ISL72028BSEH

3.3V Radiation Tolerant CAN Transceiver, with Low-Power Shutdown, Split Termination Output

FN8902
Rev 0.00
November 30, 2016

The ISL72028BSEH is a radiation tolerant 3.3V CAN transceiver that is compatible with the ISO11898-2 standard for applications calling for Controller Area Network (CAN) serial communication in satellites and aerospace communications, and telemetry data processing in harsh industrial environments.

The transceiver can transmit and receive at bus speeds up to 5Mbps. It can drive a 40m cable at 1Mbps per the ISO11898-2 specification. It was designed to operate over a common-mode range of -7V to +12V with a maximum of 120 nodes. The device has three discrete selectable driver rise/fall time options, a Low-Power Shutdown mode and a split termination output.

Receiver (Rx) inputs feature a “full fail-safe” design, which ensures a logic high Rx output if the Rx inputs are floating, shorted, or terminated but undriven.

The ISL72028BSEH is available in an 8 Ld hermetic ceramic flatpack and die form that operate across the temperature range of -55°C to +125°C. The logic inputs are tolerant with 5V systems.

Other CAN transceivers available are the ISL72026BSEH and ISL72027BSEH. For a list of differences see Table 1 on page 2.

Related Literature

- For a full list of related documents, visit our website
  - ISL72028BSEH product page

Applications

- Satellites and aerospace communications
- Telemetry data processing
- High-end industrial environments
- Harsh environments

Features

- Electrically screened to SMD 5962-15228
- ESD protection on all pins . . . . . 4kV HBM
- Compatible with ISO11898-2
- Operating supply range . . . . . 3.0V to 3.6V
- Bus pin fault protection to ±20V
- Undervoltage lockout
- Cold spare: powered-down devices/nodes will not affect active devices operating in parallel
- Three selectable driver rise and fall times
- Glitch free bus I/O during power-up and power-down
- Full fail-safe (open, short, terminated/undriven) receiver
- Hi-Z input allows for 120 nodes on the bus
- High data rates . . . . . up to 5Mbps
- Quiescent supply current . . . . . 7mA (maximum)
- Low-Power Shutdown mode . . . . . 50µA (maximum)
- -7V to +12V common-mode input voltage range
- 5V tolerant logic inputs
- Thermal shutdown
- Acceptance tested to 75krad(Si) (LDR) wafer-by-wafer
- Radiation tolerance
  - SEL/B immune to LET_{TH} . . . . . 86.4MeV•cm^2/mg
  - Low dose rate (0.01rad(Si)/s) . . . . . 75krad(Si)
  - High dose rate (50-300rad(Si)/s). . . . . 100krad(Si)

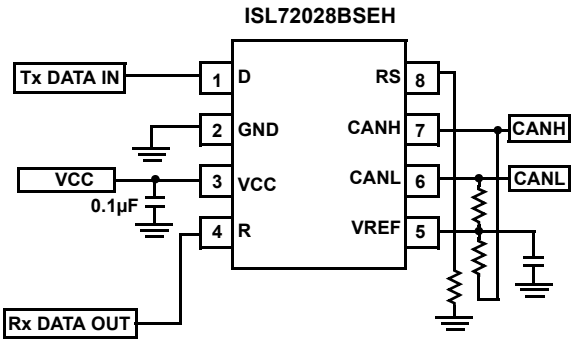


FIGURE 1. TYPICAL APPLICATION

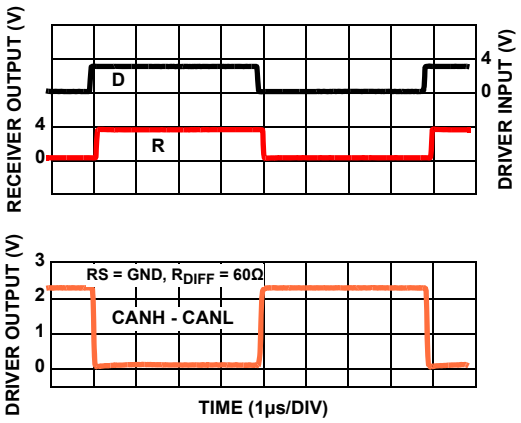


FIGURE 2. FAST DRIVER AND RECEIVER WAVEFORMS

Ordering Information

ORDERING SMD NUMBER (Note 1)	PART NUMBER (Note 2)	TEMPERATURE RANGE (°C)	PACKAGE (RoHS COMPLIANT)	PKG DWG #
5962R1522806VXC	ISL72028BSEHVF	-55 to +125	8 Ld Ceramic Flatpack	K8.A
N/A	ISL72028BSEHF/PROTO, Note 3	-55 to +125	8 Ld Ceramic Flatpack	K8.A
5962R1522806V9A	ISL72028BSEHVX	-55 to +125	Die	
N/A	ISL72028BSEHX/SAMPLE, Note 3	-55 to +125	Die	
N/A	ISL72028BSEHEVAL1Z	Evaluation Board		

NOTES:

