

ISL72027CSEH

3.3V Radiation Hardened CAN Transceiver with Listen Mode and Split Termination Output

The [ISL72027CSEH](#) is a radiation hardened 3.3V CAN transceiver that is compatible with the ISO11898-2 standard for applications calling for Controller Area Network (CAN) serial communication in satellites and aerospace communications, and telemetry data processing in harsh industrial environments.

This device can transmit and receive at bus speeds of up to 5Mbps. It can drive a 40m cable at 1Mbps per the ISO11898-2 specification. The device is designed to operate over a common-mode range of -7V to +12V, with a maximum of 120 nodes. The device has three discrete selectable driver rise/fall time options, a Listen mode feature, and a Split termination output.

The receiver (Rx) inputs feature a “full fail-safe” design, which ensures a logic high Rx output if the Rx inputs are floating, shorted, or terminated but undriven.

The ISL72027CSEH is available in an 8 Ld hermetic ceramic flatpack and die form that operates across the temperature range of -55°C to +125°C. The logic inputs are tolerant with 5V systems.

Other CAN transceivers available are the [ISL72026CSEH](#) and [ISL72028CSEH](#). For a list of differences between these devices, refer to [Table 4](#).

Applications

- Satellites and aerospace communications
- Telemetry data processing and high-end industrial

Features

- Electrically screened to SMD [5962-15228](#)
- ESD protection on all pins: 4kV HBM
- Compatible with ISO11898-2
- Operating supply range: 3.0V to 3.6V
- Bus pin fault protection to $\pm 20V$
- Undervoltage lockout
- Cold spare: powered down devices/nodes do not affect active devices operating in parallel
- Three selectable driver rise and fall times
 - Fast speed (RS = 0V) - edges and propagation delays optimized for data rate of 1Mbps
 - Medium speed (RS = 10k Ω) - edges and propagation delays optimized for data rate of 500kbps
 - Slow speed (RS = 50k Ω) - edges and propagation delays optimized for data rate of 250kbps
- Glitch free bus I/O during power-up and power-down
- Full fail-safe (open, short, terminated/undriven) receiver
- Hi-Z input allows for 120 nodes on the bus
- High data rates: up to 5Mbps
- Quiescent supply current: 7mA (maximum)
- Listen mode supply current: 2mA (maximum)
- -7V to +12V common-mode input voltage range
- 5V tolerant logic inputs
- Thermal shutdown
- Acceptance tested to 75krad(Si) (LDR) and to 100krad(Si) (HDR) wafer-by-wafer
- Radiation hardened
 - SEL/B immune to LET_{TH}: 86.4MeV•cm²/mg
 - Low dose rate (0.01rad(Si)/s): 75krad(Si)
 - High dose rate (50-300rad(Si)/s): 100krad(Si)

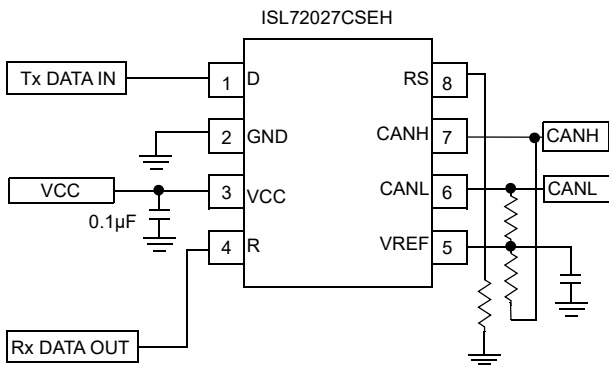


Figure 1. Typical Application

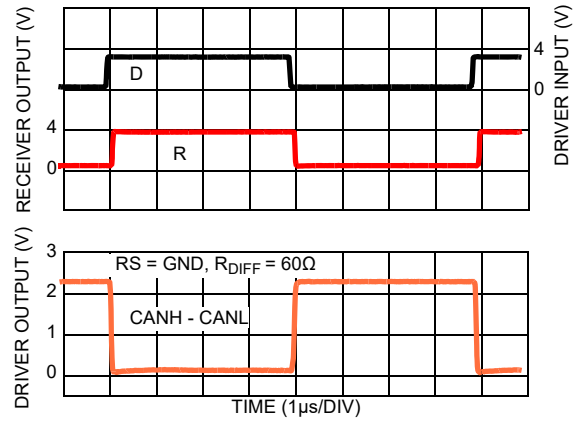


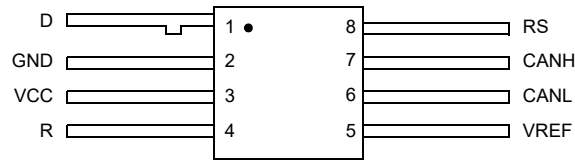
Figure 2. Fast Driver and Receiver Waveforms

Contents

1. Pin Information	4
1.1 Pin Assignments	4
1.2 Pin Descriptions	4
1.3 Equivalent Input and Output Diagrams	5
2. Specifications	6
2.1 Absolute Maximum Ratings	6
2.2 Thermal Information	6
2.3 Recommended Operating Conditions	6
2.4 Electrical Specifications	7
2.5 Test Circuits and Waveforms	11
3. Typical Performance Curves	14
4. Functional Description	18
4.1 Overview	18
4.2 Slope Adjustment	18
4.2.1 Fast Speed Mode	18
4.2.2 Medium Speed Mode	18
4.2.3 Slow Speed Mode	18
4.3 Cable Length	18
4.4 Cold Spare	18
4.5 Listen Mode	19
4.6 Using 3.3V Devices in 5V Systems	19
4.7 Split Mode Termination	19
5. Package and Die Characteristics	20
5.1 Metallization Mask Layout	21
6. Package Outline Drawing	23
7. Ordering Information	24
8. Revision History	25

1. Pin Information

1.1 Pin Assignments



Note: The package lid is tied to ground.

Figure 3. Pin Assignments - Top View

1.2 Pin Descriptions

Pin Number	Pin Name	Function
1	D	CAN driver digital input. A LOW bus state is Dominant and a HIGH bus state is Recessive. Internally tied HIGH.
2	GND	Ground connection.
3	VCC	System power supply input (3.0V to 3.6V). The typical voltage for the device is 3.3V.
4	R	CAN data receiver output. A LOW bus state is Dominant and a HIGH bus state is Recessive.
5	VREF	VCC/2 reference output for Split mode termination.
6	CANL	CAN bus line for low level output.
7	CANH	CAN bus line for high level output.
8	RS	A resistor to GND from this pin controls the rise and fall time of the CAN output waveform. Drive RS HIGH to put the device in Listen mode.

1.3 Equivalent Input and Output Diagrams

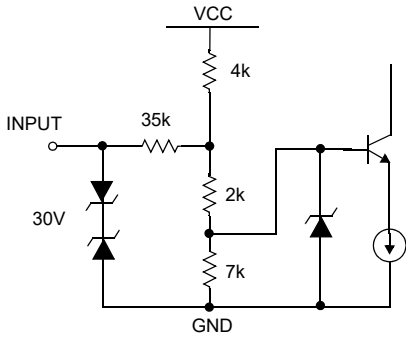


Figure 4. CANH and CANL Inputs

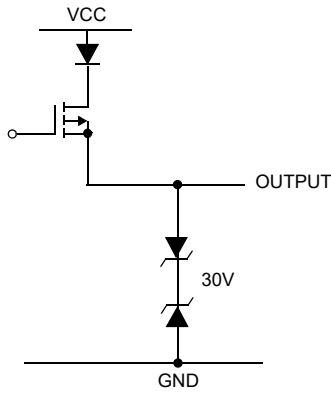


Figure 5. CANH Output

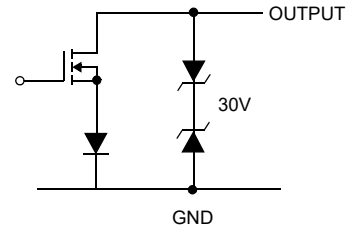


Figure 6. CANL Output

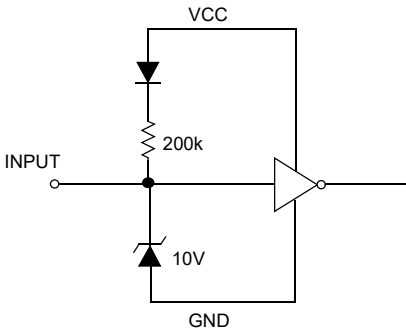


Figure 7. D Input

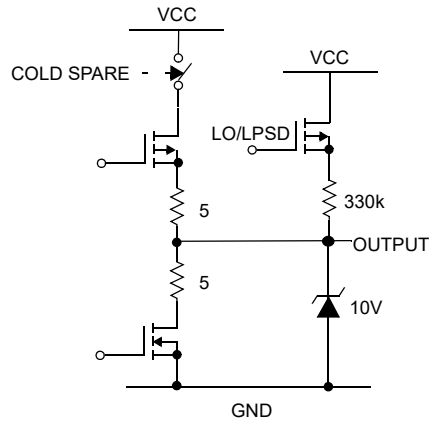


Figure 8. R Output

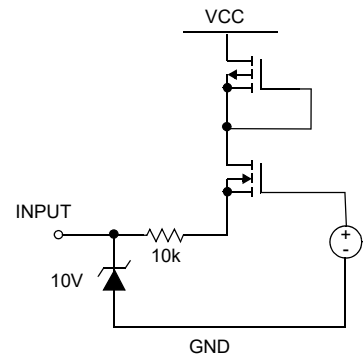


Figure 9. RS Input

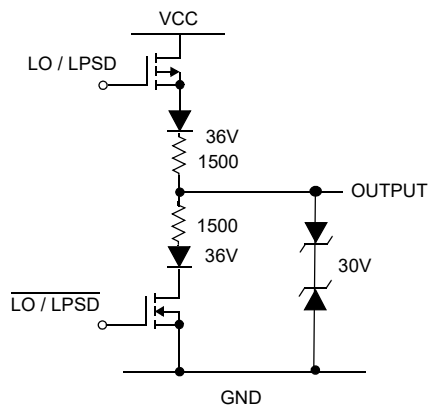


Figure 10. V_{REF}

2. Specifications

2.1 Absolute Maximum Ratings

Caution: Do not operate at or near the maximum ratings listed for extended periods of time. Exposure to such conditions may adversely impact product reliability and result in failures not covered by warranty.

