} = AV_{SS} = 0 \text{ V}$

- Note**
1. Refer to “Power On Clear” on page 57 for further functional restriction.
  2. A crystal resonator has to be connected to the sub clock input pins as shown in Figure 4-2.
  3. External clock supply is not possible in user mode due to oscillator circuit limitation.



**Figure 4-2** Recommended Sub Oscillator Circuit

**Note** Values of  $C_{S1}$ ,  $C_{S2}$  and  $R_S$  depend on the used crystal and must be specified in cooperation with crystal manufacturer.

- Caution**
1. External clock input is prohibited.
  2. When using the main system clock oscillator, wire as shown in above figure. This will avoid an adverse effect from wiring capacitance.
    - Keep the wiring length as short as possible.
    - Do not cross the wiring with other signal lines.
    - Do not route this circuit close to a signal line with high fluctuating current flow.
    - Always make the ground point of the oscillator capacitor the same potential as  $V_{SS}$ .
    - Do not ground the capacitor to a ground pattern with high current flow.
    - Do not fetch signals from the oscillator.

**Table 4-4 Sub Oscillator Characteristics**

Parameter	Symbol	Test Conditions	Min.	Typ	Max	Unit
XT1,XT2 Oscillator Frequency	$f_{SOSC}$		32	32.768	35	KHz
Sub oscillator stabilization time	$T_{SOST}$				5 <sup>a</sup>	s

a)  $T_{SOST}$  depends on the external crystal. Shorter timing might be found by evaluation.

**Remark** These values are valid for crystal operation only.

## 4.5 Peripheral PLL Characteristics

**Conditions**  $T_A = -40 \sim +85^\circ\text{C}$ ,  
 $BV_{DD5} = 3.0 \text{ V} \sim 5.5 \text{ V}$ ,  
 $AV_{DD} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  $SMV_{DD5} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  
 $V_{DD5} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  
 $V_{SS5} = BV_{SS5} = SMV_{SS5} = AV_{SS} = 0 \text{ V}$

**Note** Refer to "Power On Clear" on page 57 for further functional restriction.

**Table 4-5 Peripheral PLL Characteristics**

Parameter	Symbol	Test Conditions	MIN.	TYP.	MAX.	Unit
PLL Startup Time	$T_{PST}$	OSC MODE			1.2	ms
PLL Output period jitter <sup>a</sup>	$T_{PJ}$	Peak to peak			1	ns
PLL Long term jitter <sup>a</sup>	$T_{LJ}$	Time = 20 $\mu$ s			2	ns

a) Not tested in production. Specified by design.

## 4.6 Spread Spectrum PLL Characteristics

**Conditions**  $T_A = -40 \sim +85^\circ\text{C}$ ,  
 $BV_{DD5} = 3.0 \text{ V} \sim 5.5 \text{ V}$ ,  
 $AV_{DD} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  $SMV_{DD5} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  
 $V_{DD5} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  
 $V_{SS5} = BV_{SS5} = SMV_{SS5} = AV_{SS} = 0 \text{ V}$

**Note** Refer to “Power On Clear” on page 57 for further functional restriction.

**Table 4-6 Spread Spectrum PLL Characteristics**

Parameter	Symbol	Test Conditions	MIN.	TYP.	MAX.	Unit
SSCG Startup Time	$T_{SSCGST}$	OSC MODE			1.2	ms
SSCG Frequency modulation range <sup>a</sup>	DITHER	OSC MODE, dither setting 3%	0		$\pm 4.2$	%
		OSC MODE, dither setting 5%			$\pm 6.8$	%
SSCG center frequency during dithering <sup>a</sup>	$f_{DITHER}$			1.0 * $f_{nominal}$		
SSCG modulation frequency <sup>a</sup>	$f_{Mod}$	SCFMC1-0 = <sup>b</sup>				kHz
		01		40		
		10		50		
		11		60		

a) Not tested in production. Specified by design.

b) The typical modulation frequency can be selected by register SCFMC.

## 4.7 Ring Oscillator Characteristics

**Conditions**  $T_A = -40 \sim +85^\circ\text{C}$ ,  
 $BV_{DD5} = 3.0 \text{ V} \sim 5.5 \text{ V}$ ,  
 $AV_{DD} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  $SMV_{DD5} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  
 $V_{DD5} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  
 $V_{SS5} = BV_{SS5} = SMV_{SS5} = AV_{SS} = 0 \text{ V}$

**Note** Refer to “Power On Clear” on page 57 for further functional restriction.

**Table 4-7 Ring Oscillator Characteristics**

Parameter	Symbol	Test Conditions	Min.	Typ	Max	Unit
Ring Oscillator Frequency	$f_{RING}$		200	240	300	KHz
Ring oscillator Stabilization Time <sup>a</sup>	$T_{ROST}$				20	$\mu\text{s}$

a) Not tested in production. Specified by design.

## 4.8 I/O Capacitances

**Conditions**  $T_A = -40 \sim +85^\circ\text{C}$ ,  
 $BV_{DD5} = 3.0 \text{ V} \sim 5.5 \text{ V}$ ,  
 $AV_{DD} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  $SMV_{DD5} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  
 $V_{DD5} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  
 $V_{SS5} = BV_{SS5} = SMV_{SS5} = AV_{SS} = 0 \text{ V}$

**Note** Refer to “Power On Clear” on page 57 for further functional restriction.

**Table 4-8 I/O Characteristics**

Parameter	Symbol	Test Conditions	MIN.	TYP.	MAX.	Unit
Input capacitance	$C_I$	$f_C = 1 \text{ MHz}$ Unmeasured pins returned to 0 V			10	pF
Input/output capacitance, all I/O pins except group 4	$C_{IO}$				15	pF
Input/output capacitance Group 4	$C_{IO4}$				30	pF

# Chapter 5 Operation Conditions

## 5.1 CPU Clock

**Conditions**  $T_A = -40 \sim +85^\circ\text{C}$ ,  
 $BV_{DD5} = 3.0 \text{ V} \sim 5.5 \text{ V}$ ,  
 $AV_{DD} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  $SMV_{DD5} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  
 $V_{DD5} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  
 $V_{SS5} = BV_{SS5} = SMV_{SS5} = AV_{SS} = 0 \text{ V}$

**Note** Refer to “Power On Clear” on page 57 for further functional restriction.

**Table 5-1 CPU Clock Frequencies**

Clock Mode	Prescale	Operation Mode	Device	CPU Operation Clock Frequency [MHz]
OSC mode	n/a	all modes	all	4
OSC mode, PLL x8	1/2			16
OSC mode, SSCG x12	1/6			8
OSC mode, SSCG x16	1/4			16
OSC mode, SSCG x 12	1/2			24
OSC mode, Ring OSC	n/a			0.2
OSC mode, Sub OSC	n/a			0.032

## 5.2 Peripheral Clock

**Conditions**  $T_A = -40 \sim +85^\circ\text{C}$ ,  
 $BV_{DD5} = 3.0 \text{ V} \sim 5.5 \text{ V}$ ,  
 $AV_{DD} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  $SMV_{DD5} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  
 $V_{DD5} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  
 $V_{SS5} = BV_{SS5} = SMV_{SS5} = AV_{SS} = 0 \text{ V}$

**Note** Refer to “Power On Clear” on page 57 for further functional restriction.

**Table 5-2 Peripheral Clock Frequencies**

Clock	Clock Source	Max	Unit
PCLK0 - 1	Main OSC	4	MHz
	Main OSC, PLL x 8	16, 8	MHz
PCLK2 - 15	Main OSC	4, 2, ... , 1/2048	MHz

Table 5-2 Peripheral Clock Frequencies (Continued)

Clock	Clock Source	Max	Unit
IICLK	Main OSC	4	MHz
	Main OSC, PLL x8	32 <sup>a</sup>	MHz
	Main OSC, SSCG		
SPCLK0 - 1	Main OSC	4	MHz
	Main OSC, PLL x8	16, 8 <sup>b</sup>	MHz
	Main OSC, SSCG		
SPCLK2 - 15	Main OSC	4, 2 ... 1/2048	MHz
	Main OSC, SSCG		
FOUT (CLKOUT)	Main OSC, PLL x8	32	MHz
	Main OSC, SSCG	32 <sup>c</sup>	MHz
	Main OSC	4	MHz
	Ring OSC	0.2	MHz
	Sub OSC	0.032	MHz
LCDCLK	Main OSC	4	MHz
	Ring OSC	0.2	MHz
	Sub OSC	0.032	MHz
WTCLK	Main OSC	4	MHz
	Ring OSC	0.2	MHz
	Sub OSC	0.032	MHz
WDTCLK	Main OSC	4	MHz
	Ring OSC	0.2	MHz
	Sub OSC	0.032	MHz
WCTCLK	Main OSC	4	MHz
	PCLK1	see PCLK1	MHz
TMCCLK	Main OSC	4	MHz
	PCLK1	see PCLK1	MHz

- a) needs to be ensured by proper configuration of the IICLK divider.  
b) needs to be ensured by proper configuration of the SPCLK divider.  
c) needs to be ensured by proper configuration of the FOUT (CLKOUT) divider.



# Chapter 6 DC Characteristics

## 6.1 General DC Characteristics

**Conditions**  $T_A = -40 \sim +85^\circ\text{C}$ ,  
 $BV_{DD5} = 3.0 \text{ V} \sim 5.5 \text{ V}$ ,  
 $AV_{DD} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  $SMV_{DD5} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  
 $V_{DD5} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  
 $V_{SS5} = BV_{SS5} = SMV_{SS5} = AV_{SS} = 0 \text{ V}$

**Note** Refer to "Power On Clear" on page 57 for further functional restriction.

**Table 6-1 General DC Characteristics**

Parameter	Pin Group	Symbol	Test Conditions	Min.	Typ	Max.	Unit
Input leakage	1	$I_{LI1}$	$0 \leq V_I \leq BV_{DD5}$	-1		+1	$\mu\text{A}$
	2	$I_{LI2}$	$0 \leq V_I \leq V_{DD50}$	-1		+1	$\mu\text{A}$
	3	$I_{LI3}$	$0 \leq V_I \leq V_{DD50}$	-1		+1	$\mu\text{A}$
	4	$I_{LIS}$	$0 \leq V_I \leq SMV_{DD5}$	-10		+10	$\mu\text{A}$
	5	$I_{LIA}$	$0 \leq V_I \leq AV_{DD}$	-0.2		+0.2	$\mu\text{A}$

## 6.2 Injected Current Characteristics

**Conditions**  $T_A = -40 \sim +85^\circ\text{C}$ ,  
 $BV_{DD5} = 3.0 \text{ V} \sim 5.5 \text{ V}$ ,  
 $AV_{DD} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  $SMV_{DD5} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  
 $V_{DD5} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  
 $V_{SS5} = BV_{SS5} = SMV_{SS5} = AV_{SS} = 0 \text{ V}$

**Note** Refer to “Power On Clear” on page 57 for further functional restriction.

**Table 6-2 Injected Current Characteristics**

Parameter	Pin Group	Symbol	Test Conditions	Min.	Typ	Max.	Unit
Injected current per pin <sup>a</sup>	All, except 5	$I_{INJ}$		-2		+2	mA
Injected current per pin <sup>a</sup>	5	$I_{INJ}$	b	-2		+2	mA

- a) The injected current will not be tested during production. Value will be verified by evaluation. The total current per pin group (injected plus operating) has to be in the limits of the absolute maximum ratings for output currents (values for output current low and output current high). The operation voltage must stay in the limits of the operating conditions. The user has to make sure that the injected current does not pull the supplied voltage outside of the operating conditions.
- b) The accuracy of the ADC specified in this document is only valid when the sum of all currents of pin group 5 is in the range of -14mA and +14mA.

## 6.3 Pin Group 1

Pin Group 1x: Pins supplied by  $BV_{DD5}$   
P00-P03, P16-P17, P30-P31, P46-P47, P50-P51

### (1) Normal Voltage Operation

**Conditions**  $T_A = -40 \sim +85^\circ\text{C}$ ,  
 $BV_{DD5} = 4.0 \text{ V} \sim 5.5 \text{ V}$ ,  
 $AV_{DD} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  $SMV_{DD5} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  
 $V_{DD5} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  
 $V_{SS5} = BV_{SS5} = SMV_{SS5} = AV_{SS} = 0 \text{ V}$

**Note** Refer to “Power On Clear” on page 57 for further functional restriction.

**Table 6-3 Pin Group 1 - Normal Voltage Operation**

Parameter	Pin mode <sup>a</sup>	Pin Group	Symbol	Test Conditions	Min.	Typ	Max.	Unit
Input voltage high	Schmitt1	1	$V_{IH1}$		$0.7 BV_{DD5}$		$BV_{DD5}$	V
	Schmitt2		$V_{IH2}$		$0.8 BV_{DD5}$		$BV_{DD5}$	V
	CMOS1	1	$V_{IH3}$		$0.7 BV_{DD5}$		$BV_{DD5}$	V
	CMOS2		$V_{IH4}$		$0.8 BV_{DD5}$		$BV_{DD5}$	V
Input voltage low	Schmitt1	1	$V_{IL1}$		0		$0.3 BV_{DD5}$	V
	Schmitt2		$V_{IL2}$		0		$0.5 BV_{DD5}$	V
	CMOS1	1	$V_{IL3}$		0		$0.3 BV_{DD5}$	V
	CMOS2		$V_{IL4}$		0		$0.5 BV_{DD5}$	V
Input hysteresis <sup>b</sup>	Schmitt1	1	$V_{HY1}$		150			mV
	Schmitt2		$V_{HY2}$		150			mV
Output voltage high	Limit1	1	$V_{OH}$	$I_{OH} = -2.0 \text{ mA}$	$BV_{DD5} - 0.45$			V
	Limit2		$V_{OH}$	$I_{OH} = -5.0 \text{ mA}$	$BV_{DD5} - 0.45$			V
Output voltage low	Limit1	1	$V_{OL}$	$I_{OL} = 2.0 \text{ mA}$			0.45	V
	Limit2		$V_{OL}$	$I_{OL} = 5.0 \text{ mA}$			0.45	V
Maximum output short circuit current high	Limit1	1	$I_{OHM1}$	$V_{OH} = 0 \text{ V}$	-2		-12	mA
	Limit2		$I_{OHM2}$		-5		-30	mA
Maximum output short circuit current low	Limit1	1	$I_{OLM1}$	$V_{OL} = BV_{DD5}$	2		12	mA
	Limit2		$I_{OLM2}$		5		30	mA

a) CMOS1, CMOS2, Schmitt1 and Schmitt2 denote the non-schmitt and the two schmitt trigger input characteristics of the device pins. This characteristic can be selected bitwise by software.