1. Specifications for radiation tolerant QML devices are controlled by the Defense Logistics Agency Land and Maritime (DLA). The SMD numbers listed must be used when ordering.
2. These Pb-free Hermetic packaged products employ 100% Au plate - e4 termination finish, which is RoHS compliant and compatible with both SnPb and Pb-free soldering operations.
3. The /PROTO and /SAMPLE (Die) have no traceability and are intended for engineering evaluation purposes only. The /PROTO part meets the electrical limits and conditions across temperature (-55°C to +125°C) specified in the datasheet or DLA SMD and is in the same form and fit as the flight devices (Class V parts). The SAMPLE die is capable of meeting the electrical limits and conditions specified in the data sheet or DLA SMD. The /SAMPLE is a die and as such, does not receive 100% screening over temperature to the datasheet or DLA SMD requirements so, some level of fallout should be expected. These part types do not come with a Certificate of Conformance because there is no Radiation Assurance testing or items such as TCI/QCI, Burn-in, X-ray, SEM, etc.

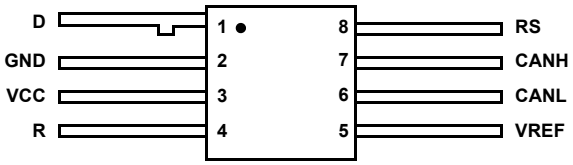
TABLE 1. ISL7202xBSEH PRODUCT FAMILY FEATURES TABLE

SPECIFICATION	ISL72026BSEH	ISL72027BSEH	ISL72028BSEH
Loopback Feature	Yes	No	No
VREF Output	No	Yes	Yes
Listen Mode	Yes	Yes	No
Shutdown Mode	No	No	Yes
VTHRLM	1150mV (Maximum)	1150mV (Maximum)	N/A
VTHFLM	525mV (Minimum)	525mV (Minimum)	N/A
VHYSLM	50mV (Minimum)	50mV (Minimum)	N/A
Supply Current, Listen Mode	2mA (Maximum)	2mA (Maximum)	N/A
Supply Current, Shutdown Mode	N/A	N/A	50µA (Maximum)
VREF Leakage Current	N/A	±25µA (Maximum)	±25µA (Maximum)

N/A: Not Applicable

Pin Configuration

ISL72028BSEH
(8 LD CERAMIC FLATPACK)
TOP VIEW



Note: The package lid is tied to ground.

Pin Descriptions

PIN #	PIN NAME	FUNCTION
1	D	CAN driver digital input. The bus states are LOW = Dominant and HIGH = Recessive. Internally tied HIGH.
2	GND	Ground connection.
3	VCC	System power supply input (3.0V to 3.6V). The typical voltage for the device is 3.3V.
4	R	CAN data receiver output. The bus states are LOW = Dominant and HIGH = Recessive.
5	VREF	VCC/2 reference output for split mode termination.
6	CANL	CAN bus line for high-level output.
7	CANH	CAN bus line for low-level output.
8	RS	A resistor to GND from this pin controls the rise and fall time of the CAN output waveform. Drive RS HIGH to put into low power shutdown.