Parameter	Minimum	Maximum	Unit
VCC to GND with/without Ion Beam	-0.3	5.5	V
CANH, CANL, VREF Under Ion Beam		±20	V
CANH, CANL, VREF		±20	V
I/O Voltages D, R, RS	-0.5	7	V
Receiver Output Current	-10	10	mA
Output Short-Circuit Duration	Continuous		
Maximum Junction Temperature		+150	°C
Maximum Storage Temperature Range	-65	+150	°C
Human Body Model (Tested per MIL-STD-883 TM3015.7)			
CANH, CANL Bus Pins	-	4	kV
All Other Pins	-	4	kV
Charged Device Model (Tested per JS-002-2014)	-	750	V
Machine Model (Tested per JESD22-A115C)	-	200	V

2.2 Thermal Information

Parameter	Package	Symbol	Conditions	Typical Value	Unit
Thermal Resistance	8 Ld FP Package	$\theta_{JA}^{[1]}$	Junction to ambient	39	°C/W
		$\theta_{JC}^{[2]}$	Junction to case	7	°C/W

1. θ_{JA} is measured with the component mounted on a high-effective thermal conductivity test board (two buried 1oz copper planes) with direct attach features package base mounted to a PCB thermal land with a 10 mil gap fill material having a thermal conductivity of 1W/m-K. Refer to [TB379](#).

2. For θ_{JC} , the case temperature location is the center of the package underside.

2.3 Recommended Operating Conditions

Parameter	Minimum	Maximum	Unit
Temperature Range	-55	+125	°C
V _{CC} Supply Voltage	3	3.6	V
Voltage on CAN I/O	-7	12	V
V _{IH} D Logic Pin	2	5.5	V
V _{IL} D Logic Pin	0	0.8	V
I _{OH} Driver (CANH - CANL = 1.5V, V _{CC} = 3.3V)	-	-40	mA
I _{OH} Receiver (V _{OH} = 2.4V)	-	-4	mA

Parameter	Minimum	Maximum	Unit
I_{OL} Driver (CANH - CANL = 1.5V, V_{CC} = 3.3V)	-	40	mA
I_{OL} Receiver (V_{OL} = 0.4V)	-	4	mA

2.4 Electrical Specifications

Test Conditions: V_{CC} = 3V to 3.6V. Typical values are at T_A = +25°C^[1], unless otherwise specified^[2]. **Boldface limits apply across the operating temperature range, -55°C to +125°C; over a total ionizing dose of 75krad(Si) at +25°C with exposure at a low dose rate of <10mrad(Si)/s, and over a total ionizing dose of 100krad(Si) at +25°C with exposure of a high dose rate of 50krad(Si)/s to 300krad(Si)/s.**

Parameter	Symbol	Test Conditions	Temp (°C)	Min ^[3]	Typ ^[1]	Max ^[3]	Unit
Driver Electrical Characteristics							
Dominant Bus Output Voltage	$V_{O(DOM)}$	D = 0V, CANH, RS = 0V, Figure 11, Figure 12	$3V \leq V_{CC} \leq 3.6V$	Full	2.25	2.85	V_{CC}
		D = 0V, CANL, RS = 0V, Figure 11, Figure 12		Full	0.10	0.65	1.25
Recessive Bus Output Voltage	$V_{O(REC)}$	D = 3V, CANH, RS = 0V, 60Ω and no load, Figure 11, Figure 12	$3V \leq V_{CC} \leq 3.6V$	Full	1.80	2.30	2.70
		D = 3V, CANL, RS = 0V, 60Ω and no load, Figure 11, Figure 12		Full	1.80	2.30	2.80
Dominant Output Differential Voltage	$V_{OD(DOM)}$	D = 0V, RS = 0V, $3V \leq V_{CC} \leq 3.6V$, Figure 11, Figure 12	$3V \leq V_{CC} \leq 3.6V$	Full	1.5	2.2	3.0
		D = 0V, RS = 0V, $3V \leq V_{CC} \leq 3.6V$, Figure 12, Figure 13		Full	1.2	2.1	3.0
Recessive Output Differential Voltage	$V_{OD(REC)}$	D = 3V, RS = 0V, $3V \leq V_{CC} \leq 3.6V$, Figure 11, Figure 12	$3V \leq V_{CC} \leq 3.6V$	Full	-120	0.2	12
		D = 3V, RS = 0V, $3.0V \leq V_{CC} \leq 3.6V$, no load		Full	-500	-34	50
Logic Input High Voltage (D) ^[4]	V_{IH}	$3V \leq V_{CC} \leq 3.6V$	Full	2.0	-	5.5	
Logic Input Low Voltage (D) ^[4]	V_{IL}	$3V \leq V_{CC} \leq 3.6V$	Full	0	-	0.8	
High Level Input Current (D)	I_{IH}	D = 2V, $3V \leq V_{CC} \leq 3.6V$	Full	-30	-3	30	
Low Level Input Current (D)	I_{IL}	D = 0.8V, $3V \leq V_{CC} \leq 3.6V$	Full	-30	-7	30	
RS Input Voltage for Listen Mode	$V_{IN(RS)}$	$3V \leq V_{CC} \leq 3.6V$	Full	$0.75 \times V_{CC}$	1.90	5.5	
Output Short-Circuit Current	I_{OSC}	$V_{CANH} = -7V$, CANL = OPEN, $3V \leq V_{CC} \leq 3.6V$, Figure 23, Figure 24	Full	-250	-100	-	
		$V_{CANH} = +12V$, CANL = OPEN, $3V \leq V_{CC} \leq 3.6V$, Figure 23, Figure 24	Full	-	0.4	1.0	
		$V_{CANL} = -7V$, CANH = OPEN, $3V \leq V_{CC} \leq 3.6V$, Figure 23, Figure 24	Full	-1.0	-0.4	-	
		$V_{CANL} = +12V$, CANH = OPEN, $3V \leq V_{CC} \leq 3.6V$, Figure 23, Figure 24	Full	-	100	250	

Test Conditions: $V_{CC} = 3V$ to $3.6V$. Typical values are at $T_A = +25^{\circ}C$ ^[1], unless otherwise specified ^[2]. **Boldface limits apply across the operating temperature range, $-55^{\circ}C$ to $+125^{\circ}C$; over a total ionizing dose of $75krad(Si)$ at $+25^{\circ}C$ with exposure at a low dose rate of $<10mrad(Si)/s$, and over a total ionizing dose of $100krad(Si)$ at $+25^{\circ}C$ with exposure of a high dose rate of $50krad(Si)/s$ to $300krad(Si)/s$.** (Cont.)

Parameter	Symbol	Test Conditions	Temp (°C)	Min ^[3]	Typ ^[1]	Max ^[3]	Unit
Thermal Shutdown Temperature	T_{SHDN}	$3V < V_{IN} < 3.6V$	-	-	163	-	°C
Thermal Shutdown Hysteresis	T_{HYS}	$3V < V_{IN} < 3.6V$	-	-	12	-	°C
Receiver Electrical Characteristics							
Input Threshold Voltage (Rising)	V_{THR}	RS = 0V, 10k, 50k, (recessive to dominant), Figure 17 , Figure 18 and Table 1	Full	-	700	900	mV
Input Threshold Voltage (Falling)	V_{THF}	RS = 0V, 10k, 50k, (dominant to recessive), Figure 17 , Figure 18 and Table 1	Full	500	625	-	mV
Input Hysteresis	V_{HYS}	$(V_{THR} - V_{THF})$, RS = 0V, 10k, 50k, Figure 17 , Figure 18 and Table 1	Full	40	80	-	mV
Listen Mode Input Threshold Voltage (Rising)	V_{THRLM}	RS = V_{CC} , (recessive to dominant), Figure 21 , Figure 22	Full	-	650	900	mV
Listen Mode Input Threshold Voltage (Falling)	V_{THFLM}	RS = V_{CC} , (dominant to recessive), Figure 21 , Figure 22	Full	325	550	-	mV
Listen Mode Input Hysteresis	V_{HYSLM}	$(V_{THR} - V_{THF})$, RS = V_{CC} , Figure 21 , Figure 22	Full	40	100	-	mV
Receiver Output High Voltage	V_{OH}	$I_O = -4mA$	Full	2.4	$V_{CC} - 0.2$	-	V
Receiver Output Low Voltage	V_{OL}	$I_O = +4mA$	Full	-	0.2	0.4	V
Input Current for CAN Bus	I_{CAN}	CANH or CANL at 12V, D = 3V, other bus pin at 0V, RS = 0V	Full	-	470	600	μA
		CANH or CANL at 12V, D = 3V, $V_{CC} = 0V$, other bus pin at 0V, RS = 0V	Full	-	170	275	μA
		CANH or CANL at -7V, D = 3V, other bus pin at 0V, RS = 0V	Full	-500	-350	-	μA
		CANH or CANL at -7V, D = 3V, $V_{CC} = 0V$, other bus pin at 0V, RS = 0V	Full	-175	-100	-	μA
Input Capacitance (CANH or CANL)	C_{IN}	Input to GND, D = 3V, RS = 0V	25	-	35	-	pF
Differential Input Capacitance	C_{IND}	Input to Input, D = 3V, RS = 0V	25	-	15	-	pF
Input Resistance (CANH or CANL)	R_{IN}	Input to GND, D = 3V, RS = 0V	Full	20	40	50	kΩ
Differential Input Resistance	R_{IND}	Input to Input, D = 3V, RS = 0V	Full	40	80	100	kΩ

Test Conditions: $V_{CC} = 3V$ to $3.6V$. Typical values are at $T_A = +25^{\circ}C$ ^[1], unless otherwise specified ^[2]. **Boldface limits apply across the operating temperature range, $-55^{\circ}C$ to $+125^{\circ}C$; over a total ionizing dose of $75krad(Si)$ at $+25^{\circ}C$ with exposure at a low dose rate of $<10mrad(Si)/s$, and over a total ionizing dose of $100krad(Si)$ at $+25^{\circ}C$ with exposure of a high dose rate of $50krad(Si)/s$ to $300krad(Si)/s$. (Cont.)**