Limit1 and Limit2 denote the two output characteristics with current limit functionality of the device pins. The characteristic can be selected bitwise by software.

b) Not tested in production. Specified by design.

**(2) Low Voltage Operation**

**Conditions**  $T_A = -40 \sim +85^\circ\text{C}$ ,  
 $BV_{DD5} = 3.0 \text{ V} \sim 4.0 \text{ V}$ ,  
 $AV_{DD} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  $SMV_{DD5} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  
 $V_{DD5} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  
 $V_{SS5} = BV_{SS5} = SMV_{SS5} = AV_{SS} = 0 \text{ V}$

**Note** Refer to "Power On Clear" on page 57 for further functional restriction.

**Table 6-4 Pin Group 1 - Low Voltage Operation**

Parameter	Pin mode <sup>a</sup>	Pin Group	Symbol	Test Conditions	Min.	Typ	Max.	Unit
Input voltage high	Schmitt1	1	$V_{IH1}$		$0.7 BV_{DD5}$		$BV_{DD5}$	V
	Schmitt2		$V_{IH2}$		$0.8 BV_{DD5}$		$BV_{DD5}$	V
	CMOS1	1	$V_{IH3}$		$0.7 BV_{DD5}$		$BV_{DD5}$	V
	CMOS2		$V_{IH4}$		$0.8 BV_{DD5}$		$BV_{DD5}$	V
Input voltage low	Schmitt1	1	$V_{IL1}$		0		$0.3 BV_{DD5}$	V
	Schmitt2		$V_{IL2}$		0		$0.35 BV_{DD5}$	V
	CMOS1	1	$V_{IL3}$		0		$0.3 BV_{DD5}$	V
	CMOS2		$V_{IL4}$		0		$0.5 BV_{DD5}$	V
Input hysteresis <sup>b</sup>	Schmitt1	1	$V_{HY1}$		100			mV
	Schmitt2		$V_{HY2}$		100			mV
Output voltage high	Limit1	1	$V_{OH}$	$I_{OH} = -1.0 \text{ mA}$	$BV_{DD5} - 0.45$			V
	Limit2	1	$V_{OH}$	$I_{OH} = -2.0 \text{ mA}$	$BV_{DD5} - 0.45$			V
Output voltage low	Limit1	1	$V_{OL}$	$I_{OL} = 1.0 \text{ mA}$			0.45	V
	Limit2	1	$V_{OL}$	$I_{OL} = 2.0 \text{ mA}$			0.45	V
Maximum output short circuit current high	Limit1	1	$I_{OHM1}$	$V_{OH} = 0 \text{ V}$	-1			mA
	Limit2		$I_{OHM2}$		-2			mA
Maximum output short circuit current low	Limit1	1	$I_{OLM1}$	$V_{OL} = BV_{DD5}$	1			mA
	Limit2		$I_{OLM2}$		2			mA

a) CMOS1, CMOS2, Schmitt1 and Schmitt2 denote the non-schmitt and the two schmitt trigger input characteristics of the device pins. This characteristic can be selected bitwise by software.

Limit1 and Limit2 denote the two output characteristics with current limit functionality of the device pins. The characteristic can be selected bitwise by software.

b) Not tested in production. Specified by design.

## 6.4 Pin group 2: $\overline{\text{RESET}}$ and FLMD0

Pin Group 2: Pins supplied by  $V_{DD50}$   
2: ( $\overline{\text{RESET}}$ , FLMD0)

**Conditions**  $T_A = -40 \sim +85^\circ\text{C}$ ,  
 $BV_{DD5} = 3.0 \text{ V} \sim 5.5 \text{ V}$ ,  
 $AV_{DD} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  $SMV_{DD5} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  
 $V_{DD5} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  
 $V_{SS5} = BV_{SS5} = SMV_{SS5} = AV_{SS} = 0 \text{ V}$

**Note** Refer to “Power On Clear” on page 57 for further functional restriction.

**Table 6-5 Pin Group 2 - Normal Voltage Operation**

Parameter	Pin mode	Pin Group	Symbol	Test Conditions	Min.	Typ	Max.	Unit
Input voltage high	Schmitt1	2	$V_{IH1}$		$0.7 V_{DD50}$		$V_{DD50}$	V
Input voltage low	Schmitt1	2	$V_{IL1}$		0		$0.3 V_{DD50}$	V

## 6.5 Pin Group 3: GPIO and LCD Controller

Pin Group 3: GPIO and LCD Controller supplied by  $BV_{DD5}$

3A: P20-P24

3B: P20-P27, P34-P37, P60-P67

3C: P32, P43-P45, P80-P83, P85-P87, P104-P107

3D: P90-P97

**Caution** Do not operate buffers of pin group 3 in current limit state, when the LCD function is used. Failing to do so may lead to a decreased accuracy of the LCD waveforms.

### (1) Normal Voltage Operation

**Conditions**  $T_A = -40 \sim +85^\circ\text{C}$ ,  
 $BV_{DD5} = 4.0 \text{ V} \sim 5.5 \text{ V}$ ,  
 $AV_{DD} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  $SMV_{DD5} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  
 $V_{DD5} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  
 $V_{SS5} = BV_{SS5} = SMV_{SS5} = AV_{SS} = 0 \text{ V}$

**Note** Refer to “Power On Clear” on page 57 for further functional restriction.

**Table 6-6 Pin Group 3 - Normal Voltage Operation**

Parameter	Pin mode <sup>a</sup>	Pin Group	Symbol	Test Conditions	Min.	Typ	Max.	Unit
Input voltage high	Schmitt1	3	$V_{IH1}$		$0.7 BV_{DD5}$		$BV_{DD5}$	V
	Schmitt2		$V_{IH2}$		$0.8 BV_{DD5}$		$BV_{DD5}$	V
	CMOS1	3	$V_{IH3}$		$0.7 BV_{DD5}$		$BV_{DD5}$	V
	CMOS2		$V_{IH4}$		$0.8 BV_{DD5}$		$BV_{DD5}$	V
Input voltage low	Schmitt1	3	$V_{IL1}$		0		$0.3 BV_{DD5}$	V
	Schmitt2		$V_{IL2}$		0		$0.5 BV_{DD5}$	V
	CMOS1	3	$V_{IL3}$		0		$0.3 BV_{DD5}$	V
	CMOS2		$V_{IL4}$		0		$0.5 BV_{DD5}$	V
Input hysteresis <sup>b</sup>	Schmitt1	3	$V_{HY1}$		150			mV
	Schmitt2		$V_{HY2}$		150			mV
Output voltage high	Limit1	3	$V_{OH}$	$I_{OH} = -2.0 \text{ mA}$	$BV_{DD5} - 0.45$			V
	Limit2		$V_{OH}$	$I_{OH} = -5.0 \text{ mA}$	$BV_{DD5} - 0.45$			V
Output voltage low	Limit1	3	$V_{OL}$	$I_{OL} = 2.0 \text{ mA}$			0.45	V
	Limit2		$V_{OL}$	$I_{OL} = 5.0 \text{ mA}$			0.45	V

Table 6-6 Pin Group 3 - Normal Voltage Operation

Parameter	Pin mode <sup>a</sup>	Pin Group	Symbol	Test Conditions	Min.	Typ	Max.	Unit
Maximum output short circuit current high	Limit1	3	$I_{OHM1}$	$V_{OH} = 0\text{ V}$	-2		-12	mA
	Limit2		$I_{OHM2}$		-5		-30	mA
Maximum output short circuit current low	Limit1		$I_{OLM1}$	$V_{OL} = BV_{DD5}$	2		12	mA
	Limit2		$I_{OLM2}$		5		30	mA

- a) CMOS1, CMOS2, Schmitt1 and Schmitt2 denote the non-schmitt and the two schmitt trigger input characteristics of the device pins. This characteristic can be selected bitwise by software.  
Limit1 and Limit2 denote the two output characteristics with current limit functionality of the device pins. The characteristic can be selected bitwise by software.
- b) Not tested in production. Specified by design.

**(2) Low Voltage Operation**

**Conditions**  $T_A = -40 \sim +85^\circ\text{C}$ ,  
 $BV_{DD5} = 3.0 \text{ V} \sim 4.0 \text{ V}$ ,  
 $AV_{DD} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  $SMV_{DD5} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  
 $V_{DD5} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  
 $V_{SS5} = BV_{SS5} = SMV_{SS5} = AV_{SS} = 0 \text{ V}$

**Note** Refer to “Power On Clear” on page 57 for further functional restriction.

**Table 6-7 Pin Group 3 - Low Voltage Operation**

Parameter	Pin mode <sup>a</sup>	Pin Group	Symbol	Test Conditions	Min.	Typ	Max.	Unit
Input voltage high	Schmitt1	3	$V_{IH1}$		$0.7 BV_{DD5}$		$BV_{DD5}$	V
	Schmitt2		$V_{IH2}$		$0.8 BV_{DD5}$		$BV_{DD5}$	V
	CMOS1	3	$V_{IH3}$		$0.7 BV_{DD5}$		$BV_{DD5}$	V
	CMOS2		$V_{IH4}$		$0.8 BV_{DD5}$		$BV_{DD5}$	V
Input voltage low	Schmitt1	3	$V_{IL1}$		0		$0.3 BV_{DD5}$	V
	Schmitt2		$V_{IL2}$		0		$0.35 BV_{DD5}$	V
	CMOS1	3	$V_{IL3}$		0		$0.3 BV_{DD5}$	V
	CMOS2		$V_{IL4}$		0		$0.5 BV_{DD5}$	V
Input hysteresis <sup>b</sup>	Schmitt1	3	$V_{HY1}$		100			mV
	Schmitt2		$V_{HY2}$		100			mV
Output voltage high	Limit1	3	$V_{OH}$	$I_{OH} = -1.0 \text{ mA}$	$BV_{DD5} - 0.45$			V
	Limit2		$V_{OH}$	$I_{OH} = -2.0 \text{ mA}$	$BV_{DD5} - 0.45$			V
Output voltage low	Limit1	3	$V_{OL}$	$I_{OL} = 1.0 \text{ mA}$			0.45	V
	Limit2		$V_{OL}$	$I_{OL} = 2.0 \text{ mA}$			0.45	V
Maximum output short circuit current high	Limit1	3	$I_{OHM1}$	$V_{OH} = 0 \text{ V}$	-1		-12	mA
	Limit2		$I_{OHM2}$		-2		-30	mA
Maximum output short circuit current low	Limit1	3	$I_{OLM1}$	$V_{OL} = BV_{DD5}$	1		12	mA
	Limit2		$I_{OLM2}$		2		30	mA

a) CMOS1, CMOS2, Schmitt1 and Schmitt2 denote the non-schmitt and the two schmitt trigger input characteristics of the device pins. This characteristic can be selected bitwise by software.

Limit1 and Limit2 denote the two output characteristics with current limit functionality of the device pins. The characteristic can be selected bitwise by software.

b) Not tested in production. Specified by design



## 6.6 ADC Input

This chapter describes the digital functions available at the pins supplied by AVDD.

Pin Group 5: Pins supplied by AV<sub>DD5</sub>  
P70 .. P77

### (1) Normal Voltage Operating

**Conditions**  $T_A = -40 \sim +85^\circ\text{C}$ ,  
 $BV_{DD5} = 3.0 \text{ V} \sim 5.5 \text{ V}$ ,  
 $AV_{DD} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  $SMV_{DD5} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  
 $V_{DD5} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  
 $V_{SS5} = BV_{SS5} = SMV_{SS5} = AV_{SS} = 0 \text{ V}$

**Note** Refer to “Power On Clear” on page 57 for further functional restriction.

**Table 6-8 Pin Group 5 - Normal Voltage Operation**

Parameter	Pin mode <sup>a</sup>	Symbol	Test Conditions	Min	Typ	Max	Unit
Input Voltage High	Schmitt1	$V_{IH1}$		$0.7 AV_{DD5}$		$AV_{DD5}$	V
	Schmitt2	$V_{IH2}$		$0.8 AV_{DD5}$		$AV_{DD5}$	V
Input Voltage Low	Schmitt1	$V_{IL1}$		0		$0.3 AV_{DD5}$	V
	Schmitt2	$V_{IL2}$		0		$0.5 AV_{DD5}$	V
Input Voltage Hysteresis <sup>b</sup>	Schmitt1	$V_{HI1}$		150			mV
	Schmitt2	$V_{HI2}$		150			mV

a) Schmitt1 denotes the schmitt trigger input characteristics of the device pins.

b) Not tested in production. Specified by design.