Equivalent Input and Output Schematic Diagrams

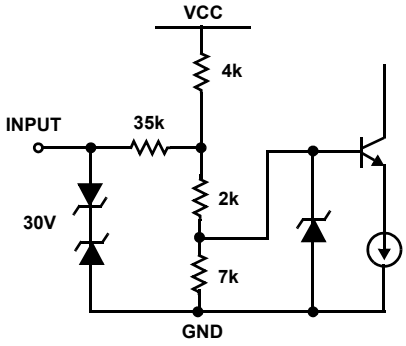


FIGURE 3. CANH AND CANL INPUTS

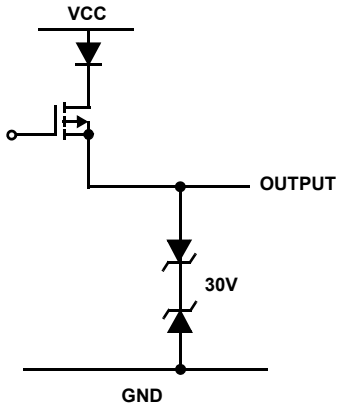


FIGURE 4. CANH OUTPUT

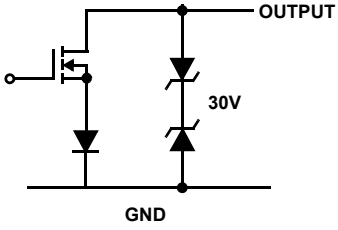


FIGURE 5. CANL OUTPUT

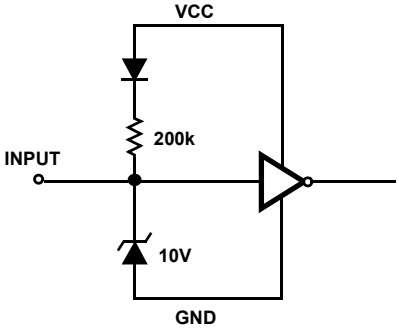


FIGURE 6. D INPUT

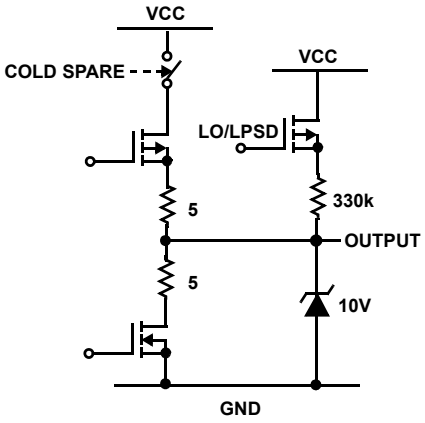


FIGURE 7. R OUTPUT

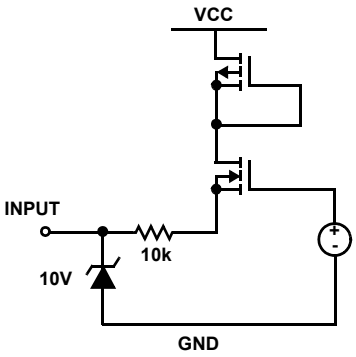


FIGURE 8. RS INPUT

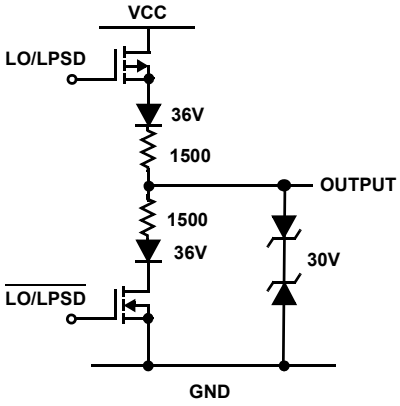


FIGURE 9. VREF

Absolute Maximum Ratings

VCC to GND With/Without Ion Beam . . . . . -0.3V to 5.5V
CANH, CANL, VREF Under Ion Beam . . . . . ±18V
CANH, CANL, VREF . . . . . ±20V
I/O Voltages
D, R, RS . . . . . -0.5V to 7V
Receiver Output Current . . . . . -10mA to 10mA
Output Short-Circuit Duration . . . . . Continuous
ESD Rating:
Human Body Model
CANH, CANL Bus Pins (Tested per MIL-PRF-883 3015.7) 4kV
All Other Pins (Tested per MIL-PRF-883 3015.7) 4kV
Charged Device Model (Tested per JESD22-C101D) 750V
Machine Model (Tested per JESD22-A115-A) 200V

Thermal Information

Thermal Resistance (Typical)	θ_{JA} (°C/W)	θ_{JC} (°C/W)
8 Ld FP Package (Notes 4, 5)	39	7

Maximum Junction Temperature . . . . . +175°C
Storage Temperature Range . . . . . -65°C to +150°C

Recommended Operating Conditions

Temperature Range . . . . . -55°C to +125°C
V_{CC} Supply Voltage . . . . . 3.0V to 3.6V
Voltage on CAN I/O . . . . . -7V to 12V
V_{IH} D Logic Pin . . . . . 2V to 5.5V
V_{IL} D Logic Pin . . . . . 0V to 0.8V
I_{OH} Driver (CANH - CANL = 1.5V, V_{CC} = 3.3V) . . . . . - 40mA
I_{OH} Receiver (V_{OH} = 2.4V) . . . . . -4mA
I_{OL} Driver (CANH - CANL = 1.5V, V_{CC} = 3.3V) . . . . . +40mA
I_{OL} Receiver (V_{OL} = 0.4V) . . . . . +4mA

CAUTION: Do not operate at or near the maximum ratings listed for extended periods of time. Exposure to such conditions may adversely impact product reliability and result in failures not covered by warranty.

NOTES:

4. θ_{JA} is measured with the component mounted on a high-effective thermal conductivity test board (two buried 1oz copper planes) with "direct attach" features package base mounted to PCB thermal land with a 10 mil gap fill material having a k of 1W/m-K. See Tech Brief TB379.
5. For θ_{JC}, the "case temp" location is the center of the package underside.

Electrical Specifications

Test Conditions: V_{CC} = 3.0V to 3.6V; typicals are at T_A = +25°C (Note 8); unless otherwise specified (Note 6). **Boldface limits apply across the operating temperature range, -55°C to +125°C; over a total ionizing dose of 75krad(Si) at +25°C with exposure at a low dose rate of <10mrad(Si)/s; and over a total ionizing dose of 100krad(Si) at +25°C with exposure of a high dose rate of 50krad(Si)/s. to 300krad(Si)/s.**