Parameter	Symbol	Test Conditions	Temp (°C)	Min ^[3]	Typ ^[1]	Max ^[3]	Unit
Supply Current							
Supply Current, Listen Mode	$I_{CC(L)}$	$RS = D = V_{CC}, 3V \leq V_{CC} \leq 3.6V$	Full	-	1	2	mA
Supply Current, Dominant	$I_{CC(DOM)}$	$D = RS = 0V$, no load, $3V \leq V_{CC} \leq 3.6V$	Full	-	5	7	mA
Supply Current, Recessive	$I_{CC(REC)}$	$D = V_{CC}, RS = 0V$, no load, $3V \leq V_{CC} \leq 3.6V$	Full	-	2.6	5.0	mA
Cold Sparring Bus Current							
CANH Leakage Current	$I_{L(CANH)}$	$V_{CC} = 0.2V$, CANH = $-7V$ or $12V$, CANL = float, $D = V_{CC}$, $RS = 0V$	Full	-25	-4	25	μA
CANL Leakage Current	$I_{L(CANL)}$	$V_{CC} = 0.2V$, CANL = $-7V$ or $12V$, CANH = float, $D = V_{CC}$, $RS = 0V$	Full	-25	-4	25	μA
V_{REF} Leakage Current	$I_{L(VREF)}$	$V_{CC} = 0.2V$, $V_{REF} = -7V$ or $12V$, $D = V_{CC}$	Full	-25.00	0.01	25.00	μA
Driver Switching Characteristics							
Propagation Delay LOW to HIGH	t_{PDLH1}	$RS = 0V$, Figure 14 , Figure 15	Full	-	90	160	ns
Propagation Delay LOW to HIGH	t_{PDLH2}	$RS = 10k\Omega$, Figure 14 , Figure 15	Full	-	350	550	ns
Propagation Delay LOW to HIGH	t_{PDLH3}	$RS = 50k\Omega$, Figure 14 , Figure 15	Full	-	475	800	ns
Propagation Delay HIGH to LOW	t_{PDHL1}	$RS = 0V$, Figure 14 , Figure 15	Full	-	115	180	ns
Propagation Delay HIGH to LOW	t_{PDHL2}	$RS = 10k\Omega$, Figure 14 , Figure 15	Full	-	410	600	ns
Propagation Delay HIGH to LOW	t_{PDHL3}	$RS = 50k\Omega$, Figure 14 , Figure 15	Full	-	550	900	ns
Output Skew	t_{SKEW1}	$RS = 0V$, $(t_{PHL} - t_{PLH})$, Figure 15	Full	-	20	65	ns
	t_{SKEW2}	$RS = 10k\Omega$, $(t_{PHL} - t_{PLH})$, Figure 15	Full	-	60	275	ns
	t_{SKEW3}	$RS = 50k\Omega$, $(t_{PHL} - t_{PLH})$, Figure 15	Full	-	75	400	ns
Output Rise Time	t_{r1}	$RS = 0V$, (fast speed - 1Mbps) Figure 15	Full	15	30	85	ns
Output Fall Time	t_{f1}		Full	10	20	65	ns
Output Rise Time	t_{r2}	$RS = 10k\Omega$, (medium speed - 500kbps) Figure 15	Full	125	250	550	ns
Output Fall Time	t_{f2}		Full	100	250	425	ns

Test Conditions: $V_{CC} = 3V$ to $3.6V$. Typical values are at $T_A = +25^\circ C$ ^[1], unless otherwise specified ^[2]. **Boldface limits apply across the operating temperature range, $-55^\circ C$ to $+125^\circ C$; over a total ionizing dose of $75krad(Si)$ at $+25^\circ C$ with exposure at a low dose rate of $<10mrad(Si)/s$, and over a total ionizing dose of $100krad(Si)$ at $+25^\circ C$ with exposure of a high dose rate of $50krad(Si)/s$ to $300krad(Si)/s$.** (Cont.)

Parameter	Symbol	Test Conditions	Temp (°C)	Min ^[3]	Typ ^[1]	Max ^[3]	Unit
Output Rise Time	t_{r3}	RS = 50k Ω , (slow speed - 250kbps)	Full	200	360	800	ns
Output Fall Time	t_{f3}	Figure 15	Full	175	390	600	ns
Total Loop Delay, Driver Input to Receiver Output, Recessive to Dominant	$t_{(LOOP1)}$	RS = 0V, Figure 19, Figure 20	Full	-	140	225	ns
		RS = 10k Ω , Figure 19, Figure 20	Full	-	380	600	ns
		RS = 50k Ω , Figure 19, Figure 20	Full	-	500	800	ns
Total Loop Delay, Driver Input to Receiver Output, Dominant to Recessive	$t_{(LOOP2)}$	RS = 0V, Figure 19, Figure 20	Full	-	160	285	ns
		RS = 10k Ω , Figure 19, Figure 20	Full	-	450	700	ns
		RS = 50k Ω , Figure 19, Figure 20	Full	-	575	950	ns
Listen to Valid Dominant Time	t_{L-DOM}	Figure 21, Figure 22	Full	-	5	15	μs
Receiver Switching Characteristics							
Propagation Delay LOW to HIGH	t_{PLH}	Figure 17, Figure 18	Full	-	50	110	ns
Propagation Delay HIGH to LOW	t_{PHL}	Figure 17, Figure 18	Full	-	50	110	ns
Rx Skew	t_{SKEW1}	$ (t_{PHL} - t_{PLH}) $, Figure 17, Figure 18	Full	-	2	35	ns
Rx Rise Time	t_r	Figure 17, Figure 18	Full	-	2	-	ns
Rx Fall Time	t_f	Figure 17, Figure 18	Full	-	2	-	ns
VREF/RS Pin Characteristics							
VREF Pin Voltage	V_{REF}	$-5\mu A < I_{REF} < 5\mu A$	Full	$0.45 \times V_{CC}$	1.60	$0.55 \times V_{CC}$	V
		$-50\mu A < I_{REF} < 50\mu A$	Full	$0.4 \times V_{CC}$	1.6	$0.6 \times V_{CC}$	V
RS Pin Input Current	$I_{RS(H)}$	RS = $0.75 \times V_{CC}$	Full	-10.0	-0.2	-	μA
	$I_{RS(L)}$	$V_{RS} = 0V$	Full	-450	-125	0	μA

1. Typical values are at 3.3V. Parameters with a single entry in the TYP column apply to 3.3V. Typical values shown are not guaranteed.
2. All currents into device pins are positive; all currents out of device pins are negative. All voltages are referenced to device ground unless otherwise specified.
3. Parameters with MIN and/or MAX limits are 100% tested at $-55^\circ C$, $+25^\circ C$, and $+125^\circ C$, unless otherwise specified.
4. Parameter included in functional testing.

2.5 Test Circuits and Waveforms

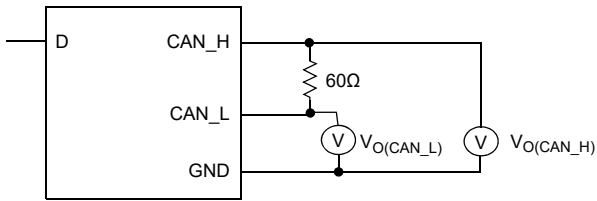


Figure 11. Driver Test Circuit

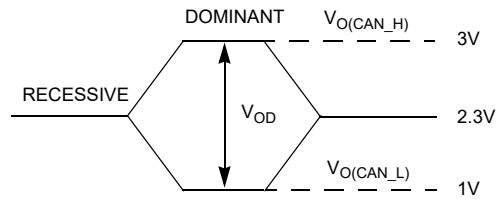


Figure 12. Driver Bus Voltage Definitions

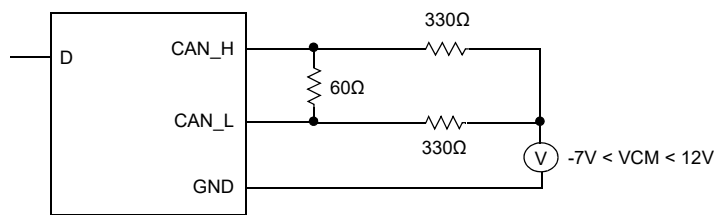
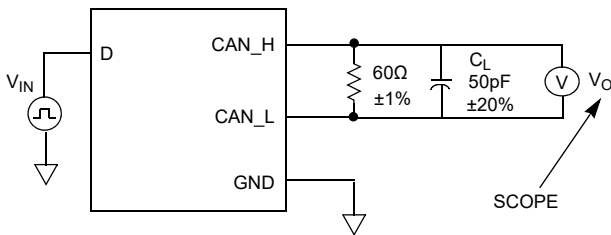


Figure 13. Driver Common-Mode Circuit



$V_{IN} = 125\text{kHz}$, 0V to V_{CC} , DUTY CYCLE 50%, $t_r = t_f \leq 6\text{ns}$, $Z_O = 50\Omega$
 C_L Includes Fixture and Instrumentation Capacitance

Figure 14. Driver Timing Test Circuit

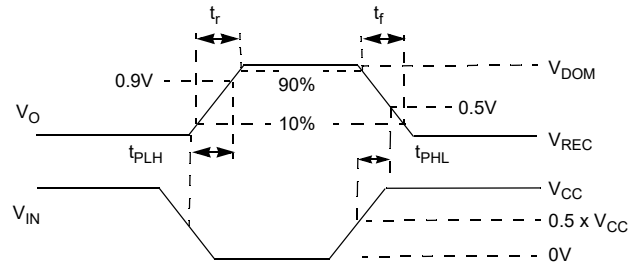


Figure 15. Driver Timing Measurement Points

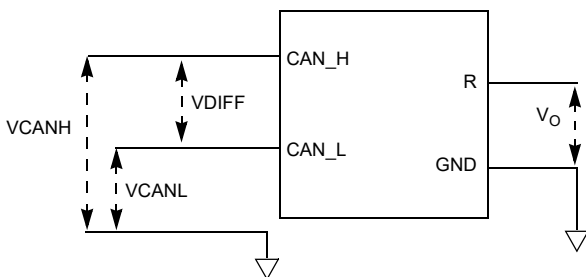
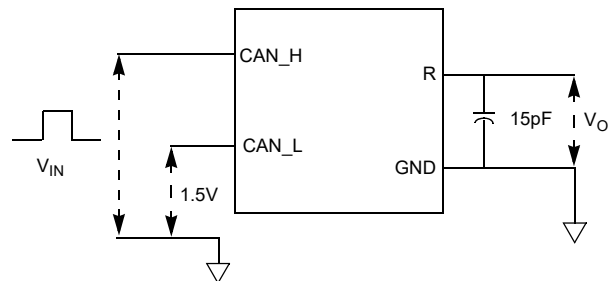