**(2) Low Voltage Operation**

**Conditions**  $T_A = -40 \sim +85^\circ\text{C}$ ,  
 $BV_{DD5} = 3.0 \text{ V} \sim 5.5 \text{ V}$ ,  
 $AV_{DD} = 3.2 \text{ V} \sim 4.0 \text{ V}$ ,  $SMV_{DD5} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  
 $V_{DD5} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  
 $V_{SS5} = BV_{SS5} = SMV_{SS5} = AV_{SS} = 0 \text{ V}$

**Note** Refer to “Power On Clear” on page 57 for further functional restriction.

**Table 6-9 Pin Group 5 - Low Voltage Operation**

Parameter	Pin mode <sup>a</sup>	Symbol	Test Conditions	Min	Typ	Max	Unit
Input Voltage High	Schmitt1	$V_{IH1}$		$0.7 AV_{DD5}$		$AV_{DD5}$	V
	Schmitt2	$V_{IH2}$		$0.8 AV_{DD5}$		$AV_{DD5}$	V
Input Voltage Low	Schmitt1	$V_{IL1}$		0		$0.3 AV_{DD5}$	V
	Schmitt2	$V_{IL2}$				$0.35 AV_{DD5}$	V
Input Voltage Hysteresis <sup>b</sup>	Schmitt1	$V_{HI1}$	150			mV	
	Schmitt2	$V_{HI2}$	150			mV	

<sup>a)</sup> Schmitt1 denotes the schmitt trigger input characteristics of the device pins.

<sup>b)</sup> Not tested in production. Specified by design.

## 6.7 LCD Common and Segment Lines

**Conditions**  $T_A = -40 \sim +85^\circ\text{C}$ ,  
 $BV_{DD5} = 4.5 \text{ V} \sim 5.5 \text{ V}$ ,  
 $AV_{DD} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  $SMV_{DD5} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  
 $V_{DD5} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  
 $V_{SS5} = BV_{SS5} = SMV_{SS5} = AV_{SS} = 0 \text{ V}$

**Note** Refer to “Power On Clear” on page 57 for further functional restriction.

**Table 6-10 DC Characteristics LCD Common and Segment Lines**

Parameter	Symbol	TestConditions	Min.	Typ	Max	Unit
LCD Segment Output Voltage (unloaded)	$V_{ODS}$	$IO = \pm 1 \mu\text{A}$	$V_{LCDn} - 0.2$	$V_{LCDn}^a$	$V_{LCDn} + 0.2$	V
LCD Common Output Voltage (unloaded)	$V_{ODC}$	$IO = \pm 1 \mu\text{A}$	$V_{LCDn} - 0.2$	$V_{LCDn}$	$V_{LCDn} + 0.2$	V
LCD split voltage <sup>b</sup>	$V_{LC0}$	$IO = \pm 1.5 \text{ mA}$	$V_{LCD0} - 0.1$	$V_{LCD0}$	$V_{LCD0} + 0.1$	V
	$V_{LC1}$	$IO = \pm 1.0 \text{ mA}$	$V_{LCD1} - 0.1$	$V_{LCD1}$	$V_{LCD1} + 0.1$	V
	$V_{LC2}$	$IO = \pm 1.0 \text{ mA}$	$V_{LCD2} - 0.1$	$V_{LCD2}$	$V_{LCD2} + 0.1$	V
	$V_{LC3}$	$IO = \pm 1.5 \text{ mA}$	$V_{LCD3} - 0.1$	$V_{LCD3}$	$V_{LCD3} + 0.1$	V
LCD Series resistance <sup>c</sup>	$R_{LCDS}$	Segment lines, $V_{LCDn}$ to pin			1.8	k $\Omega$
	$R_{LCDC}$	Common lines, $V_{LCDn}$ to pin			1.8	k $\Omega$
LCD operation current	$IDD_{LCD}$	$f_{frame}=244\text{Hz}$ , All segment and common lines set to LCD mode and open			200	$\mu\text{A}$

a)  $V_{LCDn}$  ( $n=0..3$ ) represents one of the four possible voltage levels at the LCD pins. See table below for reference.

b) The split voltage is an internal design value. Direct measurement is not possible.

c) The Series resistance is an internal design value. Direct measurement is not possible.

**Note** The power supply configuration is restricted, when the LCD is used. The LCD voltages are generated centrally.

VLCDn	Voltage
VLCD0	$BV_{DD5}$
VLCD1	$2/3 \times BV_{DD5}$
VLCD2	$1/3 \times BV_{DD5}$
VLCD3	$0 \times BV_{DD5} = BV_{SS5}$

## 6.8 Stepper Motor Driver IO

Pin Group 4: Stepper Motor outputs supplied by  $SMV_{DD5}$

4A: P120-P127

4B: P130-P137

### (1) Normal Voltage Operation

#### (a) Input Characteristics

**Conditions**  $T_A = -40 \sim +85^\circ\text{C}$ ,  
 $BV_{DD5} = 3.0 \text{ V} \sim 5.5 \text{ V}$ ,  
 $AV_{DD} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  $SMV_{DD5} = 4.0 \text{ V} \sim 5.5 \text{ V}$ ,  
 $V_{DD5} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  
 $V_{SS5} = BV_{SS5} = SMV_{SS5} = AV_{SS} = 0 \text{ V}$

**Note** Refer to “Power On Clear” on page 57 for further functional restriction.

**Table 6-11 DC Characteristics Stepper Motor Driver Input - Normal Voltage Operation**

Parameter	Pin mode <sup>a</sup>	Symbol	Test Conditions	Min	Typ	Max	Unit
Input Voltage High	Schmitt1	$V_{IH1}$		$0.7 SMV_{DD5}$		$SMV_{DD5}$	V
	Schmitt2	$V_{IH2}$		$0.8 SMV_{DD5}$		$SMV_{DD5}$	
	CMOS1	$V_{IH3}$		$0.7 SMV_{DD5}$		$SMV_{DD5}$	V
	CMOS2	$V_{IH4}$		$0.8 SMV_{DD5}$		$SMV_{DD5}$	V
Input Voltage Low	Schmitt1	$V_{IL1}$		0		$0.3 SMV_{DD5}$	V
	Schmitt2	$V_{IL2}$		0		$0.5 SMV_{DD5}$	
	CMOS1	$V_{IL3}$		0		$0.3 SMV_{DD5}$	V
	CMOS2	$V_{IL4}$				$0.5 SMV_{DD5}$	
Input Voltage Hysteresis <sup>b</sup>	Schmitt1	$V_{HI1}$	150			mV	
	Schmitt2	$V_{HI2}$	150			mV	

a) CMOS1 and Schmitt1 denote the non-schmitt trigger and the two schmitt trigger input characteristics of the device pins. This characteristic can be selected bitwise by software.

b) Not tested in production. Specified by design.

**(b) Output Characteristics**

**Conditions**  $T_A = -40 \sim +85^\circ\text{C}$ ,  
 $BV_{DD5} = 3.0 \text{ V} \sim 5.5 \text{ V}$ ,  
 $AV_{DD} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  $SMV_{DD5} = 4.75 \text{ V} \sim 5.25 \text{ V}$ ,  
 $V_{DD5} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  
 $V_{SS5} = BV_{SS5} = SMV_{SS5} = AV_{SS} = 0 \text{ V}$

**Note** Refer to "Power On Clear" on page 57 for further functional restriction.

**Table 6-12 DC Characteristics Stepper Motor Driver Output - Normal Voltage Operation**

Parameter	Pin mode	Symbol	Test Conditions	Min	Typ	Max	Unit
Output Voltage High		$V_{OH}$	$I_{OH} = -40 \text{ mA}$ , $T_A = -40^\circ\text{C}$	$SMV_{DD5} - 0.5$		$SMV_{DD5}$	V
		$V_{OH}$	$I_{OH} = -30 \text{ mA}$ , $T_A = +25^\circ\text{C}$	$SMV_{DD5} - 0.5$		$SMV_{DD5}$	V
		$V_{OH}$	$I_{OH} = -27 \text{ mA}$ , $T_A = +85^\circ\text{C}$	$SMV_{DD5} - 0.5$		$SMV_{DD5}$	V
Output Voltage Low		$V_{OL}$	$I_{OL} = 40 \text{ mA}$ , $T_A = -40^\circ\text{C}$	0		0.5	V
		$V_{OL}$	$I_{OL} = 30 \text{ mA}$ , $T_A = +25^\circ\text{C}$	0		0.5	V
		$V_{OL}$	$I_{OL} = 27 \text{ mA}$ , $T_A = +85^\circ\text{C}$	0		0.5	V
Output voltage deviation <sup>a</sup>		$V_{DEV}$		0		50	mV
Output Slew rate <sup>b</sup>		$t_{RF}$	10% - 90%	12	25	70	ns
Peak Cross Current <sup>c</sup>		$I_{CROSS}$				50	mA
Output Pulse width <sup>d</sup>		$t_{MO}$		125			ns
Output Pulse length deviation <sup>e</sup>		$t_{SMDEV}$		-10	+5	+45	ns

- a) Output voltage deviation defines the difference of the outputs levels of the same stepper motor.  
 $V_{DEV} = \max(|V_{OHx} - V_{OHy}|, |V_{OLx} - V_{OLy}|) @ I_{OHx} = I_{OHy}, I_{OLx} = I_{OLy}$ .  
x and y denote any combination of two pins of the following pin groups: (P120-123, P124-P127, P130-P133, P134-P137)
- b) The slew rate is not tested, but derived from simulation.
- c) The slew rate control generates a cross current in the output stage to control the energy of the external inductive load. The cross current flows only during the output transition time  $t_{RF}$ . It flows in addition to the output current. The cross current is not tested, but derived from simulation.
- d) The output buffer can not generate high or low pulses shorter than this time, because of its slew rate control system. This value is not tested, but derived from simulation.
- e) The slew rate control function causes a deviation of output pulse time compared to the ideal selected output pulse setting. This value is not tested, but derived from simulation.

**Caution** The stepper output drivers have no current limitation and are not protected against short circuit.

**(2) Low Voltage Operation****(a) Input Characteristics**

**Conditions**  $T_A = -40 \sim +85^\circ\text{C}$ ,  
 $BV_{DD5} = 3.0 \text{ V} \sim 5.5 \text{ V}$ ,  
 $AV_{DD} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  $SMV_{DD5} = 3.2 \text{ V} \sim 4.0 \text{ V}$ ,  
 $V_{DD5} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  
 $V_{SS5} = BV_{SS5} = SMV_{SS5} = AV_{SS} = 0 \text{ V}$

**Note** Refer to “Power On Clear” on page 57 for further functional restriction.

**Table 6-13 DC Characteristics Stepper Motor Driver Input - Low Voltage Operation**

Parameter	Pin mode <sup>a</sup>	Symbol	Test Conditions	Min	Typ	Max	Unit
Input Voltage High	Schmitt1	$V_{IH1}$		0.7 $SMV_{DD5}$		$SMV_{DD5}$	V
	Schmitt2	$V_{IH2}$		0.8 $SMV_{DD5}$		$SMV_{DD5}$	V
	CMOS1	$V_{IH3}$		0.7 $SMV_{DD5}$		$SMV_{DD5}$	V
	CMOS2	$V_{IH4}$		0.8 $SMV_{DD5}$		$SMV_{DD5}$	V
Input Voltage Low	Schmitt1	$V_{IL1}$		0		0.3 $SMV_{DD5}$	V
	Schmitt2	$V_{IL2}$				0.35 $SMV_{DD5}$	V
	CMOS1	$V_{IL3}$		0		0.3 $SMV_{DD5}$	V
	CMOS2	$V_{IL4}$				0.5 $SMV_{DD5}$	V
Input Voltage Hysteresis <sup>b</sup>	Schmitt1	$V_{HI1}$		100			mV
	Schmitt2	$V_{HI2}$		100			mV

a) CMOS1 and Schmitt1 denote the non-schmitt trigger and the two schmitt trigger input characteristics of the device pins. This characteristic can be selected bitwise by software.

b) Not tested in production. Specified by design.

**(b) Output Characteristics**

**Conditions**  $T_A = -40 \sim +85^\circ\text{C}$ ,  
 $BV_{DD5} = 3.0 \text{ V} \sim 5.5 \text{ V}$ ,  
 $AV_{DD} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  $SMV_{DD5} = 3.2 \text{ V} \sim 4.75 \text{ V}$ ,  
 $V_{DD5} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  
 $V_{SS5} = BV_{SS5} = SMV_{SS5} = AV_{SS} = 0 \text{ V}$

**Note** Refer to “Power On Clear” on page 57 for further functional restriction.

**Table 6-14 DC Characteristics Stepper Motor Driver Output - Low Voltage Operation**

Parameter	Pin mode	Symbol	Test Conditions	Min	Typ	Max	Unit
Output Voltage High		$V_{OH}$	$I_{OH} = -5 \text{ mA}$ ,	$SMV_{DD5} - 0.5$		$SMV_{DD5}$	V
Output Voltage Low		$V_{OL}$	$I_{OL} = +5 \text{ mA}$ ,	0		0.5	V

## 6.9 Current Limit Function of I/O buffers

The output buffers of the pin groups 1 incorporate a current limiting function. This function limits the output current of the buffer to a certain value during output signal switching.

The limit is disabled when the buffer output voltage is near to its target voltage, thus providing full drivability. During full drivability the current may reach values given in absolute maximum ratings for a single pin.