PARAMETER	SYMBOL	TEST CONDITIONS		TEMP (°C)	MIN (Note 7)	TYP (Note 8)	MAX (Note 7)	UNIT
DRIVER ELECTRICAL CHARACTERISTICS								
Dominant Bus Output Voltage	$V_{O(DOM)}$	D = 0V, CANH, RS = 0V, Figures 10 and 11	3.0V ≤ V_{CC} ≤ 3.6V	Full	**2.25**	2.85	**V_{CC}**	V
		D = 0V, CANL, RS = 0V, Figures 10 and 11		Full	**0.10**	0.65	**1.25**	V
Recessive Bus Output Voltage	$V_{O(REC)}$	D = 3V, CANH, RS = 0V, 60Ω and no load, Figures 10 and 11	3.0V ≤ V_{CC} ≤ 3.6V	Full	**1.80**	2.30	**2.70**	V
		D = 3V, CANL, RS = 0V, 60Ω and no load, Figures 10 and 11		Full	**1.80**	2.30	**2.80**	V
Dominant Output Differential Voltage	$V_{OD(DOM)}$	D = 0V, RS = 0V, 3.0V ≤ V_{CC} ≤ 3.6V, Figures 10 and 11		Full	**1.5**	2.2	**3.0**	V
		D = 0V, RS = 0V, 3.0V ≤ V_{CC} ≤ 3.6V, Figures 11 and 12		Full	**1.2**	2.1	**3.0**	V
Recessive Output Differential Voltage	$V_{OD(REC)}$	D = 3V, RS = 0V, 3.0V ≤ V_{CC} ≤ 3.6V, Figures 10 and 11		Full	**-120**	0.2	**12**	mV
		D = 3V, RS = 0V, 3.0V ≤ V_{CC} ≤ 3.6V, no load		Full	**-500**	-34	**50**	mV
Logic Input High Voltage (D)	V_{IH}	3.0V ≤ V_{CC} ≤ 3.6V, Note 9		Full	**2.0**	-	**5.5**	V
Logic Input Low Voltage (D)	V_{IL}	3.0V ≤ V_{CC} ≤ 3.6V, Note 9		Full	**0**	-	**0.8**	V
High-Level Input Current (D)	I_{IH}	D = 2.0V, 3.0V ≤ V_{CC} ≤ 3.6V		Full	**-30**	-3	**30**	µA
Low-Level Input Current (D)	I_{IL}	D = 0.8V, 3.0V ≤ V_{CC} ≤ 3.6V		Full	**-30**	-7	**30**	µA
RS Input Voltage for Low-Power Shutdown Mode	$V_{IN(RS)}$	3.0V ≤ V_{CC} ≤ 3.6V		Full	**0.75 x V_{CC}**	1.9	**5.5**	V

Electrical Specifications

Test Conditions: V_{CC} = 3.0V to 3.6V; typicals are at T_A = +25°C (Note 8); unless otherwise specified (Note 6). **Boldface limits apply across the operating temperature range, -55°C to +125°C; over a total ionizing dose of 75krad(Si) at +25°C with exposure at a low dose rate of <10mrad(Si)/s; and over a total ionizing dose of 100krad(Si) at +25°C with exposure of a high dose rate of 50krad(Si)/s. to 300krad(Si)/s. (Continued)**