Figure 16. Receiver Voltage Definitions



$V_{IN} = 125\text{kHz}$, Duty Cycle 50%, $t_r = t_f = 6\text{ns}$, $Z_O = 50\Omega$
 C_L Includes Test Setup Capacitance

Figure 17. Receiver Test Circuit

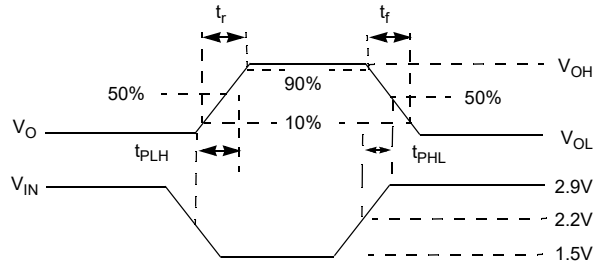


Figure 18. Receiver Test Measurement Points

Table 1. Differential Input Voltage Threshold Test

Input		Output	Measured
V _{CANH}	V _{CANL}	R	V _{DIFF}
-6.1V	-7V	L	900mV
12V	11.1V	L	900mV
-1V	-7V	L	6V
12V	6V	L	6V
-6.5V	-7V	H	500mV
12V	11.5V	H	500mV
-7V	-1V	H	6V
6V	12V	H	6V
Open	Open	H	X

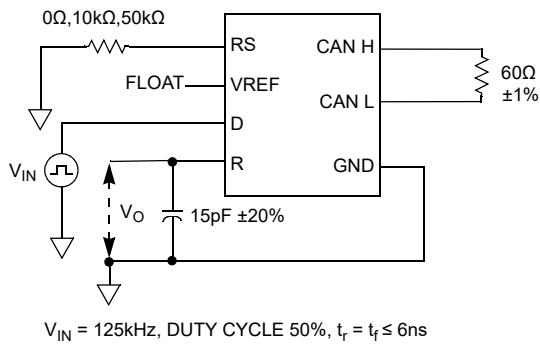


Figure 19. Total Loop Delay Test Circuit

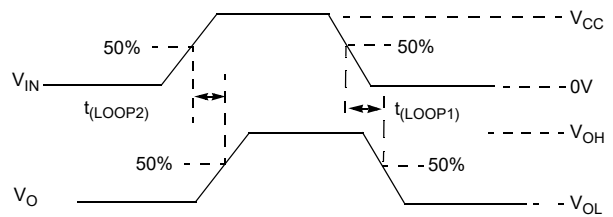
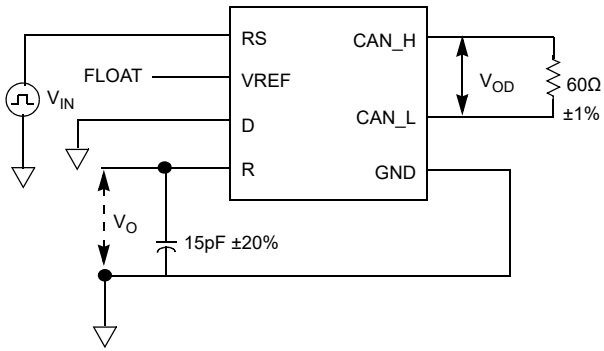


Figure 20. Total Loop Delay Measurement Points



$V_{IN} = 125\text{kHz}$, $0\text{V to } V_{CC}$, DUTY CYCLE 50%, $t_r = t_f \leq 6\text{ns}$

Figure 21. Listen to Valid Dominant Time Circuit

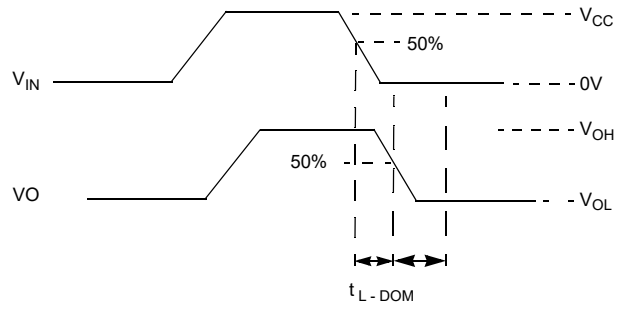


Figure 22. Listen to Valid Dominant Time Measurement Points

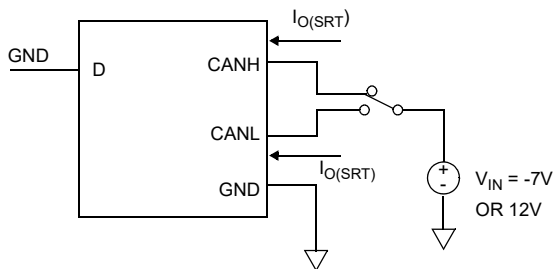


Figure 23. Output Short-Circuit Current Circuit

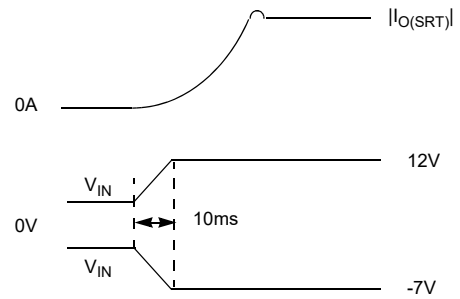


Figure 24. Output Short-Circuit Current Waveforms

3. Typical Performance Curves

$V_{CC} = 3.3V$, $CL = 15pF$, $TA = +25^{\circ}C$; unless otherwise specified.