The user can select different limit ranges by software (see Functional Target Specification for details).

The limit function is independent from the operation mode of the device.

A permanent short circuit of outputs is not permitted.

The stepper motor driver outputs do not support a current limiting function.

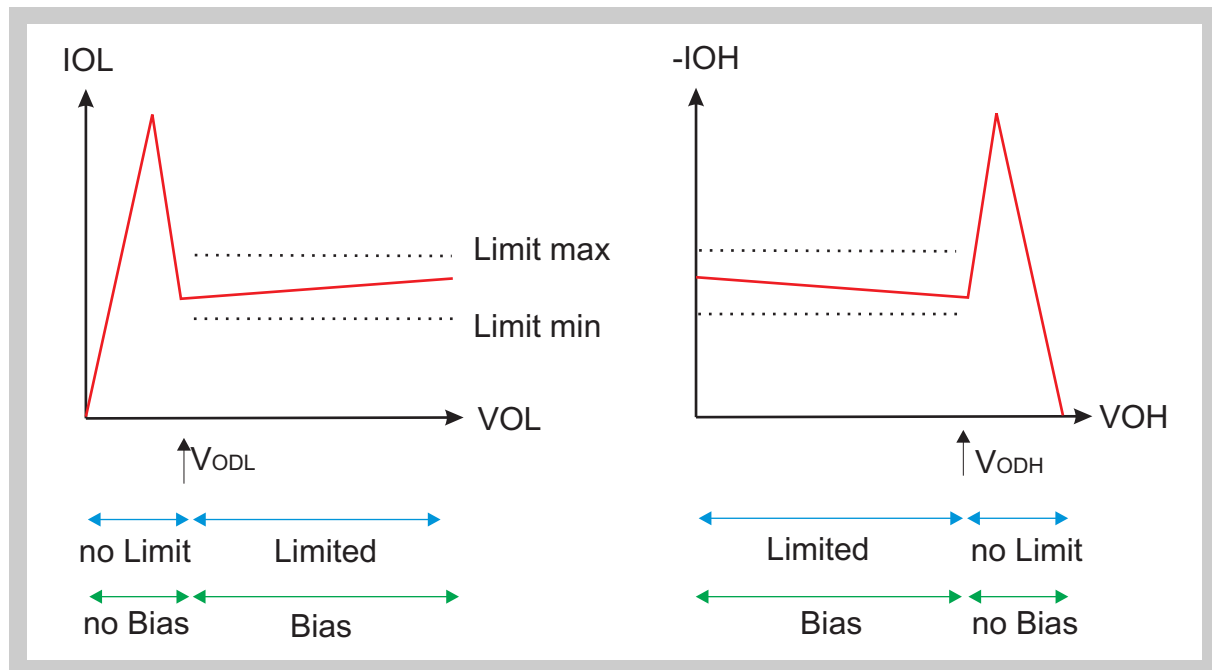


Figure 6-1 Current Limit Function Principle

**Note** The current limit function of the I/O buffers needs additional bias current to control the output stage. The additional bias current depend on the status of each buffer. Each buffer with either high or low output and in the stage of current limiting will draw this bias current.

**Conditions**  $T_A = -40 \sim +85^\circ\text{C}$ ,  
 $BV_{DD5} = 3.0 \text{ V} \sim 5.5 \text{ V}$ ,  
 $AV_{DD} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  $SMV_{DD5} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  
 $V_{DD5} = 3.2 \text{ V} \sim 5.5 \text{ V}$ , (  
 $V_{SS5} = BV_{SS5} = SMV_{SS5} = AV_{SS} = 0 \text{ V}$

**Note** Refer to “Power On Clear” on page 57 for further functional restriction.

**Table 6-15 DC Characteristics of Current Limiting Function <sup>a</sup>**

Parameter	Pin mode	Symbol	Test Conditions	Min	Typ	Max	Unit
Limit disable threshold voltage for $V_{OH}$		$V_{ODH}$		$V_{DDx}^b - 1.6$		$V_{DDx} - 1.1$	V
Limit disable threshold voltage for $V_{OL}$		$V_{ODL}$		1.1		1.6	V
Supply Current per buffer for current limitation <sup>c</sup>	Limit1	$I_{DDCL1}$				0.8	mA
	Limit2	$I_{DDCL2}$				1.7	mA

a) These values are not tested. They are given based on design simulation

b)  $V_{DDx}$  denotes the corresponding voltage supply of the pin.

c) This current need not be considered during absolute maximum current calculation.

**Note** The function of the current limiting operation is sensitive against inductive loads under a certain condition:

- The load of the pin is below the selected current limit and the device could reach a sufficient output voltage. The device changed to full drivability.
- The external circuitry sinks/sources more and more current.
- The current creates an increasing voltage drop in the output stage of the device.
- The increasing voltage drop enables the current limiting function.
- The enabling of the current limit together with an external inductance may lead to an oscillation of the output between the limited and unlimited state. The external inductance creates voltage peaks that change the state of the output buffers current limiting function.
- Recommendation: keep external inductance small (keep external wiring short).



## 6.10 Supply Current

Table 6-16 DC Characteristics Supply Current  $\mu$ PD70F3417(A),  $\mu$ PD70F3416(A)<sup>a</sup>

Parameter	Symbol	Test Conditions	Min	Typ	Max	Unit
Supply current	$I_{DD13}$	Operating ( $f_{CPU} = 24$ MHz; SSCG,PLL: on)		40	55	mA
	$I_{DD13}$	Operating ( $f_{CPU} = 16$ MHz; SSCG,PLL: on)		29	40	mA
	$I_{DD13}$	Operating ( $f_{CPU} = 8$ MHz; SSCG,PLL: on)		18	25	mA
	$I_{DD14}$	Operating ( $f_{CPU} = 4$ MHz; SSCG,PLL: off)		11	15	mA
	$I_{DD15}$	Operating ( $f_{CPU} = 32$ kHz; SSCG,PLL: off)		0.5	0.8	mA
	$I_{DD16}$	Operating ( $f_{CPU} = \text{RingOSC} = 300$ kHz; SSCG,PLL: off)		3.5	5.0	mA
	$I_{DD21}$	HALT Mode ( $f_{PLL} = 16$ MHz; SSCG,PLL: on)		16	24	mA
	$I_{DD31}$	IDLE Mode ( $f_{PLL} = 16$ MHz; SSCG,PLL: on)		3.2	4.8	mA
	$I_{DD5}$	STOP		10	190	$\mu$ A
	$I_{DD6}$	WATCH		150	350	$\mu$ A
	$I_{DD6A}$	WATCH Monitored		165	390	$\mu$ A
	$I_{DD7}$	SUB WATCH		50	200	$\mu$ A
	$I_{DD7A}$	SUB WATCH Monitored		65	215	$\mu$ A
	$I_{DD7B}$	SUB WATCH on RingOSC		65	215	$\mu$ A

<sup>a)</sup> These values are target values without current consumption due to external circuitry at the IO-pins.

The low current modes (STOP, WATCH, SUB WATCH) are tested under the following conditions:

- Operation modes setting as described in table below.
- All functional pins with output possibility are set to output with alternating high and low output levels.
- Testequipment is disconnected from output pins.
- $I_{DD}$  is the total sum of currents to the device supply pins  $V_{DD5}$ ,  $BV_{DD5}$ ,  $SMV_{DD5}$ ,  $AV_{DD}$
- Device drives its own leakage currents by its output stages.
- The leakage current is included in the given  $I_{DD}$  values.

Unit	Watch	Watch monitored	Sub Watch	Sub Watch on RingOSC	Sub Watch monitored	STOP
Main-oscillator	running	running	stopped	stopped	stopped	stopped
Sub-oscillator	stopped (XT1 clamped)	stopped (XT1 clamped)	running	stopped (XT1 clamped)	running	stopped
Ring-oscillator	stopped	running	stopped	running	running	stopped
SSCG	stopped	stopped	stopped	stopped	stopped	stopped
PLL	stopped	stopped	stopped	stopped	stopped	stopped
CPU system	stopped	stopped	stopped	stopped	stopped	stopped
IICCLK	stopped	stopped	stopped	stopped	stopped	stopped
PCLK0, PCLK1	stopped	stopped	stopped	stopped	stopped	stopped
PCLK2...PCLK15	stopped	stopped	stopped	stopped	stopped	stopped
SPCLK0, SPCLK1	stopped	stopped	stopped	stopped	stopped	stopped
SPCLK2...SPCLK15	stopped	stopped	stopped	stopped	stopped	stopped
FOUT	stopped	stopped	stopped	stopped	stopped	stopped
WTCLK	running	running	running	running	running	stopped
WDTCLK	stopped	stopped	stopped	stopped	stopped	stopped
TM0CLK	stopped	stopped	stopped	stopped	stopped	stopped
LCD	disabled	disabled	disabled	disabled	disabled	disabled
ADC	disabled	disabled	disabled	disabled	disabled	disabled
Regulator <sup>a</sup>	Standby	Standby	Standby	Standby	Standby	Standby

a) Regulator in standby: STBCTL = 0x03

# Chapter 7 AC Characteristics

## 7.1 AC Test Input/Output Waveform

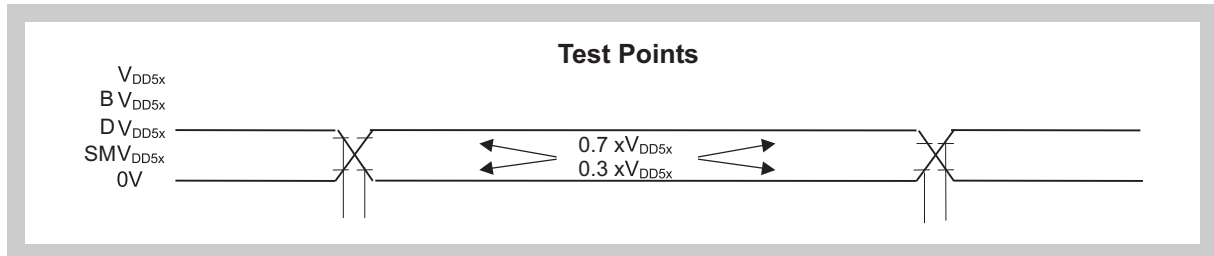


Figure 7-1 AC Test Input/Output Waveform

## 7.2 AC Test Load Condition

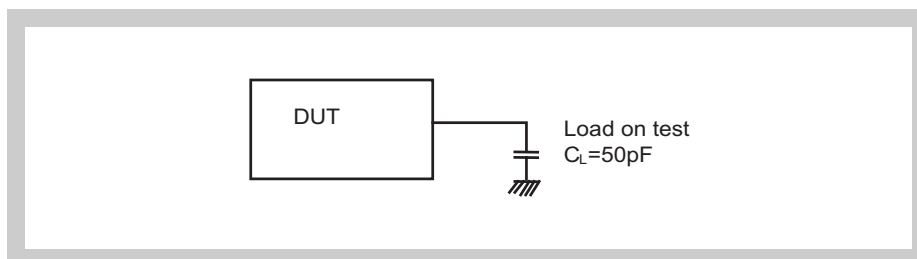


Figure 7-2 AC Test Load Condition

## 7.3 Reset

**Conditions**  $T_A = -40 \sim +85^\circ\text{C}$ ,  
 $BV_{DD5} = 3.0 \text{ V} \sim 5.5 \text{ V}$ ,  
 $AV_{DD} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  $SMV_{DD5} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  
 $V_{DD5} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  
 $V_{SS5} = BV_{SS5} = SMV_{SS5} = AV_{SS} = 0 \text{ V}$

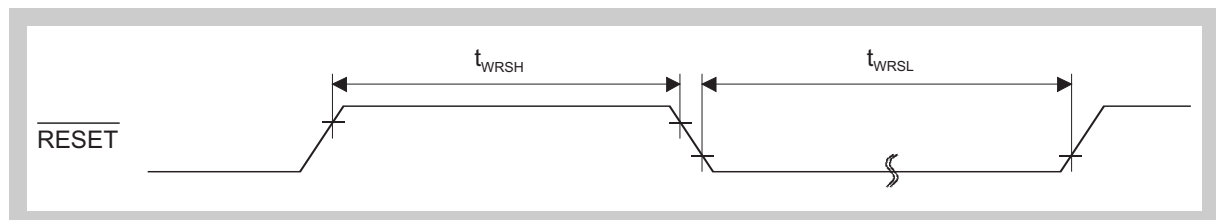
**Note** Refer to “Power On Clear” on page 57 for further functional restriction.

**Table 7-1 Reset AC Characteristics**

Parameter	Symbol	Test Conditions	MIN.		MAX.	Unit
RESET high-level width <sup>a</sup>	$t_{WRSH}$		500			ns
RESET low-level width <sup>b</sup>	$t_{WRSL}$		500			ns
RESET Pulse rejection <sup>c</sup>	$t_{WRRJ}$		50			ns

- a) This signal high time is needed to ensure that the internal RESET release operation starts.  
 b) This signal low time is needed to ensure that the internal RESET is activated.  
 c) The RESET input incorporates an analog filter. Pulses shorter than this minimum will be ignored. Not tested in production.

**Note** Reset pulses shorter than the given value may not be recognized by the device, they do not cause undefined states of the device.