PARAMETER	SYMBOL	TEST CONDITIONS	TEMP (°C)	MIN (Note 7)	TYP (Note 8)	MAX (Note 7)	UNIT
Output Short-Circuit Current	I_{OSC}	V_{CANH} = -7V, CANL = OPEN, 3.0V ≤ V_{CC} ≤ 3.6V, Figure 17	Full	**-250**	-100	-	mA
		V_{CANH} = +12V, CANL = OPEN, 3.0V ≤ V_{CC} ≤ 3.6V, Figure 17	Full	-	0.4	**1.0**	mA
		V_{CANL} = -7V, CANH = OPEN, 3.0V ≤ V_{CC} ≤ 3.6V, Figure 17	Full	**-1.0**	-0.4	-	mA
		V_{CANL} = +12V, CANH = OPEN, 3.0V ≤ V_{CC} ≤ 3.6V, Figure 17	Full	-	100	**250**	mA
Thermal Shutdown Temperature	T_{SHDN}	3.0V < V_{IN} < 3.6V	-	-	163	-	°C
Thermal Shutdown Hysteresis	T_{HYS}	3.0V < V_{IN} < 3.6V	-	-	12	-	°C
RECEIVER ELECTRICAL CHARACTERISTICS							
Input Threshold Voltage (Rising)	V_{THR}	RS = 0V, 10k, 50k, (recessive to dominant), Figures 14 and 15	Full	-	750	**900**	mV
Input Threshold Voltage (Falling)	V_{THF}	RS = 0V, 10k, 50k, (dominant to recessive), Figures 14 and 15	Full	**500**	650	-	mV
Input Hysteresis	V_{HYS}	(V_{THR} - V_{THF}), RS = 0V, 10k, 50k, Figures 14 and 15	Full	**40**	90	-	mV
Receiver Output High Voltage	V_{OH}	I_O = -4mA	Full	**2.4**	V_{CC} - 0.2	-	V
Receiver Output Low Voltage	V_{OL}	I_O = +4mA	Full	-	0.2	**0.4**	V
Input Current for CAN Bus	I_{CAN}	CANH or CANL at 12V, D = 3V, other bus pin at 0V, RS = 0V	Full	-	420	**500**	µA
		CANH or CANL at 12V, D = 3V, V_{CC} = 0V, other bus pin at 0V, RS = 0V	Full	-	150	**250**	µA
		CANH or CANL at -7V, D = 3V, other bus pin at 0V, RS = 0V	Full	**-400**	-300	-	µA
		CANH or CANL at -7V, D = 3V, V_{CC} = 0V, other bus pin at 0V, RS = 0V	Full	**-150**	-85	-	µA
Input Capacitance (CANH or CANL)	C_{IN}	Input to GND, D = 3V, RS = 0V	25	-	35	-	pF
Differential Input Capacitance	C_{IND}	Input to input, D = 3V, RS = 0V	25	-	15	-	pF
Input Resistance (CANH or CANL)	R_{IN}	Input to GND, D = 3V, RS = 0V	Full	**20**	40	**50**	kΩ
Differential Input Resistance	R_{IND}	Input to input, D = 3V, RS = 0V	Full	**40**	80	**100**	kΩ
SUPPLY CURRENT							
Supply Current, Low-Power Shutdown Mode	$I_{CC(LPS)}$	RS = D = V_{CC}, 3.0V ≤ V_{CC} ≤ 3.6V, Note 10	Full	-	20	50	µA
Supply Current, Dominant	$I_{CC(DOM)}$	D = RS = 0V, no load, 3.0V ≤ V_{CC} ≤ 3.6V	Full	-	5	**7**	mA
Supply Current, Recessive	$I_{CC(REC)}$	D = V_{CC}, RS = 0V, no load, 3.0V ≤ V_{CC} ≤ 3.6V	Full	-	2.6	**5.0**	mA
COLD SPARING BUS CURRENT							
CANH Leakage Current	$I_{L(CANH)}$	V_{CC} = 0.2V, CANH = -7V or 12V, D = V_{CC}, CANL = float, RS = 0V	Full	**-25**	-4	**25**	µA
CANL Leakage Current	$I_{L(CANL)}$	V_{CC} = 0.2V, CANL = -7V or 12V, D = V_{CC}, CANH = float, RS = 0V	Full	**-25**	-4	**25**	µA
VREF Leakage Current	$I_{L(VREF)}$	V_{CC} = 0.2V, V_{REF} = -7V or 12V, D = V_{CC}	Full	**-25.00**	0.01	**25.00**	µA
DRIVER SWITCHING CHARACTERISTICS							
Propagation Delay LOW to HIGH	t_{PDLH1}	RS = 0V, Figure 13	Full	-	75	**150**	ns
Propagation Delay LOW to HIGH	t_{PDLH2}	RS = 10kΩ, Figure 13	Full	-	520	**850**	ns
Propagation Delay LOW to HIGH	t_{PDLH3}	RS = 50kΩ, Figure 13	Full	-	850	**1400**	ns
Propagation Delay HIGH to LOW	t_{PDHL1}	RS = 0V, Figure 13	Full	-	80	**155**	ns

Electrical Specifications

Test Conditions: V_{CC} = 3.0V to 3.6V; typicals are at T_A = +25°C (Note 8); unless otherwise specified (Note 6). **Boldface limits apply across the operating temperature range, -55°C to +125°C; over a total ionizing dose of 75krad(Si) at +25°C with exposure at a low dose rate of <10mrad(Si)/s; and over a total ionizing dose of 100krad(Si) at +25°C with exposure of a high dose rate of 50krad(Si)/s. to 300krad(Si)/s. (Continued)**