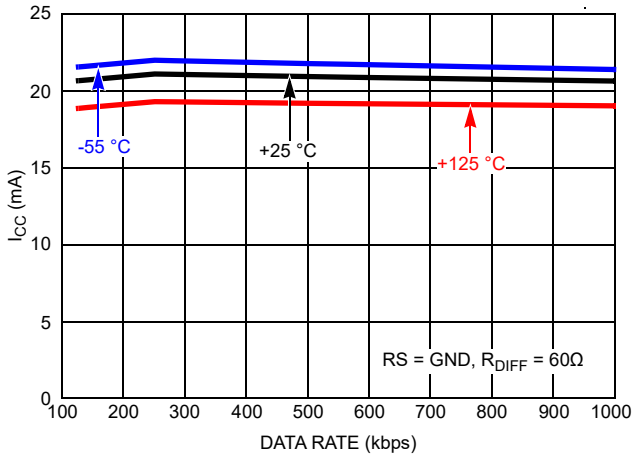


Figure 25. Supply Current vs Fast Data Rate vs Temperature

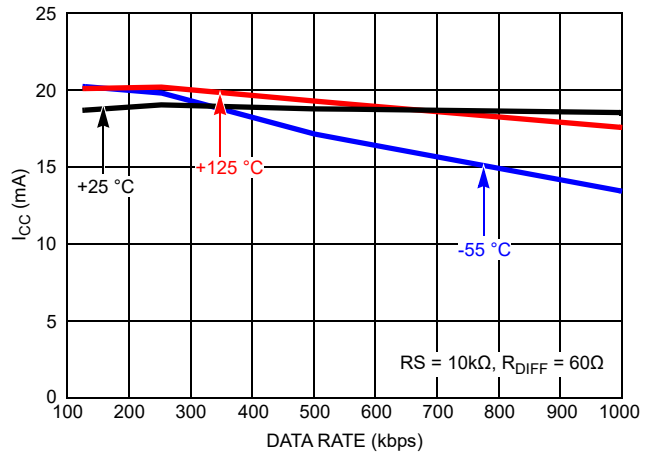


Figure 26. Supply Current vs Medium Data Rate vs Temperature

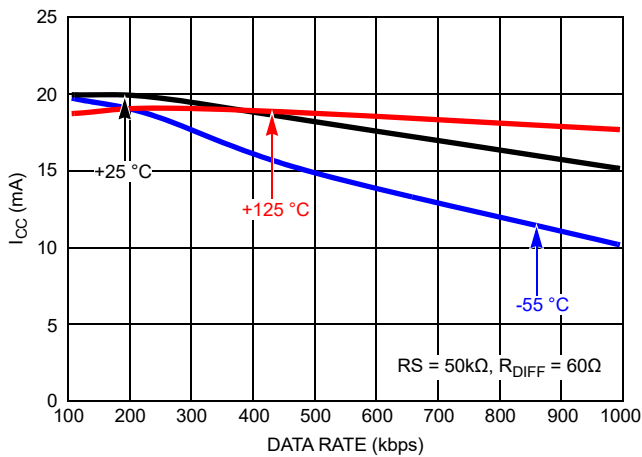


Figure 27. Supply Current vs Slow Data Rate vs Temperature

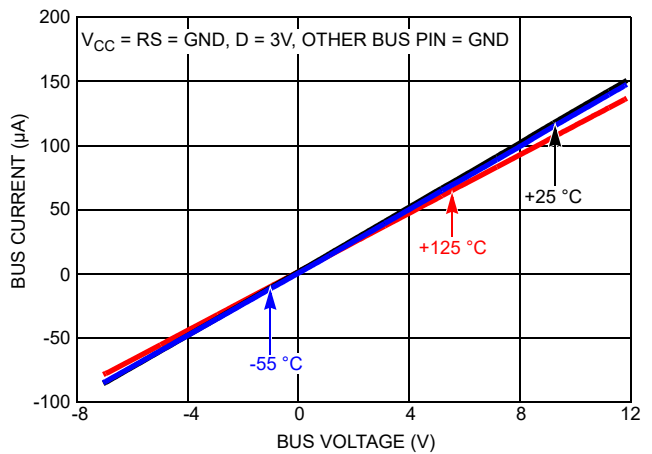


Figure 28. Bus Pin Leakage vs V_{CM} at $V_{CC} = 0V$

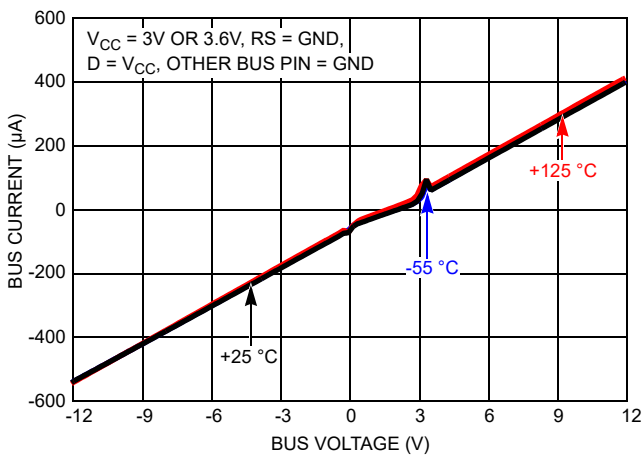


Figure 29. Bus Pin Leakage vs $\pm 12V V_{CM}$

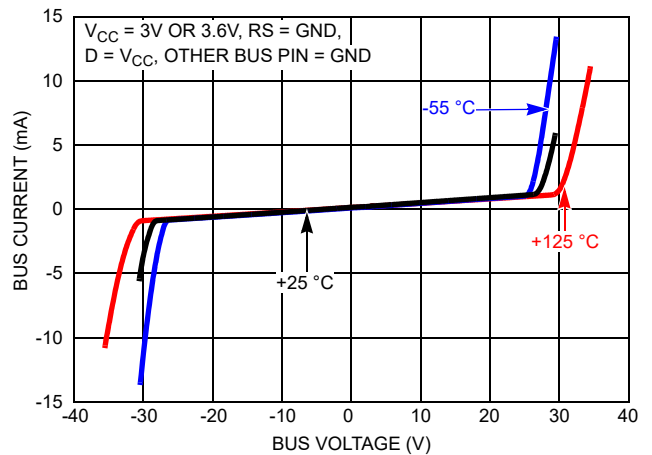


Figure 30. Bus Pin Leakage vs $\pm 35V V_{CM}$

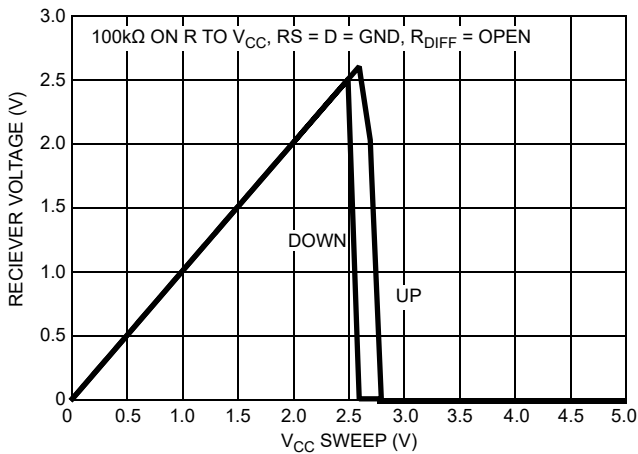


Figure 31. V_{CC} Undervoltage Lockout

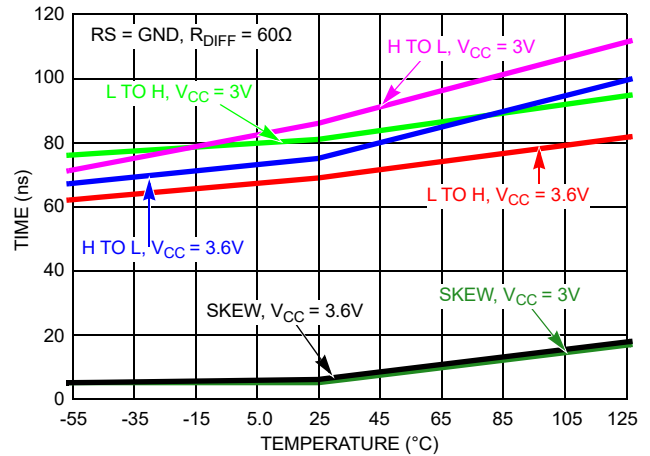


Figure 32. Transmitter Propagation Delay and Skew vs Temperature at Fast Speed

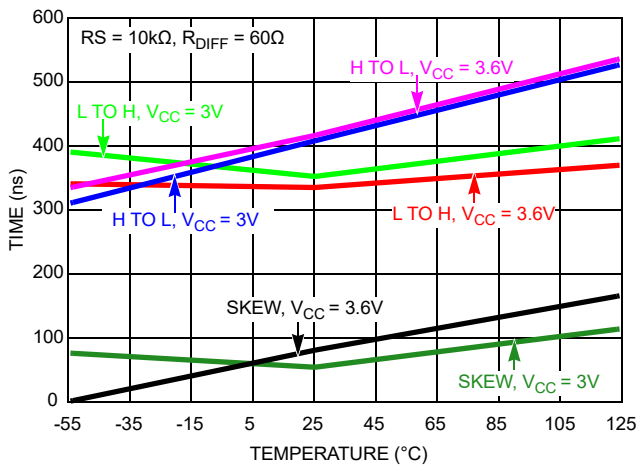


Figure 33. Transmitter Propagation Delay and Skew vs Temperature at Medium Speed

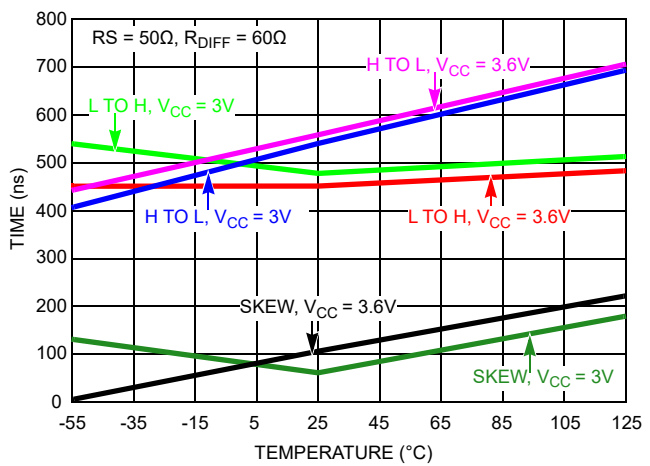


Figure 34. Transmitter Propagation Delay and Skew vs Temperature at Slow Speed

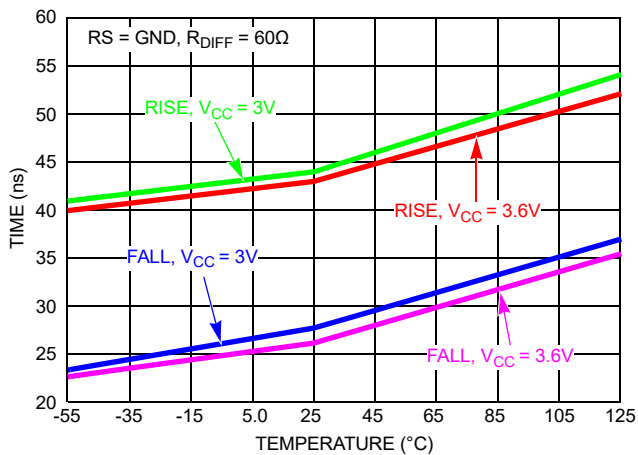


Figure 35. Transmitter Rise and Fall Times vs Temperature at Fast Speed

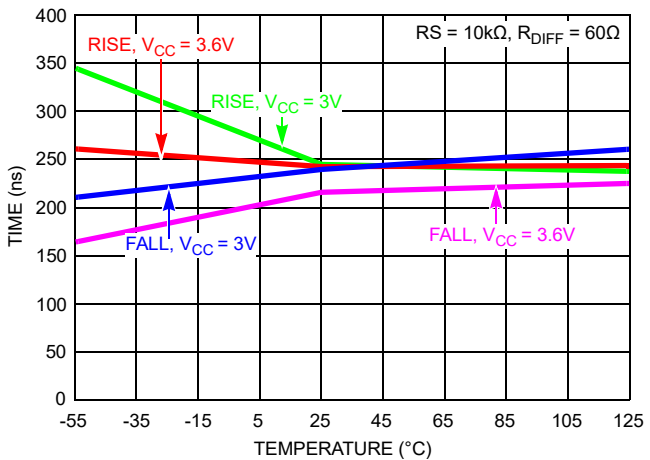


Figure 36. Transmitter Rise and Fall Times vs Temperature at Medium Speed

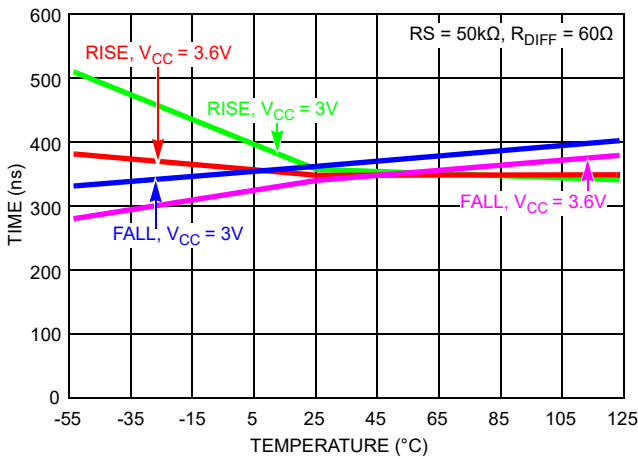


Figure 37. Transmitter Rise and Fall Times vs Temperature at Slow Speed