**Figure 7-3 Reset Timing**

## 7.4 Interrupt Timing

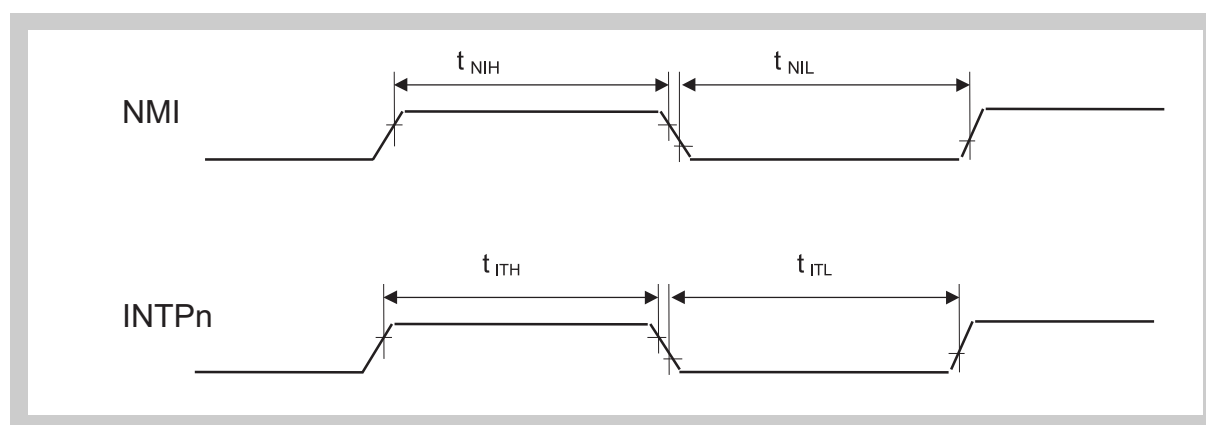
**Conditions**  $T_A = -40 \sim +85^\circ\text{C}$ ,  
 $BV_{DD5} = 3.0 \text{ V} \sim 5.5 \text{ V}$ ,  
 $AV_{DD} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  $SMV_{DD5} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  
 $V_{DD5} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  
 $V_{SS5} = BV_{SS5} = SMV_{SS5} = AV_{SS} = 0 \text{ V}$

**Note** Refer to “Power On Clear” on page 57 for further functional restriction.

**Table 7-2 Interrupt AC Characteristics**

Parameter	Symbol	Test Conditions	Min	Typ	Max	Unit
NMI high-level width <sup>a</sup>	$t_{NIH}$		360			ns
NMI low-level width <sup>a</sup>	$t_{NIL}$		360			ns
NMI pulse rejection <sup>b</sup>	$t_{NIRJ}$		50		360	ns
INTPn <sup>c</sup> high-level width <sup>a</sup>	$t_{ITH}$		360			ns
INTPn <sup>c</sup> low-level width <sup>a</sup>	$t_{ITL}$		360			ns
INTPn <sup>c</sup> pulse rejection <sup>b</sup>	$t_{ITRJ}$		50		360	ns

- a) Pulses longer than this value will pass the input filter.  
 b) Pulses shorter than this value do not pass the input filters. Not tested in production.  
 c)  $n = 7 \dots 0$



**Figure 7-4 Interrupt Timing**

**Note** Interrupt timing is generated by analog delay elements. Delay characteristics have a wide range in production.

## 7.5 Peripheral Function Characteristics

The following conditions are valid for all peripheral function characteristics unless otherwise noted.

**Conditions**  $T_A = -40 \sim +85^\circ\text{C}$ ,  
 $BV_{DD5} = 3.0 \text{ V} \sim 5.5 \text{ V}$ ,  
 $AV_{DD} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  $SMV_{DD5} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  
 $V_{DD5} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  
 $V_{SS5} = BV_{SS5} = SMV_{SS5} = AV_{SS} = 0 \text{ V}$

**Note** Refer to “Power On Clear” on page 57 for further functional restriction.

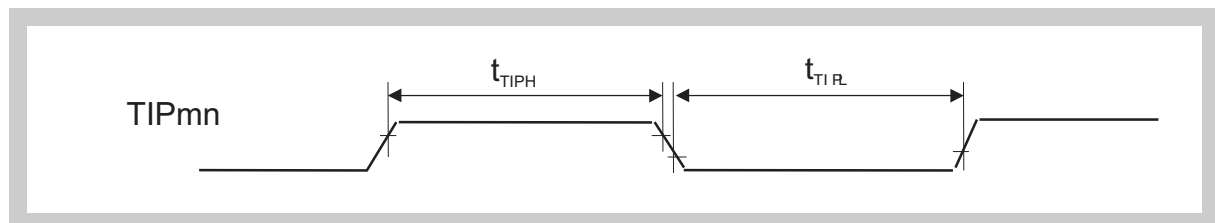
### 7.5.1 Timer P

**Table 7-3 Timer P AC Characteristics**

Parameter	Symbol	Test Conditions	Min	Typ	Max	Unit
TIPmn <sup>a</sup> high-level width	$t_{TIPHD}$	Digital filter	$45 + 3/f_{PCLK0}$ <sup>b</sup>			ns
	$t_{TIPHNB}$	No digital filter, react on both edge	$45 + 2/f_{PCLK0}$			ns
	$t_{TIPHNS}$	No digital filter, react on single edge	$45 + 1/f_{PCLK0}$			ns
TIPmn <sup>a</sup> low-level width	$t_{TIPL}$	Digital filter	$45 + 3/f_{PCLK0}$			ns
	$t_{TIPLNB}$	No digital filter, react on both edge	$45 + 2/f_{PCLK0}$			ns
	$t_{TIPLNS}$	No digital filter, react on single edge	$45 + 1/f_{PCLK0}$			ns

a)  $m = 0, n = 1 \dots 0$

b)  $f_{PCLK0}$  is the clock frequency of the digital filter connected to the input pin.



**Figure 7-5 Timer P Input Timing**

## 7.5.2 Timer G

**Table 7-4 Timer G Input Characteristics**

Parameter	Symbol	Test Conditions	Min	Typ	Max	Unit
TIGmn <sup>a</sup> high-level width	t <sub>TIGH1</sub>	Digital filter, f <sub>PCLK0</sub> <sup>b</sup> = f <sub>CCLK</sub> <sup>c</sup>	45 + 3/f <sub>PCLK0</sub>			ns
	t <sub>TIGH2</sub>	Digital filter, f <sub>PCLK0</sub> > f <sub>CCLK</sub>	45 + 2/f <sub>CCLK</sub>			ns
	t <sub>TIGH0</sub>	No digital filter	45 + 2/f <sub>CCLK</sub>			ns
TIGmn <sup>a</sup> low-level width	t <sub>TIGL1</sub>	Digital filter, f <sub>PCLK0</sub> = f <sub>CCLK</sub>	45 + 3/f <sub>PCLK0</sub>			ns
	t <sub>TIGL2</sub>	Digital filter, f <sub>PCLK0</sub> > f <sub>CCLK</sub>	45 + 2/f <sub>CCLK</sub>			ns
	t <sub>TIGL0</sub>	No digital filter	45 + 2/f <sub>CCLK</sub>			ns

a) m = 0...1: n = 1...4; m = 2: n = 0...5

b) f<sub>SPCLK0</sub> is the clock frequency of the digital filter connected to the input pin.

c) f<sub>CCLK</sub> is the count clock frequency of the Timer G.

## 7.5.3 UARTA

**Table 7-5 UARTA AC Characteristics**

Parameter	Symbol	Test Conditions	Min.	Max	Unit
Transfer rate	T <sub>UARTA</sub>		0.3	1000	Kbps

## 7.5.4 CAN

**Table 7-6 CAN AC Characteristics**

Parameter	Symbol	Test Conditions	MIN.	MAX.	Unit
Transfer rate	T <sub>F<sub>CAN</sub></sub>	f <sub>CAN</sub> <sup>a</sup> ≥ 8 MHz		1	Mbps

a) f<sub>CAN</sub> is the CAN macro clock frequency. For CAN clock selection refer to functional specification of the CAN.

## 7.5.5 CSI B (High Voltage Operation)

**Conditions** As specified at start of chapter 7.5 on page 46.

### (1) CSIB Master Mode

#### (a) With Digital Filter

**Table 7-7 CSIB Master Mode AC Characteristics with Digital Filter**

Parameter	Symbol	Test Conditions	MIN.	MAX.	Unit
$\overline{\text{SCKBn}}$ cycle time	$t_{\text{KCY1}}$		$8/f_{\text{PCLK0}}$		ns
$\overline{\text{SCKBn}}$ high level width	$t_{\text{KH1}}$		$0.5 t_{\text{KCY1}} - 15$		ns
$\overline{\text{SCKBn}}$ low level width	$t_{\text{KL1}}$		$0.5 t_{\text{KCY1}} - 15$		ns
SIBn setup time (to $\overline{\text{SCKBn}}$ )	$t_{\text{SIK1}}$		$50 + 4/f_{\text{PCLK0}}^{\text{a}}$		ns
SIBn hold time (from $\overline{\text{SCKBn}}$ )	$t_{\text{KSI1}}$		$-31 - 4/f_{\text{PCLK0}}$		ns
Delay time from $\overline{\text{SCKBn}}$ to SOBn	$t_{\text{KSO1}}$			6	ns

a)  $f_{\text{PCLK0}}$  is the clock frequency of the digital filter connected to the input pin.

#### (b) Without Digital Filter

**Table 7-8 CSIB Master Mode AC Characteristics without Digital Filter**

Parameter	Symbol	Test Conditions	MIN.	MAX.	Unit
$\overline{\text{SCKBn}}$ cycle time	$t_{\text{KCY1}}$		125		ns
$\overline{\text{SCKBn}}$ high level width	$t_{\text{KH1}}$		$0.5 t_{\text{KCY1}} - 15$		ns
$\overline{\text{SCKBn}}$ low level width	$t_{\text{KL1}}$		$0.5 t_{\text{KCY1}} - 15$		ns
SIBn setup time (to $\overline{\text{SCKBn}}$ )	$t_{\text{SIK1}}$		50		ns
SIBn hold time (from $\overline{\text{SCKBn}}$ )	$t_{\text{KSI1}}$		-31		ns
Delay time from $\overline{\text{SCKBn}}$ to SOBn	$t_{\text{KSO1}}$			6	ns

**Note** n = 0...1



**(2) CSIB Slave Mode****(a) With Digital Filter****Table 7-9 CSIB Slave Mode AC Characteristics with Digital Filter**

Parameter	Symbol	Test Conditions	Min	Max	Unit
$\overline{\text{SCKBn}}$ cycle time	$t_{\text{KCY1}}$		$8/f_{\text{PCLK0}}$		ns
$\overline{\text{SCKBn}}$ high level width	$t_{\text{KH1}}$		$4/f_{\text{PCLK0}} - 5$		ns
$\overline{\text{SCKBn}}$ low level width	$t_{\text{KL1}}$		$4/f_{\text{PCLK0}} - 5$		ns
SIBn setup time (to $\overline{\text{SCKBn}}$ )	$t_{\text{SIK1}}$		$15 + 2/f_{\text{PCLK0}}^{\text{a}}$		ns
SIBn hold time (from $\overline{\text{SCKBn}}$ )	$t_{\text{KSI1}}$		$5 + 2/f_{\text{PCLK0}}$		ns
Delay time from $\overline{\text{SCKBn}}$ to SOBn	$t_{\text{KSO1}}$			$45 + 3/f_{\text{PCLK0}}$	ns

a)  $f_{\text{PCLK0}}$  is the clock frequency of the digital filter connected to the input pin.

**(b) Without Digital Filter****Table 7-10 CSIB Slave Mode AC Characteristics without Digital Filter**

Parameter	Symbol	Test Conditions	Min	Max	Unit
$\overline{\text{SCKBn}}$ cycle time	$t_{\text{KCY1}}$		125		ns
$\overline{\text{SCKBn}}$ high level width	$t_{\text{KH1}}$		50		ns
$\overline{\text{SCKBn}}$ low level width	$t_{\text{KL1}}$		50		ns
SIBn setup time (to $\overline{\text{SCKBn}}$ )	$t_{\text{SIK1}}$		15		ns
SIBn hold time (from $\overline{\text{SCKBn}}$ )	$t_{\text{KSI1}}$		5		ns
Delay time from $\overline{\text{SCKBn}}$ to SOBn	$t_{\text{KSO1}}$			45	ns