PARAMETER	SYMBOL	TEST CONDITIONS	TEMP (°C)	MIN (Note 7)	TYP (Note 8)	MAX (Note 7)	UNIT
Propagation Delay HIGH to LOW	t_{PDHL2}	RS = 10kΩ, Figure 13	Full	-	460	**800**	ns
Propagation Delay HIGH to LOW	t_{PDHL3}	RS = 50kΩ, Figure 13	Full	-	725	**1300**	ns
Output Skew	t_{SKEW1}	RS = 0V, ($\|t_{PHL} - t_{PLH}\|$), Figure 13	Full	-	5	**50**	ns
Output Skew	t_{SKEW2}	RS = 10kΩ, ($\|t_{PHL} - t_{PLH}\|$), Figure 13	Full	-	60	**510**	ns
Output Skew	t_{SKEW3}	RS = 50kΩ, ($\|t_{PHL} - t_{PLH}\|$), Figure 13	Full	-	110	**800**	ns
Output Rise Time	t_{r1}	RS = 0V, (fast speed) Figure 13	Full	**20**	55	**100**	ns
Output Fall Time	t_{f1}		Full	**10**	25	**75**	ns
Output Rise Time	t_{r2}	RS = 10kΩ, (medium speed - 250Kbps) Figure 13	Full	**200**	400	**780**	ns
Output Fall Time	t_{f2}		Full	**175**	300	**500**	ns
Output Rise Time	t_{r3}	RS = 50kΩ, (slow speed - 125Kbps) Figure 13	Full	**400**	700	**1400**	ns
Output Fall Time	t_{f3}		Full	**300**	650	**1000**	ns
Total Loop Delay, Driver Input to Receiver Output, Recessive to Dominant	$t_{(LOOP1)}$	RS = 0V, Figure 15	Full	-	115	**210**	ns
		RS = 10kΩ, Figure 15	Full	-	550	**875**	ns
		RS = 50kΩ, Figure 15	Full	-	850	**1400**	ns
Total Loop Delay, Driver Input to Receiver Output, Dominant to Recessive	$t_{(LOOP2)}$	RS = 0V, Figure 15	Full	-	130	**270**	ns
		RS = 10kΩ, Figure 15	Full	-	500	**825**	ns
		RS = 50kΩ, Figure 15	Full	-	750	**1300**	ns
Low-Power Shutdown to Valid Dominant Time	t_{LPS_DOM}	Figure 16, Note 10	Full	-	6	**15**	µs
RECEIVER SWITCHING CHARACTERISTICS							
Propagation Delay LOW to HIGH	t_{PLH}	Figure 14	Full	-	50	**110**	ns
Propagation Delay HIGH to LOW	t_{PHL}	Figure 14	Full	-	50	**110**	ns
Rx Skew	t_{SKEW1}	$\|(t_{PHL} - t_{PLH})\|$, Figure 14	Full	-	2	**35**	ns
Rx Rise Time	t_r	Figure 14	Full	-	2	-	ns
Rx Fall Time	t_f	Figure 14	Full	-	2	-	ns
VREF/RS PIN CHARACTERISTICS							
VREF Pin Voltage	VREF	-5µA < I_{REF} < 5µA	Full	**0.45 x V_{CC}**	1.6	**0.55 x V_{CC}**	V
		-50µA < I_{REF} < 50µA	Full	**0.40 x V_{CC}**	1.6	**0.60 x V_{CC}**	V
RS Pin Input Current	$I_{RS(H)}$	RS = 0.75xV_{CC}	Full	**-10.0**	-0.2	-	µA
	$I_{RS(L)}$	V_{RS} = 0V	Full	**-450**	-125	**0**	µA

NOTES:

6. All currents into device pins are positive; all currents out of device pins are negative. All voltages are referenced to device ground unless otherwise specified.
7. Parameters with MIN and/or MAX limits are 100% tested at -55°C, +25°C and +125°C, unless otherwise specified.
8. Typical values are at 3.3V. Parameters with a single entry in the “TYP” column apply to 3.3V. Typical values shown are not guaranteed.
9. Parameter included in functional testing.
10. Performed during the 100% screening operations across the full operating temperature range. Not performed as part of TCI Group E and Group C. Radiation characterization testing performed as part of the initial release and any major changes in design.

Test Circuits and Waveforms

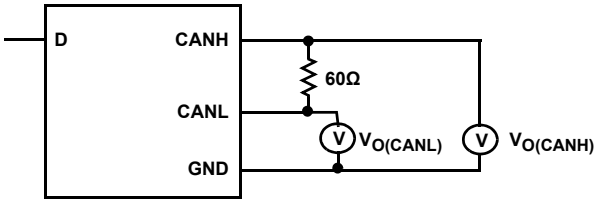


FIGURE 10. DRIVER TEST CIRCUIT

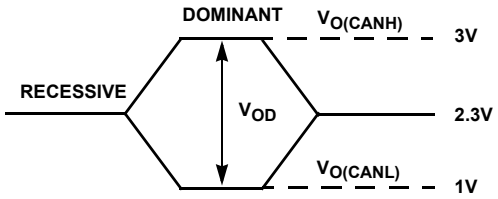


FIGURE 11. DRIVER BUS VOLTAGE DEFINITIONS

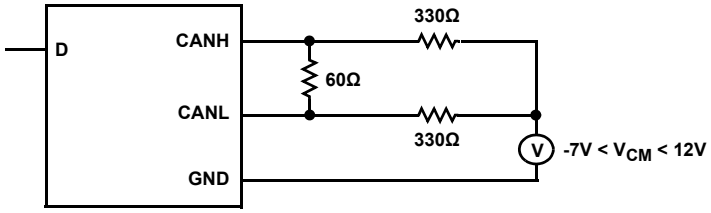
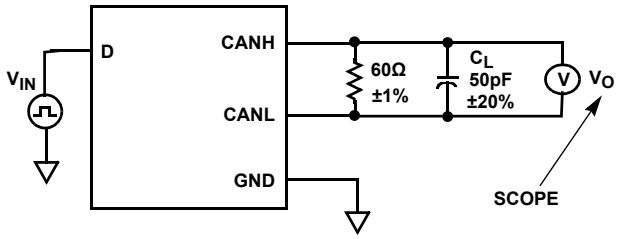


FIGURE 12. DRIVER COMMON-MODE CIRCUIT



V_{IN} = 125kHz, 0V to V_{CC}, Duty Cycle 50%, $t_r = t_f \leq 6ns$, $Z_O = 50\Omega$
C_L includes fixture and instrumentation capacitance