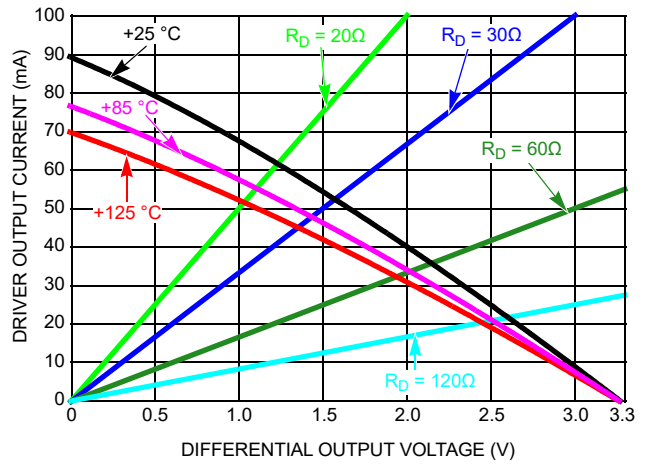


Figure 38. Driver Output Current vs Differential Output Voltage

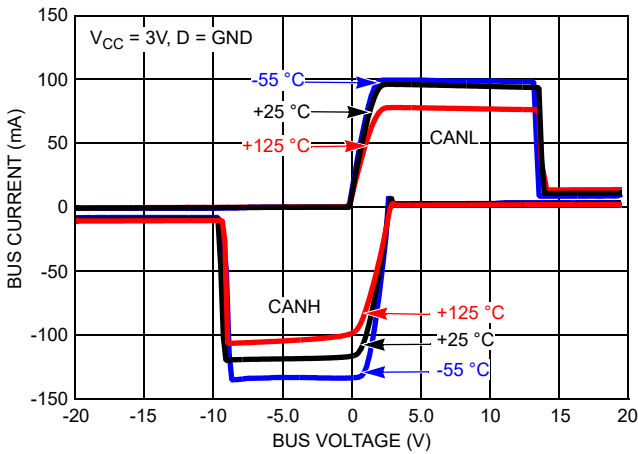


Figure 39. Driver Output Current vs Short-Circuit Voltage vs Temperature

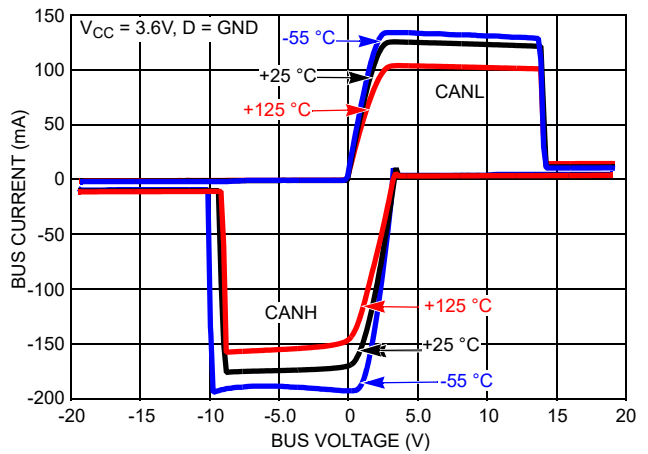


Figure 40. Driver Output Current vs Short-Circuit Voltage vs Temperature

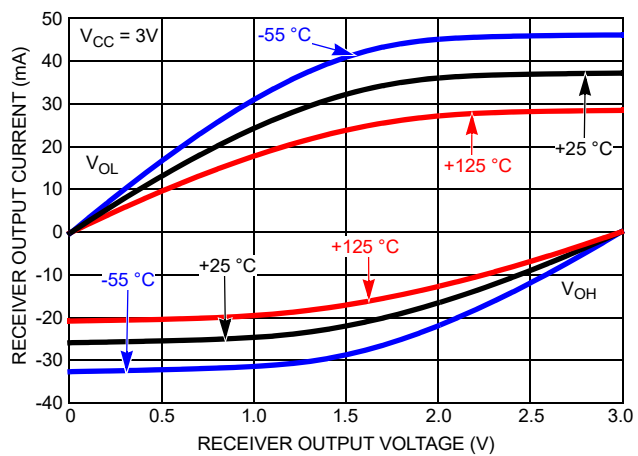


Figure 41. Receiver Output Current vs Receiver Output Voltage at $V_{CC} = 3V$

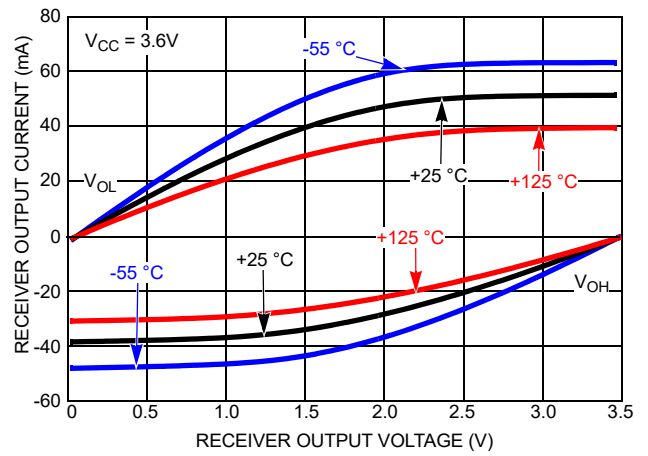


Figure 42. Receiver Output Current vs Receiver Output Voltage at $V_{CC} = 3.6V$

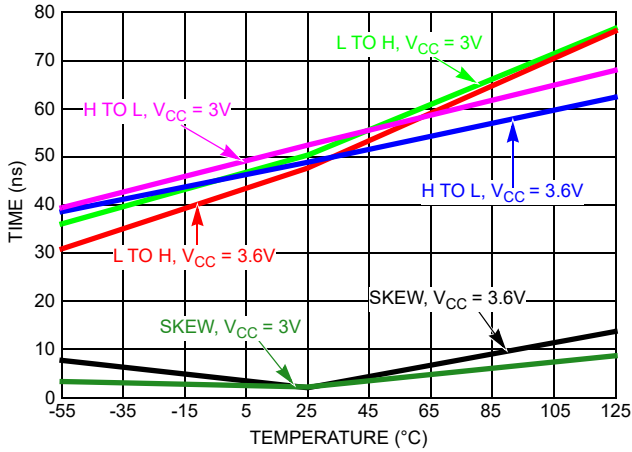


Figure 43. Receiver Propagation Delay and Skew vs Temperature

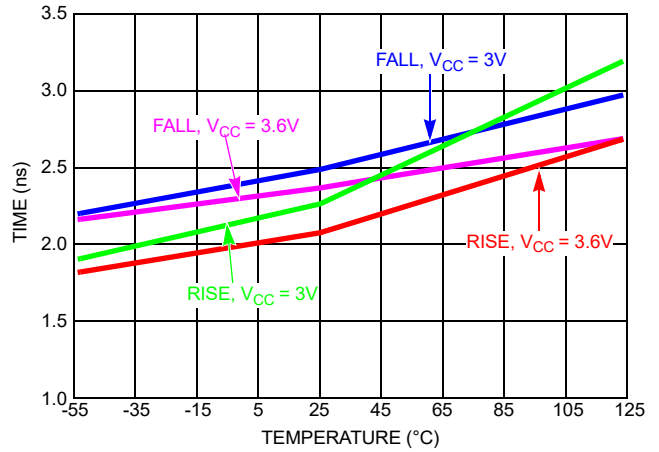


Figure 44. Receiver Rise and Fall Times vs Temperature

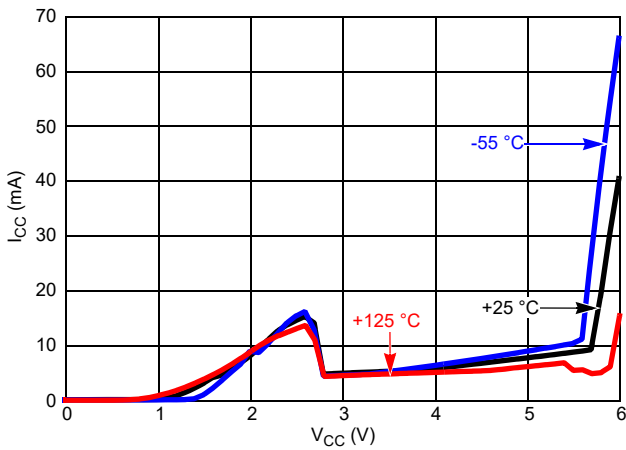


Figure 45. Supply Current vs Supply Voltage vs Temperature

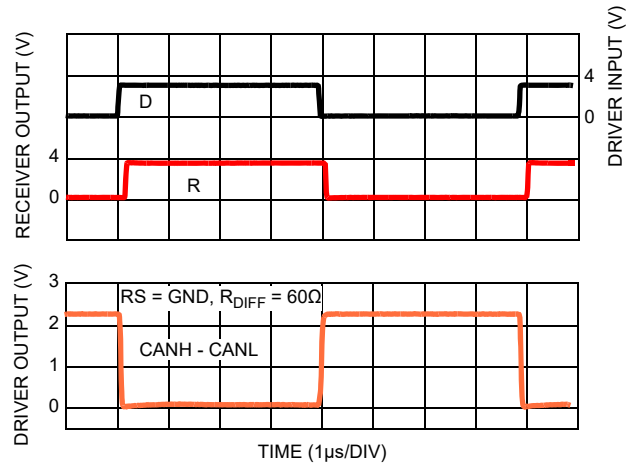


Figure 46. Fast Driver and Receiver Waveforms

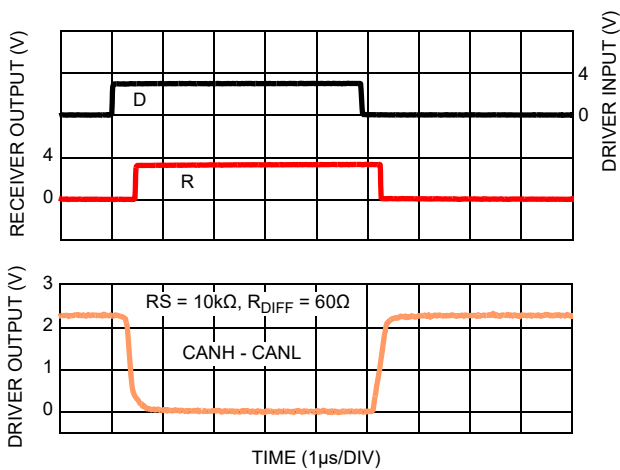


Figure 47. Medium Driver and Receiver Waveforms

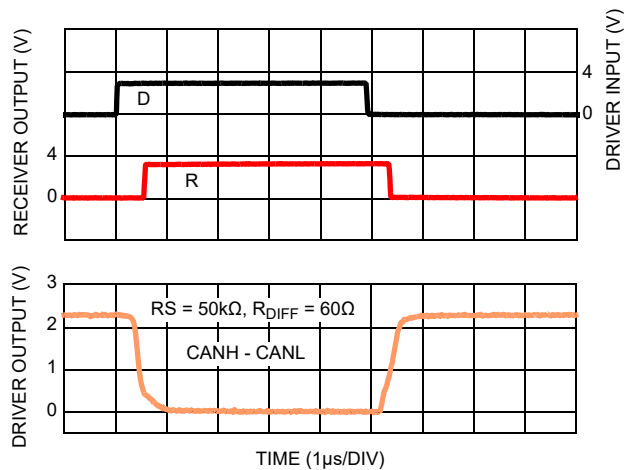


Figure 48. Slow Driver and Receiver Waveforms

4. Functional Description

4.1 Overview

The ISL72027CSEH is a 3.3V radiation hardened CAN transceiver compatible with the ISO11898-2 standard for use in Controller Area Network (CAN) serial communication systems.