**Note** n = 0...1

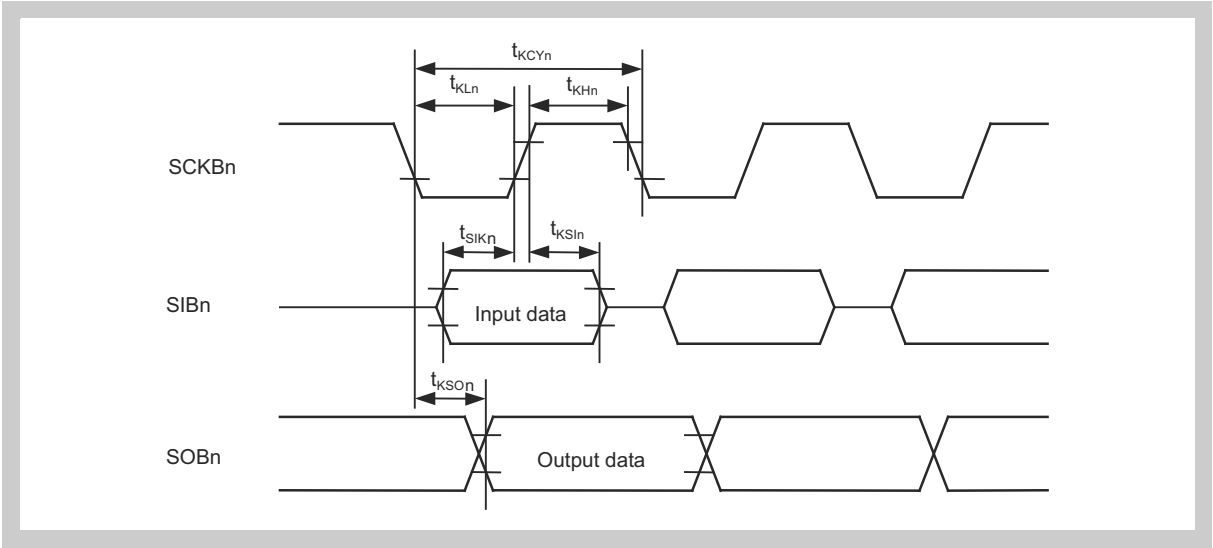


Figure 7-6 CSI Master/Slave Mode Timing

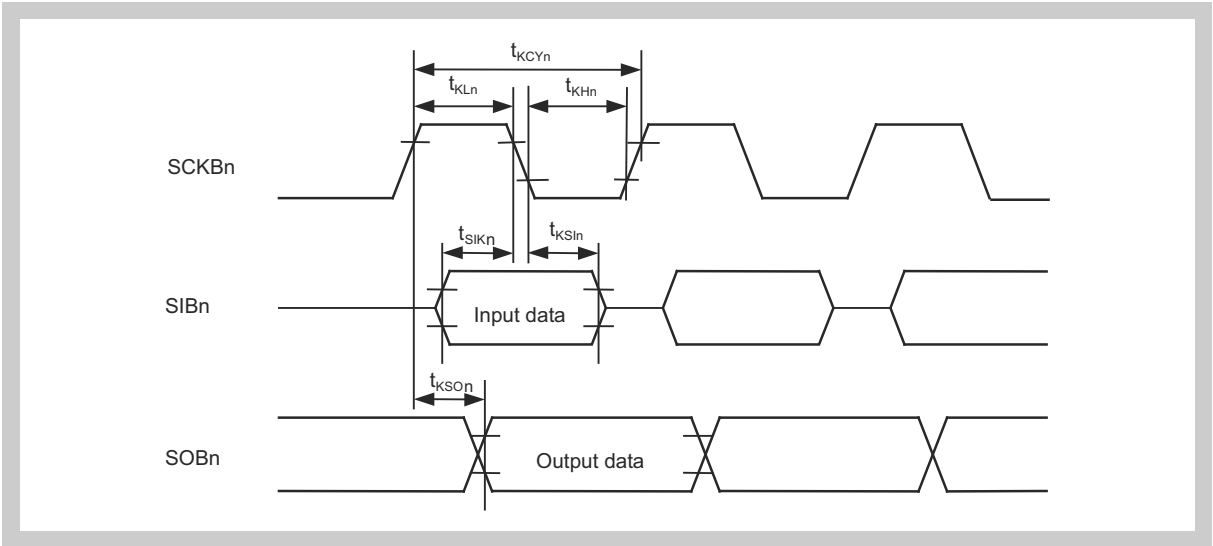


Figure 7-7 CSI Master/Slave Mode Timing Inverted Clock

## 7.5.6 CSIB (Low Voltage Operation)

**Conditions**  $T_A = -40 \sim +85^\circ\text{C}$ ,  
 $BV_{DD5} = 3.0 \text{ V} \sim 4.5 \text{ V}$ ,  
 $AV_{DD} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  $SMV_{DD5} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  
 $V_{DD5} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  
 $V_{SS5} = BV_{SS5} = SMV_{SS5} = AV_{SS} = 0 \text{ V}$

**Note** Refer to “Power On Clear” on page 57 for further functional restriction.

### (1) CSIB Master Mode - Low Voltage Operation

#### (a) With Digital Filter

**Table 7-11 CSIB Master Mode AC Characteristics with Digital Filter - Low Voltage Operation**

Parameter	Symbol	Test Conditions	MIN.	MAX.	Unit
$\overline{\text{SCKBn}}$ cycle time	$t_{\text{KCY1}}$		$8/f_{\text{PCLK0}}$		ns
$\overline{\text{SCKBn}}$ high level width	$t_{\text{KH1}}$		$0.5 t_{\text{KCY1}} - 15$		ns
$\overline{\text{SCKBn}}$ low level width	$t_{\text{KL1}}$		$0.5 t_{\text{KCY1}} - 15$		ns
SIBn setup time (to $\overline{\text{SCKBn}}$ )	$t_{\text{SIK1}}$		$93 + 4/f_{\text{PCLK0}}^a$		ns
SIBn hold time (from $\overline{\text{SCKBn}}$ )	$t_{\text{KSI1}}$		$-49 - 4/f_{\text{PCLK0}}$		ns
Delay time from $\overline{\text{SCKBn}}$ to SOBn	$t_{\text{KSO1}}$			45	ns

a)  $f_{\text{PCLK0}}$  is the clock frequency of the digital filter connected to the input pin.

#### (b) Without Digital Filter

**Table 7-12 CSIB Master Mode AC Characteristics without Digital Filter - Low Voltage Operation**

Parameter	Symbol	Test Conditions	MIN.	MAX.	Unit
$\overline{\text{SCKBn}}$ cycle time	$t_{\text{KCY1}}$		125		ns
$\overline{\text{SCKBn}}$ high level width	$t_{\text{KH1}}$		$0.5 t_{\text{KCY1}} - 80$		ns
$\overline{\text{SCKBn}}$ low level width	$t_{\text{KL1}}$		$0.5 t_{\text{KCY1}} - 80$		ns
SIBn setup time (to $\overline{\text{SCKBn}}$ )	$t_{\text{SIK1}}$		93		ns
SIBn hold time (from $\overline{\text{SCKBn}}$ )	$t_{\text{KSI1}}$		-49		ns
Delay time from $\overline{\text{SCKBn}}$ to SOBn	$t_{\text{KSO1}}$			45	ns

**Note**  $n = 0 \dots 1$

**(2) CSIB Slave Mode - Low Voltage Operation****(a) With Digital Filter****Table 7-13 CSIB Slave Mode AC Characteristics with Digital Filter - Low Voltage Operation**

Parameter	Symbol	Test Conditions	Min	Max	Unit
$\overline{\text{SCKBn}}$ cycle time	$t_{\text{KCY1}}$		$8/f_{\text{PCLK0}}$		ns
$\overline{\text{SCKBn}}$ high level width	$t_{\text{KH1}}$		$4/f_{\text{PCLK0}} - 5$		ns
$\overline{\text{SCKBn}}$ low level width	$t_{\text{KL1}}$		$4/f_{\text{PCLK0}} - 5$		ns
SIBn setup time (to $\overline{\text{SCKBn}}$ )	$t_{\text{SIK1}}$		$15 + 2/f_{\text{PCLK0}}^{\text{a}}$		ns
SIBn hold time (from $\overline{\text{SCKBn}}$ )	$t_{\text{KSI1}}$		$5 + 2/f_{\text{PCLK0}}$		ns
Delay time from $\overline{\text{SCKBn}}$ to SOBn	$t_{\text{KSO1}}$			$100 + 3/f_{\text{PCLK0}}$	ns

a)  $f_{\text{PCLK0}}$  is the clock frequency of the digital filter connected to the input pin.

**(b) Without Digital Filter****Table 7-14 CSIB Slave Mode AC Characteristics without Digital Filter - Low Voltage Operation**

Parameter	Symbol	Test Conditions	Min	Max	Unit
$\overline{\text{SCKBn}}$ cycle time	$t_{\text{KCY1}}$		125		ns
$\overline{\text{SCKBn}}$ high level width	$t_{\text{KH1}}$		50		ns
$\overline{\text{SCKBn}}$ low level width	$t_{\text{KL1}}$		50		ns
SIBn setup time (to $\overline{\text{SCKBn}}$ )	$t_{\text{SIK1}}$		15		ns
SIBn hold time (from $\overline{\text{SCKBn}}$ )	$t_{\text{KSI1}}$		5		ns
Delay time from $\overline{\text{SCKBn}}$ to SOBn	$t_{\text{KSO1}}$			100	ns

**Note** n = 0...1

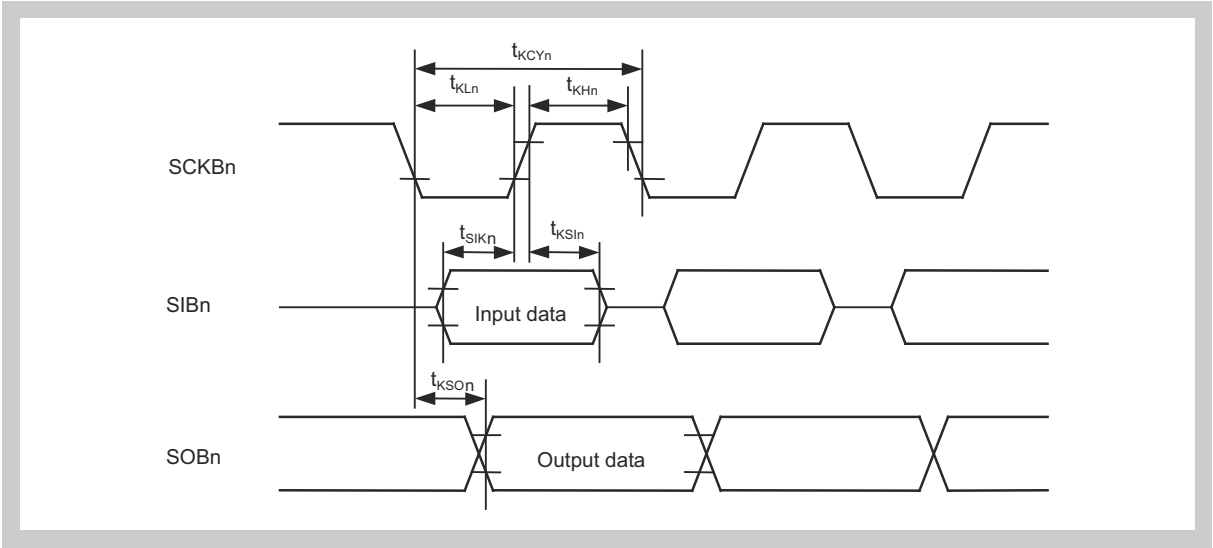


Figure 7-8 CSI Master/Slave Mode Timing - Low Voltage Operation

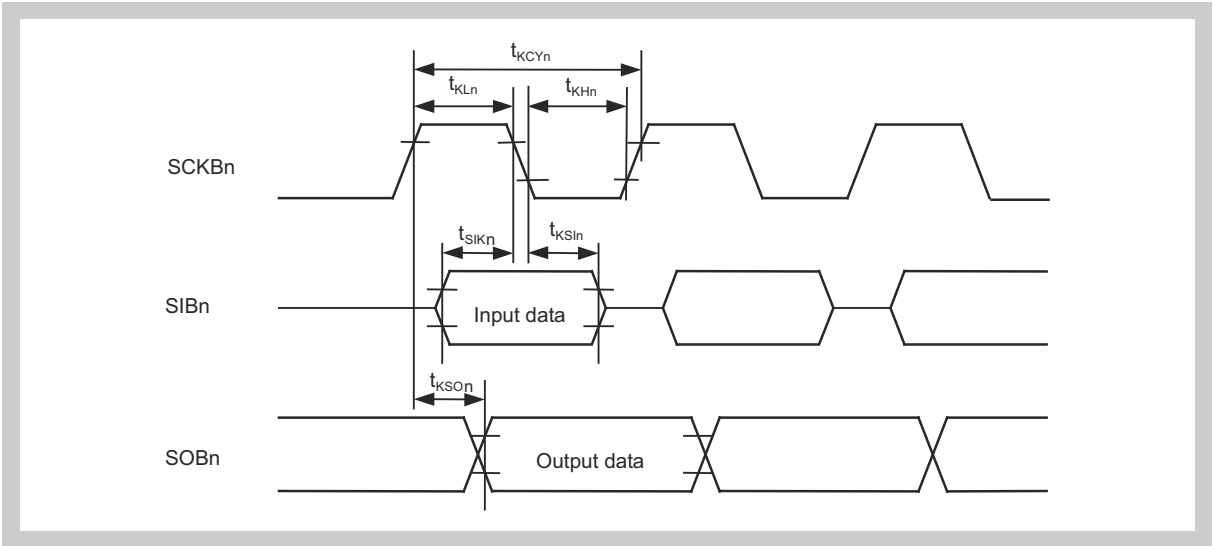
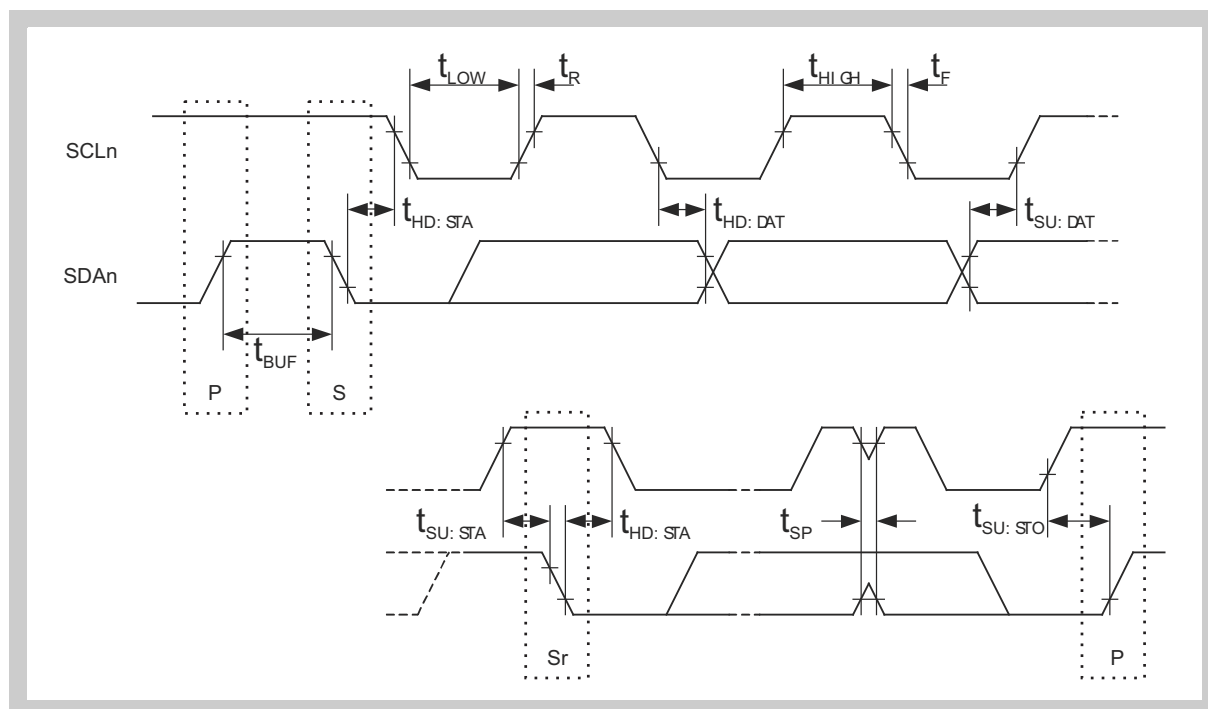