FIGURE 13A. DRIVER TIMING TEST CIRCUIT

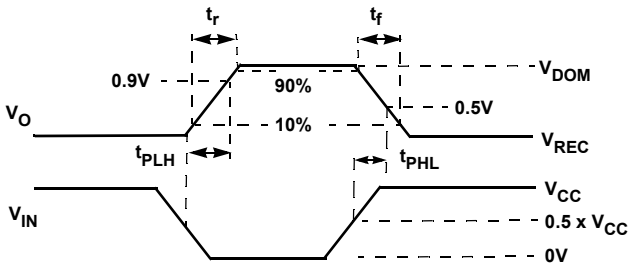


FIGURE 13B. DRIVER TIMING MEASUREMENT POINTS

FIGURE 13. DRIVER TIMING

Test Circuits and Waveforms (Continued)

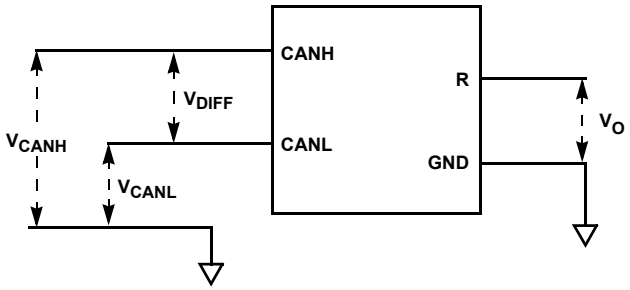
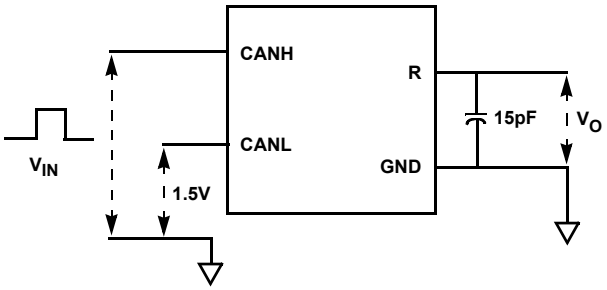


FIGURE 14A. RECEIVER VOLTAGE DEFINITIONS



V_{IN} = 125kHz, Duty Cycle 50%, $t_r = t_f \leq 6ns$, $Z_O = 50\Omega$
C_L includes test setup capacitance

FIGURE 14B. RECEIVER TEST CIRCUIT

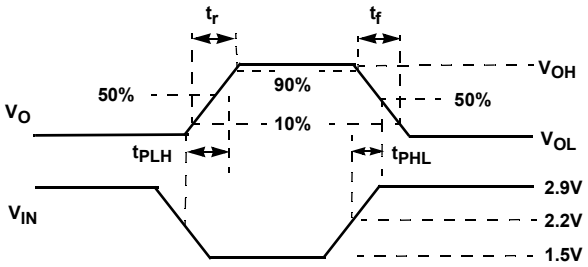


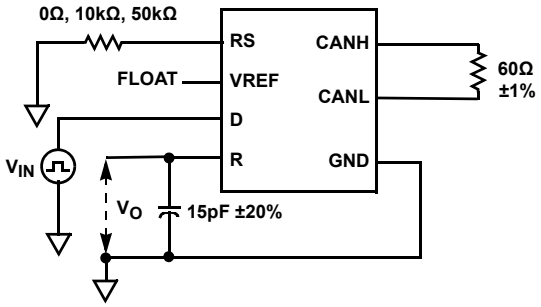
FIGURE 14C. RECEIVER TEST MEASUREMENT POINTS

FIGURE 14. RECEIVER TEST

TABLE 2. DIFFERENTIAL INPUT VOLTAGE THRESHOLD TEST

INPUT		OUTPUT	MEASURED
V_{CANH}	V_{CANL}	R	V_{DIFF}
-6.1V	-7V	L	900mV
12V	11.1V	L	900mV
-1V	-7V	L	6V
12V	6V	L	6V
-6.5V	-7V	H	500mV
12V	11.5V	H	500mV
-7V	-1V	H	6V
6V	12V	H	6V
Open	Open	H	X

Test Circuits and Waveforms (Continued)



V_{IN} = 125kHz, Duty Cycle 50%, $t_r = t_f \leq 6ns$

FIGURE 15A. TOTAL LOOP DELAY TEST CIRCUIT

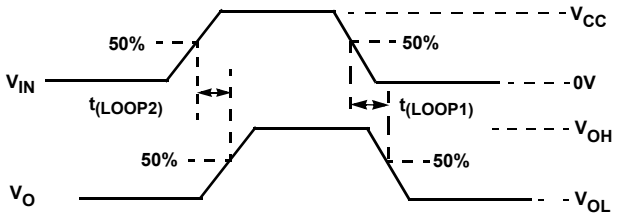
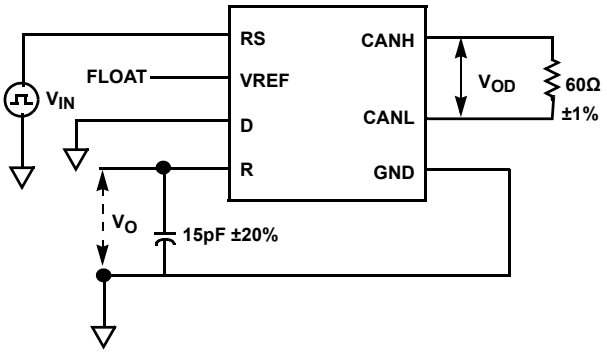


FIGURE 15B. TOTAL LOOP DELAY MEASUREMENT POINTS

FIGURE 15. TOTAL LOOP DELAY



V_{IN} = 125kHz, 0V to V_{CC}, Duty Cycle 50%, $t_r = t_f \leq 6ns$.