The device performs transmit and receive functions between the CAN controller and the CAN differential bus. It can transmit and receive at bus speeds of up to 5Mbps. It is designed to operate across a common-mode range of -7V to +12V, with a maximum of 120 nodes. The device is capable of withstanding $\pm 20V$ on the CANH and CANL bus pins outside of ion beam and $\pm 16V$ under ion beam.

4.2 Slope Adjustment

The transceiver driver has three programmable rise/fall time options programmed by the resistor value connected from the RS pin to GND. A 0Ω resistor sets the part in Fast Speed mode. A resistor of $10k\Omega$ sets the part in Medium Speed mode. A resistor of $50k\Omega$ puts the part in Slow Speed mode. Putting a high logic level on the RS pin places the part in Listen mode. See [Listen Mode](#) for more information.

4.2.1 Fast Speed Mode

Connecting the RS pin directly to GND (0Ω resistor) results in the fastest driver output switching times, limited only by the drive capability of the output state. In Fast Speed mode ($RS = 0V$), the rise/fall times, propagation delays, and total loop delays are optimized for a data rate of 1Mbps.

4.2.2 Medium Speed Mode

In Medium Speed mode, ($RS = 10k\Omega$), the rise/fall times, propagation delays, and total loop delays have been optimized for a data rate of 500kbps. $RS = 10k\Omega$ provides for a typical slew rate of $12V/\mu s$. The slower edges in Medium Speed mode at 500kbps provide better EMI results than running at 1Mbps in Fast Speed mode.

4.2.3 Slow Speed Mode

In Slow Speed mode ($RS = 50k\Omega$), the rise/fall times, propagation delays, and total loop delays are optimized for a data rate of 250kbps. $RS = 50k\Omega$ provides for a typical slew rate of $8V/\mu s$. The slower edges in Slow Speed mode at 250kbps give better EMI results than running at 500kbps in Medium Speed mode.

4.3 Cable Length

The device can operate according to the ISO11898 specification with a 40m cable and stub length of 0.3m and 60 nodes at 1Mbps. This is greater than the ISO requirement of 30 nodes. The cable type specified is a twisted pair (shielded or unshielded) with a characteristic impedance of 120Ω . Resistors equal to this impedance are to be terminated at both ends of the cable. Stubs should be kept as short as possible to prevent reflections.

4.4 Cold Spare

To reduce the risk of a single-point failure, use redundant bus transceivers in parallel. Space systems call for high reliability in data communications that are resistant to single point failures. This is achieved by using a redundant bus transceiver in parallel. In this arrangement, both active and quiescent devices can be present simultaneously on the bus. The quiescent devices are powered down for cold spare and do not affect the communication of the other active nodes.

The powered down transceiver ($V_{CC} < 200mV$) has a resistance between the VREF pin or the CANH pin or CANL pin to the V_{CC} supply rail of $>480k\Omega$ (maximum) with a typical resistance $>2M\Omega$. The resistance between CANH and CANL of a powered down transceiver is typically $80k\Omega$. The receiver output (R pin) of a powered-down transceiver ($V_{CC} < 200mV$) is internally connected to ground. Therefore, the receiver outputs of an active transceiver and a cold spare transceiver cannot be connected together in the redundant application.

4.5 Listen Mode

When a high level is applied to the RS pin, the device enters Low Power Listen mode. The driver of the transceiver is switched off to conserve power while the receiver remains active. In Listen mode, the transceiver draws 2mA (maximum) of current.

A low level on the RS pin brings the device back to normal operation.

4.6 Using 3.3V Devices in 5V Systems

In both the 3.3V and 5V devices, the differential voltage is the same, and the recessive common-mode output is the same. The dominant common-mode output voltage for the 3.3V device is slightly lower than that of the 5V counterparts. The receiver specifications for both devices are also the same. Although the electrical parameters appear compatible, perform necessary system testing to verify interchangeable operation.

4.7 Split Mode Termination

The VREF pin provides a $V_{CC}/2$ output voltage for Split mode termination. The VREF pin has the same ESD protection, short-circuit protection, and common-mode operating range as the bus pins.

The Split mode termination technique is shown in [Figure 49](#).

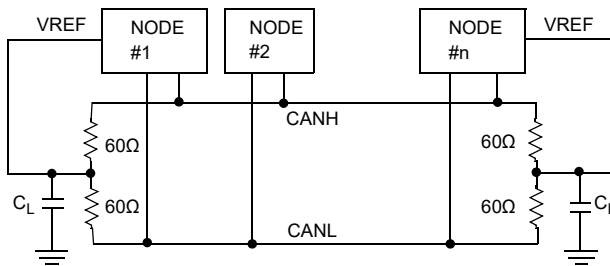


Figure 49. Split Termination

Split mode termination is used to stabilize the bus voltage at $V_{CC}/2$ and prevent it from drifting to a high common-mode voltage during periods of inactivity. The technique improves the electromagnetic compatibility of a network. The Split mode termination is put at each end of the bus.

The C_L capacitor between the two 60Ω resistors filters unwanted high frequency noise to ground. The resistors should have a tolerance of 1% or better and the two resistors should be carefully matched to provide the most effective EMI immunity. A typical value of C_L for a high speed CAN network is 4.7nF, which generates a 3dB point at 1.1Mbps. The capacitance value used is dependent on the signaling rate of the network.

5. Package and Die Characteristics

Table 2. Die and Assembly Related Information

Die Information	
Dimensions	2413 μ m x 3322 μ m (95 mils x 130.79 mils) Thickness: 305 μ m \pm 25 μ m (12 mils \pm 1 mil)
Interface Materials	
Glassivation	Type: 12k \AA Silicon Nitride on 3k \AA Oxide
Top Metallization	Type: 300 \AA TiN on 2.8 μ m AlCu In Bondpads, TiN has been removed.
Backside Finish	Silicon
Process	P6SOI
Assembly Information	
Substrate Potential	Floating
Additional Information	
Worst Case Current Density	1.6 x 10 ⁵ A/cm ²
Transistor Count	4055
Weight of Packaged Device	0.31 grams
Lid Characteristics	Finish: Gold Potential: Grounded, tied to package Pin 2