Figure 7-9 CSI Master/Slave Mode Timing Inverted Clock - Low Voltage Operation

7.5.7 I<sup>2</sup>CTable 7-15: I<sup>2</sup>C AC Characteristics

Parameter		Symbol	Normal Mode		Fast-speed Mode		Unit
			min	max	min	max	
SCL0 clock frequency		f <sub>CLK</sub>	0	100	0	381	kHz
Bus-free time (between stop/start conditions)		t <sub>BUF</sub>	4.7	—	1.3	—	μs
Hold time <sup>a</sup>		t <sub>HD:STA</sub>	4.0	—	0.6	—	μs
SCL0 clock low-level width		t <sub>LOW</sub>	4.7	—	1.3	—	μs
SCL0 clock high-level width		t <sub>HIGH</sub>	4.0	—	0.6	—	μs
Setup time for start/restart conditions		t <sub>SU:STA</sub>	4.7	—	0.6	—	μs
Data hold time	CBUS compatible master	t <sub>HD:DAT</sub>	5.0	—	—	—	μs
	I <sup>2</sup> C mode		0 <sup>b</sup>	3.45 <sup>c</sup>	0 <sup>Note b</sup>	0.9 <sup>c</sup>	μs
Data setup time		t <sub>SU:DAT</sub>	250	—	100 <sup>d</sup>	—	ns
STOP condition setup time		t <sub>SU:STO</sub>	4.0	—	0.6	—	μs
Noise suppression <sup>e</sup>		t <sub>SP</sub>				t <sub>IICLK</sub> <sup>f</sup>	ns
Capacitive load of each bus line		C <sub>b</sub>	—	400	—	400	pF

- a) At the start condition, the first clock pulse is generated after the hold time
- b) The system requires a minimum of 300ns hold time Internally for the SDA signal ( at V<sub>IHmin</sub> of SCL0 signal ) in order to occupy the undefined area at the falling edge of SCL0.
- c) If the system does not extend the SCL0 signal low hold time ( t<sub>low</sub> ), only the maximum data hold time ( t<sub>HD:DAT</sub> ) needs to be satisfied.
- d) The fast-speed-mode IIC bus can be used In a normal-mode IIC bus system.  
In this case, set the fast-speed-mode IIC bus so that It meets the following conditions:  
- If the system does not extend the SCL0n signal's low state hold time: t<sub>SU:DAT</sub> >= 250ns  
- If the system extends the SCL0n signal's low state hold time:  
Transmit the following data bit to the SDA0 line prior to releasing the SCL0 line  
( t<sub>Rmax</sub> + t<sub>SU:DAT</sub> = 1000 + 250 = 1250ns: Normal mode IIC bus specification ).
- e) Noise suppression is only available in Fast-speed mode.
- f) t<sub>IICLK</sub> is the period of the IICLK supplied by the clock controller.

Figure 7-10 I<sup>2</sup>C Timing

- Remarks**
1. P: Stop condition
  2. S: Start condition
  3. Sr: Restart condition
  4. Rise and Fall time depend on the actual load of the signal and the selected output current limit. For a capacitive load the time can be roughly calculated from:  
 $(t_R = V_{OH} / I_{OH} * C_L)$ ,  
 $(t_F = V_{OH} / I_{OL} * C_L)$

# Chapter 8 Analog Functions

## 8.1 A/D Converter

8 channel input P70 - P77

**Conditions**  $T_A = -40 \sim +85^\circ\text{C}$ ,  
 $BV_{DD5} = 3.0 \text{ V} \sim 5.5 \text{ V}$ ,  
 $AV_{DD} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  $SMV_{DD5} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  
 $V_{DD5} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  
 $V_{SS5} = BV_{SS5} = SMV_{SS5} = AV_{SS} = 0 \text{ V}$

**Note** Refer to "Power On Clear" on page 57 for further functional restriction.

**Table 8-1 A/D Converter Characteristics**

Parameter	Symbol	Test Conditions	Min	Typ	Max	Unit
Resolution	-			10		Bit
Reference voltage	AVREF		AVSS		AVDD	V
Overall error <sup>a</sup>	-	$AV_{SS} \leq AIN \leq AV_{REF}$ , $4.5V \leq (AV_{REF} = AV_{DD}) \leq 5.5V$			+/- 3.5	LSB
	-	$AV_{SS} \leq AIN \leq AV_{REF}$ , $3.5V = AV_{REF}$ , $4.0V \leq AV_{DD} \leq 5.5V$			+/- 10	LSB
Additional error due to disturbance by digital read of P70..P77 <sup>b</sup>	DRERR				1	LSB
Conversion time <sup>c</sup>	T <sub>CONV</sub>		3.88		15.50	μs
Analog input voltage	V <sub>IAN</sub>		AVSS		AVDD	V
Analogue supply current	I <sub>AVDD</sub>				10	mA
Analog input equivalent circuit resistance <sup>b</sup> )	R <sub>INA</sub>		0.3		2.55	kΩ
Analog input equivalent circuit capacitance <sup>b</sup> )	C <sub>INA</sub>		4.0		8.0	pF
Analogue supply current	I <sub>AVDD</sub>				10	mA
Reference voltage supply current <sup>d</sup>	I <sub>AVREF</sub>				250	μA

a) Quantization error of ±0.5 LSB is not included

b) This value is not tested during production.

c) T<sub>CONV</sub> depends on register setting

d) The reference current is mainly a transient current that is influenced by the conversion time. The given value is the maximum value. Value is not tested during production.



## 8.2 Power On Clear

**Conditions**  $T_A = -40 \sim +85^\circ\text{C}$ ,  
 $V_{DD5} = 0 \sim 5.5 \text{ V}$ ,  
 $V_{SS} = 0 \text{ V}$

**Table 8-2 Power On Clear Characteristics**

Parameter	Symbol	Test Conditions	Min	Typ	Max	Unit
Threshold Voltage	$V_{IP}$		3.2	3.35	3.5	V
Detection time <sup>a</sup>	$T_{DETP}$	$V_{DD5}$ slope > 25mV/ $\mu\text{s}$			2	$\mu\text{s}$

<sup>a)</sup> Not tested in production.

- Note**
1. The POC ensures that the devices stops operation (RESET condition) when the device is outside the operation voltage range, under the condition that the supply voltage slope on  $V_{DD5}$  is  $\leq 25\text{mV}/\mu\text{s}$ .
  2. Full device operation is only available, when the supply voltage is above the maximum threshold voltage. The device may stop operation due to reset condition generated by POC, if the supply voltage dropps below the given max threshold voltage.

# Chapter 9 Memory Characteristics

## 9.1 Basic Characteristics

**Conditions**  $T_A = -40 \sim +85^\circ\text{C}$ ,  
 $BV_{DD5} = 3.0 \text{ V} \sim 5.5 \text{ V}$ ,  
 $AV_{DD} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  $SMV_{DD5} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  
 $V_{DD5} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  
 $V_{SS5} = BV_{SS5} = SMV_{SS5} = AV_{SS} = 0 \text{ V}$

**Note** Refer to "Power On Clear" on page 57 for further functional restriction.

**Table 9-1** Memory Operation Characteristics

Parameter	Symbol	Device	Min	Typ	Max	Unit
Operation Frequency	$f_{\text{CPU}}$	$\mu\text{PD70F3416(A)}$ $\mu\text{PD70F3417(A)}$	0.032		24	MHz

**Note** The above maximum operation frequency specification lists the center frequency of the SSCG. The maximum dithering range of the SSCG is assured for this center frequency.

## 9.2 Flash Memory Characteristics

**Conditions**  $T_A = -40 \sim +85^\circ\text{C}$ ,  
 $BV_{DD5} = 3.0 \text{ V} \sim 5.5 \text{ V}$ ,  
 $AV_{DD} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  $SMV_{DD5} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  
 $V_{DD5} = 4.5 \text{ V} \sim 5.5 \text{ V}$ ,  
 $V_{SS5} = BV_{SS5} = SMV_{SS5} = AV_{SS} = 0 \text{ V}$

**Note** Refer to “Power On Clear” on page 57 for further functional restriction.

**Table 9-2 Flash Memory Programming Characteristics**

Parameter	Symbol	Test Conditions	Min	Typ	Max	Unit
Number of Rewrites	$C_{WRT}$				1000	times
Data retention	$t_{RET}$		15			years
Blank Check Time <sup>a</sup>	$t_{IVBL4k}$	One memory block (4k)	$f_{CPU} = 24 \text{ MHz}$	520	630	$\mu\text{s}$
	$t_{IVBL128k}$	32 memory blocks (128k)		9.12	10.94	ms
Erase Time	$t_{IERT4k}$	One memory block (4k)		26.18	523.6	ms
	$t_{IERT128k}$	32 memory blocks (128k)		34.87	697.40	ms
Write Time	$t_{IWRT4k}$	Write two words <sup>b</sup>		300	900	$\mu\text{s}$
	$t_{IWRT128k}$	One memory block (4k) @ 256 bytes		42.79	354.24	ms
Erase/Write Current <sup>c</sup>	$I_{DDFL}$			1	3	mA
Programming Temperature	$t_{PRG}$		-40		+65	$^\circ\text{C}$
		maximum power dissipation 0.6W <sup>d</sup>	-40		+85	$^\circ\text{C}$

a) Blank check of one memory block (4 kB).

b) Write of 2 words. The corresponding library call is configured for 2 word per call.

c) Additional current that is only needed during erase or write of flash.

d) The power dissipation may be reduced by disabling some functionality or reducing the CPU operation speed.

### 9.3 Special Conditions for End-of-Line Programming

**Conditions**  $T_A = +15 \sim +40^\circ\text{C}$ ,  
 $BV_{DD5} = 3.0 \text{ V} \sim 5.5 \text{ V}$ ,  
 $AV_{DD} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  $SMV_{DD5} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  
 $V_{DD5} = 4.8 \text{ V} \sim 5.15 \text{ V}$ ,  
 $V_{SS5} = BV_{SS5} = SMV_{SS5} = AV_{SS} = 0 \text{ V}$

**Note** Refer to “Power On Clear” on page 57 for further functional restriction.

**Table 9-3 Flash Memory End-of-Line Programming Characteristics (PG-FP4: CSI)**

Parameter	Symbol	Device	Test Conditions	Min	Typ	Max	Unit
Blank Check	$t_{IVBL}$	$\mu\text{PD70F3417}$	W/E cycles $\leq 5$ , $f_{\text{CPU}} = 24\text{MHz}$		20	40	ms
		$\mu\text{PD70F3416}$			12	20	ms
Erase Time <sup>a</sup>	$t_{IWRT}$	$\mu\text{PD70F3417}$			0.1	0.3	s
		$\mu\text{PD70F3416}$			0.1	0.3	s
Write Time <sup>b</sup>	$t_{IERT}$	$\mu\text{PD70F3417}$			10	18	s
		$\mu\text{PD70F3416}$			6	10	s
Verify Time	$t_{IVRT}$	$\mu\text{PD70F3417}$			8	10	s
		$\mu\text{PD70F3416}$			4	5	s

a) Erase of all flash-memory blocks (0 .. 63)

b) Write of complete flash area.