5.1 Metallization Mask Layout

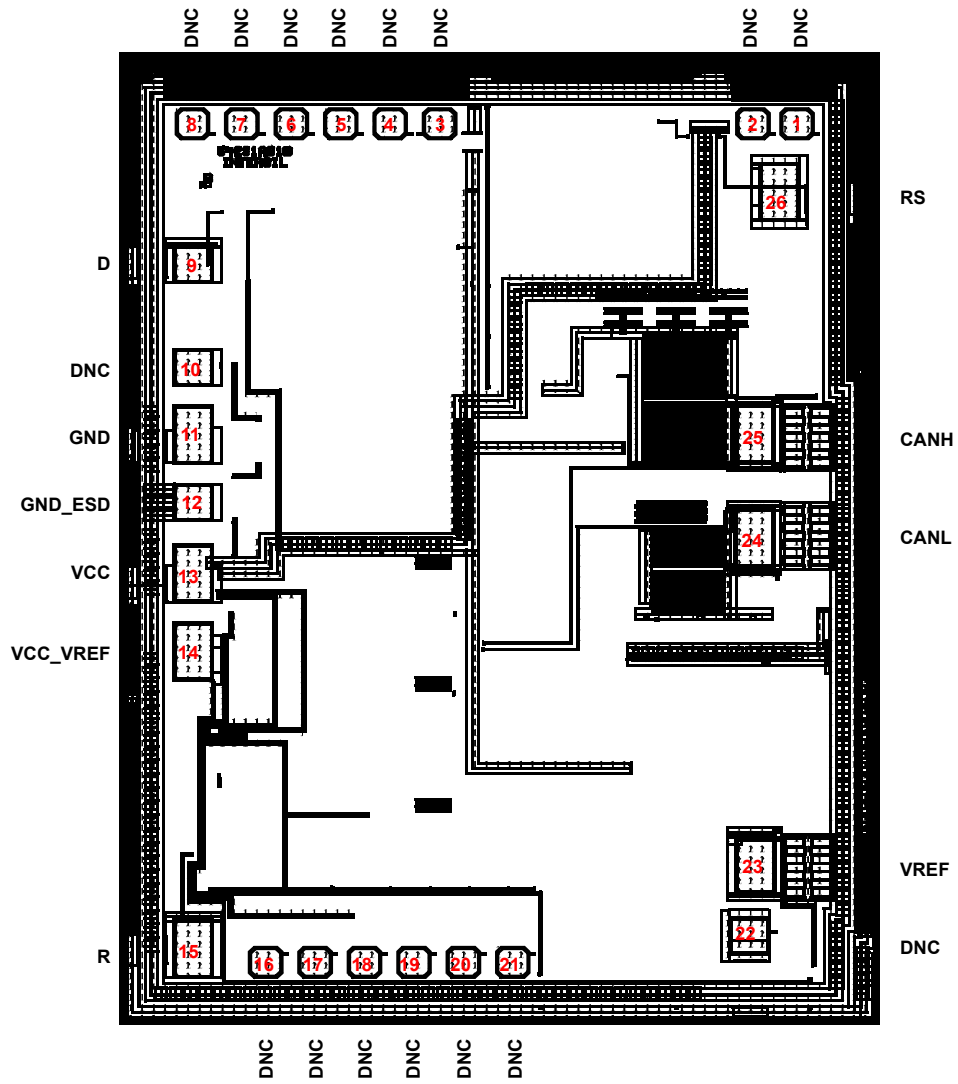


Table 3. ISL72027CSEH Die Layout X-Y Coordinates

Pad Number	Pad Name	X (μm)	Y (μm)	X	Y
1	DNC	90.0	90.0	901.4	1365.6
2	DNC	90.0	90.0	767.4	1365.6
3	DNC	90.0	90.0	-183.23	1365.6
4	DNC	90.0	90.0	-333.25	1365.6
5	DNC	90.0	90.0	-483.25	1365.6
6	DNC	90.0	90.0	-633.25	1365.6
7	DNC	90.0	90.0	-783.25	1365.6
8	DNC	90.0	90.0	-933.25	1365.6
9	D	110.0	110.0	-931.1	901.85
10	DNC	110.0	110.0	-931.1	563.25
11	GND	110.0	180.0	-931.1	342.25
12	GND_ESD	110.0	110.05	-931.1	119.42
13	VCC	110.0	180.0	-931.1	-115.05
14	VCC_VREF	110.0	180.05	-931.1	-371.08
15	R	110.0	180.0	-931.1	-1350.0
16	DNC	90.0	90.0	-711.1	-1394.95
17	DNC	90.0	90.0	-561.1	-1394.95
18	DNC	90.0	90.0	-411.1	-1394.95
19	DNC	90.0	90.0	-261.1	-1394.95
20	DNC	90.0	90.0	-111.1	-1394.95
21	DNC	90.0	90.0	38.9	-1394.95
22	DNC	110.0	110.0	756.9	-1307.3
23	VREF	110.0	180.0	775.3	-1072.3
24	CANL	110.0	180.0	772.1	2.15
25	CANH	110.0	180.05	772.1	343.33
26	RS	110.0	180.0	848.1	1140.6

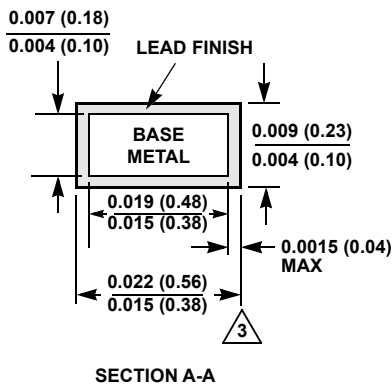
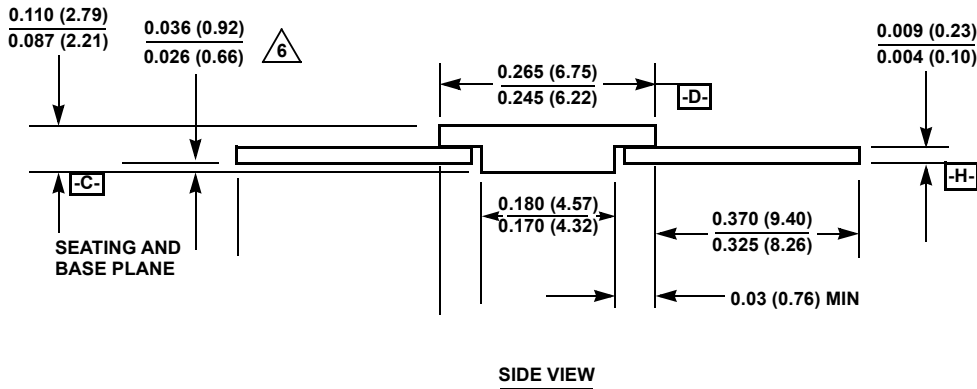
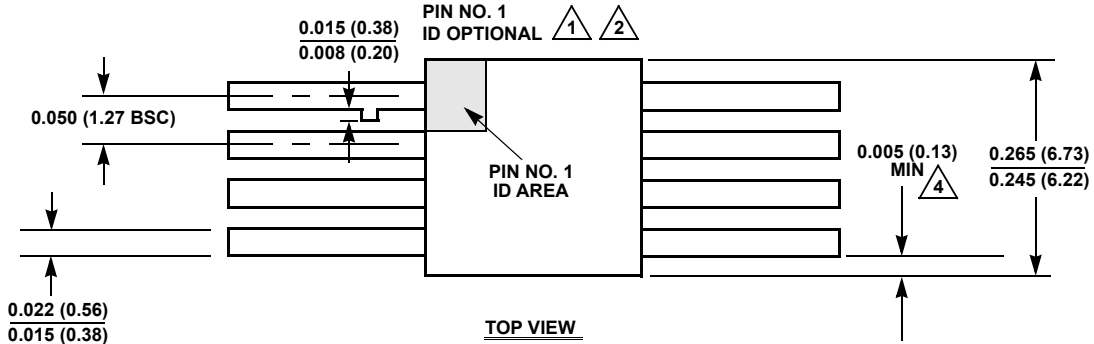
6. Package Outline Drawing

For the most recent package outline drawing, see [K8.A](#).

K8.A

8 Lead Ceramic Metal Seal Flatpack Package

Rev 4, 12/14



NOTES:

1. Index area: A notch or a pin one identification mark shall be located adjacent to pin one and shall be located within the shaded area shown. The manufacturer's identification shall not be used as a pin one identification mark. Alternately, a tab may be used to identify pin one.
2. If a pin one identification mark is used in addition to or instead of a tab, the limits of the tab dimension do not apply.
3. The maximum limits of lead dimensions (section A-A) shall be measured at the centroid of the finished lead surfaces, when solder dip or tin plate lead finish is applied.
4. Measure dimension at all four corners.
5. For bottom-brazed lead packages, no organic or polymeric materials shall be molded to the bottom of the package to cover the leads.
6. Dimension shall be measured at the point of exit (beyond the meniscus) of the lead from the body. Dimension minimum shall be reduced by 0.0015 inch (0.038mm) maximum when solder dip lead finish is applied.
7. Dimensioning and tolerancing per ANSI Y14.5M - 1982.
8. Controlling dimension: INCH.

7. Ordering Information

Ordering/SMD Number ^[1]	Part Number ^[2]	Radiation Hardness (Total Ionizing Dose)	Package Description (RoHS Compliant)	Pkg. Dwg. #	Temp Range
5962R1522811VXC	ISL72027CSEHVF	HDR to 100krad(Si) LDR to 75krad(Si)	8 Ld Ceramic Flatpack	K8.A	-55 to +125(°C)
N/A	ISL72027CSEHF/PROTO ^[3]	N/A			
5962R1522811V9A	ISL72027CSEHVX ^[4]	HDR to 100krad(Si) LDR to 75krad(Si)	Die	--	
N/A	ISL72027CSEHX/SAMPLE ^{[3][4]}	N/A			
N/A	ISL72027CSEHEVAL1Z ^[5]	Evaluation Board			

- Specifications for Radiation Tolerant QML devices are controlled by the Defense Logistics Agency Land and Maritime (DLA). The SMD numbers listed must be used when ordering.
- These Pb-free Hermetic packaged products employ 100% Au plate -e4 termination finish, which is RoHS compliant and compatible with both SnPb and Pb-free soldering operations.
- The /PROTO and /SAMPLE are not rated or certified for Total Ionizing Dose (TID) or Single Event Effect (SEE) immunity. These parts are intended for engineering evaluation purposes only. The /PROTO parts meet the electrical limits and conditions over-temperature specified in the DLA SMD and are in the same form and fit as the qualified device. The /SAMPLE die is capable of meeting the electrical limits and conditions specified in the DLA SMD at +25°C only. The /SAMPLE is a die and does not receive 100% screening over-temperature to the DLA SMD electrical limits. These part types do not come with a Certificate of Conformance because there is no Radiation Assurance testing and they are not DLA qualified devices.
- Die product tested at $T_A = +25^\circ\text{C}$. The wafer probe test includes functional and parametric testing sufficient to make the die capable of meeting the electrical performance outlined in [Electrical Specifications](#).
- Evaluation boards utilize the /PROTO parts and /PROTO parts are not rated or certified for Total Ionizing Dose (TID) or Single Event Effect (SEE) immunity.

Table 4. ISL7202xCSEH Product Family Feature Table

Specification	ISL72026CSEH	ISL72027CSEH	ISL72028CSEH
Loopback Feature	Yes	No	No
VREF Output	No	Yes	Yes
Listen Mode	Yes	Yes	No
Shutdown Mode	No	No	Yes
VTHRLM	900mV (maximum)	900mV (maximum)	N/A
VTHFLM	325mV (minimum)	325mV (minimum)	N/A
VHYSLM	40mV (minimum)	40mV (minimum)	N/A
Supply Current, Listen Mode	2mA (maximum)	2mA (maximum)	N/A
Supply Current, Shutdown Mode	N/A	N/A	50µA (maximum)
VREF Leakage Current	N/A	±25µA (maximum)	±25µA (maximum)

Table 5. Product Family Comparison for Optimal Data Rate and Total Dose Radiation Testing

Specification	ISL7202xSEH	ISL7202xASEH	ISL7202xBSEH	ISL7202xCSEH
Data Rate: RS = 0V	1Mbps	1Mbps	1Mbps	1Mbps
Data Rate: RS = 10kΩ	250kbps	500kbps	250kbps	500kbps
Data Rate: RS = 50kΩ	125kbps	250kbps	125kbps	250kbps
High Dose Rate (HDR) -100krad(Si) Testing	No	No	Yes	Yes
Low Dose Rate (LDR) -75krad(Si) Testing	Yes	Yes	Yes	Yes

8. Revision History

Rev.	Date	Description
1.01	Oct 26, 2023	Applied latest template and formatting. Updated the "Pin Descriptions" table on page 4: Change Pin 6 name to CANL and Pin 7 name to CANH to match the Pin Configuration diagram. On page 10 for Output Rise Time tr2 and Output Fall Time tf2 changed the Test Condition From: (medium speed - 50000kbps), To: (medium speed - 500kbps). Removed Related Literature section. Updated the ordering information table: Added Radiation information; Added Note 4.
1.00	Aug 11, 2017	Page 10: Changed the limit for Propagation Delay High to Low t _{PDHL2} from 650ns to 600ns. Page 10: Changed the limit for Total Loop Delay, Driver Input to Receiver Output, Dominant to Recessive t _(LOOP2) for RS = 10kΩ from 750ns to 700ns.
0.00	Apr 3, 2017	Initial Release

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