**Note** All parameters were determined at: SIO @ 2.5MHz (max. comm. speed).

**Table 9-4 Flash Memory End-of-Line Programming Characteristics (PG-FP4: UART)**

Parameter	Symbol	Device	Test Conditions	Min	Typ	Max	Unit
Blank Check	$t_{IVBL}$	$\mu\text{PD70F3417}$	W/E cycles $\leq 5$ , $f_{\text{CPU}} = 24\text{MHz}$		20	40	ms
		$\mu\text{PD70F3416}$			12	20	ms
Erase Time <sup>a</sup>	$t_{IWRT}$	$\mu\text{PD70F3417}$			0.1	0.3	s
		$\mu\text{PD70F3416}$			0.1	0.3	s
Write Time <sup>b</sup>	$t_{IERT}$	$\mu\text{PD70F3417}$			21	30	s
		$\mu\text{PD70F3416}$			11	16	s
Verify Time	$t_{IVRT}$	$\mu\text{PD70F3417}$			20	25	s
		$\mu\text{PD70F3416}$			10	12	s

a) Erase of all flash-memory blocks (0 .. 63)

b) Write of complete flash area.

**Note** All parameters were determined at: UART @ 153600baud.

**Table 9-5 Flash Memory End-of-Line Programming Characteristics (Flash-Selfprogramming)**

Parameter	Symbol	Test Conditions	Min	Typ	Max	Unit
Blank Check One memory block (4k)	$t_{IVBL4k}$	W/E cycles $\leq$ 5, $f_{CPU} = 24\text{MHz}$		0.52	0.63	ms
Blank Check 32 memory blocks (128k)	$t_{IVBL128k}$			9.12	10.94	ms
Erase Time One memory block (4k)	$t_{IERT4k}$			26.18	104.72	ms
Erase Time 32 memory blocks (128k)	$t_{IERT128k}$			34.87	139.48	ms
Write Time Write two words <sup>a</sup>	$t_{IWRT}$			0.30	0.43	ms
Write Time: One memory block (4k) @ 256 Bytes <sup>b</sup>	$t_{IWRT4k}$			42.79	112.00	ms
Verify Time: One memory block (4k)	$t_{IVRT4k}$			17.13	20.55	ms
Verify Time: 32 memory blocks (128k)	$t_{IVRT128k}$			541.20	649.44	ms

a) The corresponding library call is configured for 2 words per call.

b) The corresponding library call uses a 256 Bytes (64 words) source buffer.

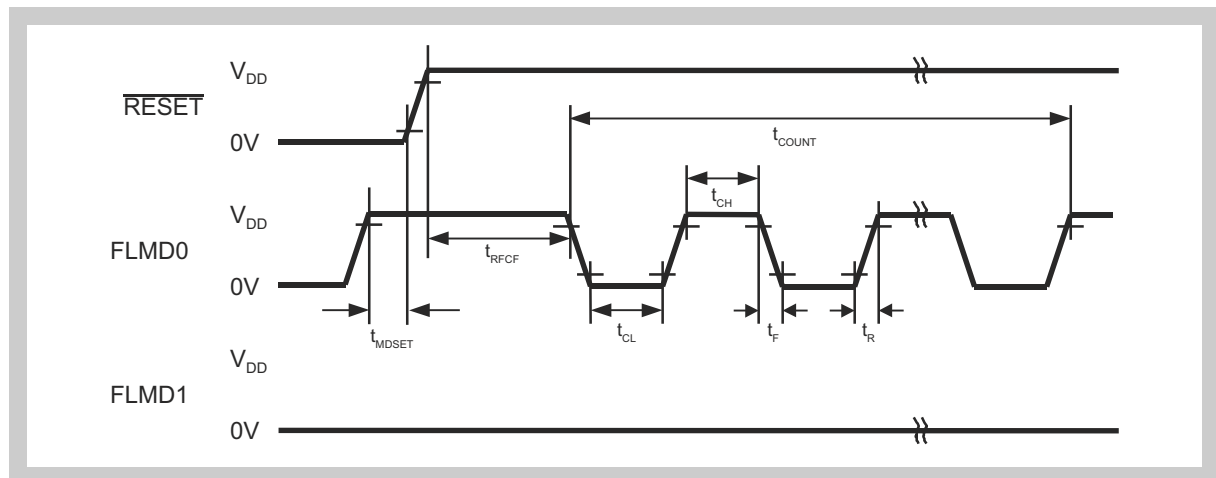
## 9.4 Serial Write Operation Characteristics

**Conditions**  $T_A = -40 \sim +85^\circ\text{C}$ ,  
 $BV_{DD5} = 3.0 \text{ V} \sim 5.5 \text{ V}$ ,  
 $AV_{DD} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  $SMV_{DD5} = 3.2 \text{ V} \sim 5.5 \text{ V}$ ,  
 $V_{DD5} = 4.5 \text{ V} \sim 5.5 \text{ V}$ ,  
 $V_{SS5} = BV_{SS5} = SMV_{SS5} = AV_{SS} = 0 \text{ V}$

**Note** Refer to “Power On Clear” on page 57 for further functional restriction.

**Table 9-6 Flash Memory AC Characteristics**

Parameter	Symbol	Test Conditions	Min	Typ	Max	Unit
FLMD0 setup time to rising edge of RESET	$t_{MDSET}$		2			ms
Count start time from rising edge of RESET to FLMD0	$t_{RFCF}$		0.8			ms
Count execution time	$t_{COUNT}$		20			ms
FLMD0 counter High/Low level width	$t_{CH}, t_{CL}$		10		100	$\mu\text{s}$
FLMD0 counter rise/fall time	$t_R, t_F$				50	ns



**Figure 9-1 Flash Memory Timing**

**Note** FLMD1 is a shared pin function.

# Chapter 10 Package

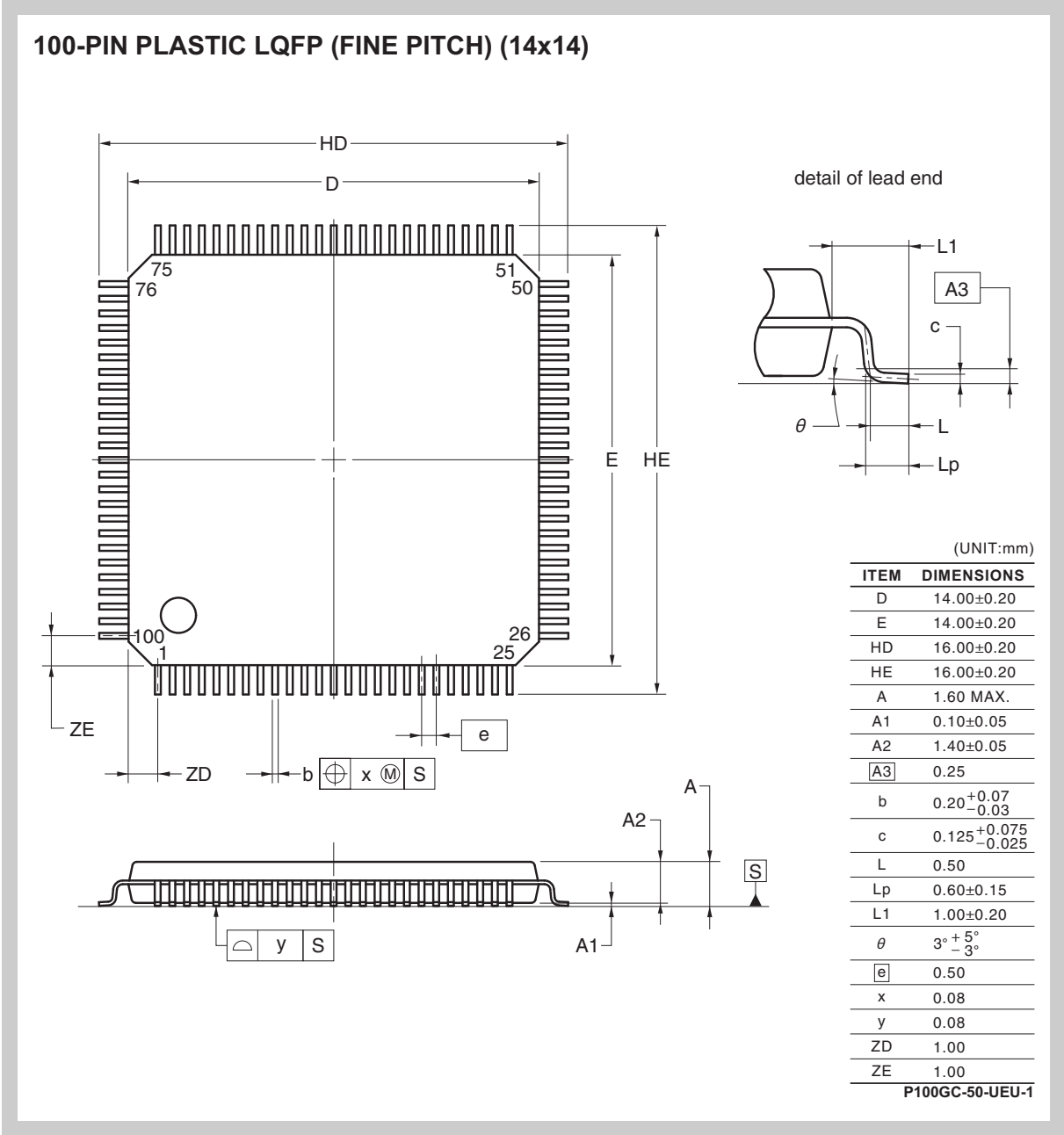


Figure 10-1 Package Drawing μPD70F3417(A)GC, μPD70F3416(A)GC

Copper lead frame with NiPdAu plating.

## Appendix A Revision History

Item	Date published	Document No.	Comment
1	Dec 19 , 2006	EASE-DS-0004-1V0	First release of this document
2	Oct 2, 2008	U19509EE1V0DS00	Update of whole document, added conditions for extended operating temperature range, added injected current characteristics, added low voltage operation for CSIB, added supply current of flash devices, updated flash memory programming characteristics, added package drawing, added device $\mu$ PD70F3416.
3	Jan 20, 2010	U19509EE1V1DS00	- $\mu$ PD70F3416(A) was $\mu$ PD70F3416 - $\mu$ PD70F3417(A) was $\mu$ PD70F3417
			- Added TM0 in Table 1-1
			- Added Table 4-3 - Main OSC Characteristics example for NDK LN-G8-1404
			- Added "Main OSC, PLLx8" and "Main OSC, SSCG" in table 5-2 for FOUT
			- Corrected values for " $\overline{\text{SCKBn}}$ high level width" and " $\overline{\text{SCKBn}}$ low level width" in table 7-9 (CSIB Slave Mode AC Characteristics with Digital Filter )
			- Corrected prefix of min. "SIBn hold time ( from $\overline{\text{SCKBn}}$ )" in table 7-11 (CSIB Master Mode AC Characteristics with Digital Filter - Low Voltage Operation)
			- Corrected Package code to "GC" (whole document)
4	Jun 8, 2011	R01DS0109ED0200	- Update the whole document to new Renesas format.
			- AC Characteristics of Flash Memory changed to more relaxed values ( $t_{\text{MDSET}}$ , $t_{\text{COUNT}}$ )



**SALES OFFICES****Renesas Electronics Corporation**<http://www.renesas.com>Refer to "<http://www.renesas.com/>" for the latest and detailed information.**Renesas Electronics America Inc.**2880 Scott Boulevard Santa Clara, CA 95050-2554, U.S.A.  
Tel: +1-408-588-6000, Fax: +1-408-588-6130**Renesas Electronics Canada Limited**1101 Nicholson Road, Newmarket, Ontario L3Y 9C3, Canada  
Tel: +1-905-898-5441, Fax: +1-905-898-3220**Renesas Electronics Europe Limited**Dukes Meadow, Millboard Road, Bourne End, Buckinghamshire, SL8 5FH, U.K  
Tel: +44-1628-585-100, Fax: +44-1628-585-900**Renesas Electronics Europe GmbH**Arcadiastrasse 10, 40472 Düsseldorf, Germany  
Tel: +49-211-65030, Fax: +49-211-6503-1327**Renesas Electronics (China) Co., Ltd.**7th Floor, Quantum Plaza, No.27 ZhiChunLu Haidian District, Beijing 100083, P.R.China  
Tel: +86-10-8235-1155, Fax: +86-10-8235-7679**Renesas Electronics (Shanghai) Co., Ltd.**Unit 204, 205, AZIA Center, No.1233 Lujiazui Ring Rd., Pudong District, Shanghai 200120, China  
Tel: +86-21-5877-1818, Fax: +86-21-6887-7858 / -7898**Renesas Electronics Hong Kong Limited**Unit 1601-1613, 16/F., Tower 2, Grand Century Place, 193 Prince Edward Road West, Mongkok, Kowloon, Hong Kong  
Tel: +852-2886-9318, Fax: +852 2886-9022/9044**Renesas Electronics Taiwan Co., Ltd.**7F, No. 363 Fu Shing North Road Taipei, Taiwan  
Tel: +886-2-8175-9600, Fax: +886 2-8175-9670**Renesas Electronics Singapore Pte. Ltd.**1 harbourFront Avenue, #06-10, keppel Bay Tower, Singapore 098632  
Tel: +65-6213-0200, Fax: +65-6278-8001**Renesas Electronics Malaysia Sdn.Bhd.**Unit 906, Block B, Menara Amcorp, Amcorp Trade Centre, No. 18, Jln Persiaran Barat, 46050 Petaling Jaya, Selangor Darul Ehsan, Malaysia  
Tel: +60-3-7955-9390, Fax: +60-3-7955-9510**Renesas Electronics Korea Co., Ltd.**11F., Samik Lavied' or Bldg., 720-2 Yeoksam-Dong, Kangnam-Ku, Seoul 135-080, Korea  
Tel: +82-2-558-3737, Fax: +82-2-558-5141

V850E/DG3



Renesas Electronics Corporation

R01DS0109ED0200, Rev. 2.00