FIGURE 16A. LOW-POWER SHUTDOWN TO DOMINANT TIME CIRCUIT

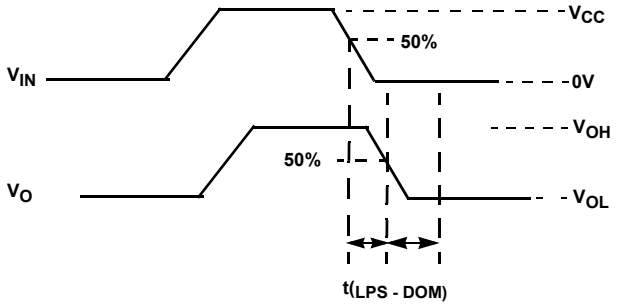


FIGURE 16B. LOW-POWER SHUTDOWN TO DOMINANT TIME MEASUREMENT POINTS

FIGURE 16. LOW-POWER SHUTDOWN TO DOMINANT TIME

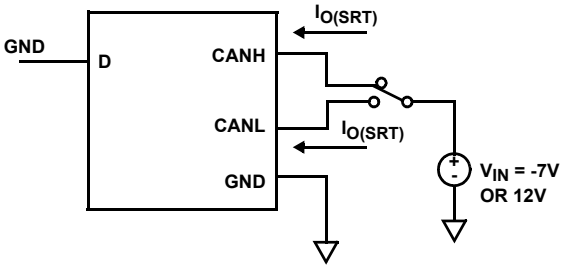


FIGURE 17A. OUTPUT SHORT-CIRCUIT CURRENT CIRCUIT

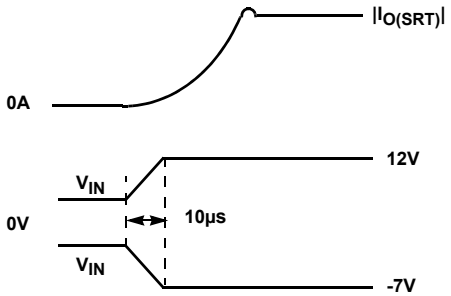


FIGURE 17B. OUTPUT SHORT-CIRCUIT CURRENT WAVEFORMS

FIGURE 17. OUTPUT SHORT-CIRCUIT

Functional Description

Overview

The ISL72028BSEH is a 3.3V radiation tolerant CAN transceiver that is compatible with the ISO11898-2 standard for use in Controller Area Network (CAN) serial communication systems.

The device performs transmit and receive functions between the CAN controller and the CAN differential bus. It can transmit and receive at bus speeds of up to 5Mbps. It is designed to operate over a common-mode range of -7V to +12V with a maximum of 120 nodes. The device is capable of withstanding ±20V on the CANH and CANL bus pins outside of ion beam and ±16V under ion beam.

Slope Adjustment

The output driver rise and fall time has three distinct selections that may be chosen by using a resistor from the RS pin to GND. Connecting the RS pin directly to GND results in output switching times that are the fastest, limited only by the drive capability of the output stage. RS = 10kΩ provides for a typical slew rate of 8V/µs and RS = 50kΩ provides for a typical slew rate of 4V/µs.

Putting a high logic level to the RS pin places the device in a Low-Power Shutdown mode. The protocol controller uses this mode to switch between Low-Power Shutdown mode and Normal Transmit mode.

Cable Length

The device can work per ISO11898 specification with a 40m cable and stub length of 0.3m and 60 nodes at 1Mbps. This is greater than the ISO requirement of 30 nodes. The cable type specified is a twisted pair (shielded or unshielded) with a characteristic impedance of 120Ω. Resistors equal to this are to be terminated at both ends of the cable. Stubs should be kept as short as possible to prevent reflections.

Cold Spare

High reliability system designers implementing data communications have to be sensitive to the potential for single point failures. To mitigate the risk of a failure, they will use redundant bus transceivers in parallel. In this arrangement, both active and quiescent devices can be present simultaneously on the bus. The quiescent devices are powered down for cold spare and do not affect the communication of the other active nodes.

To achieve this, a powered-down transceiver (V_{CC} < 200mV) has a resistance between the VREF pin, the CANH pin, or the CANL pin and the VCC supply rail of >480kΩ (maximum) with a typical resistance >2MΩ. The resistance between CANH and CANL of a powered-down transceiver has a typical resistance of 80kΩ.

Low-Power Shutdown Mode

When a high level is applied to the RS pin, the device enters the Low-Power Shutdown mode in which the driver and receiver are switched off to conserve power. The bus pins are at High Z and the R pin will be at logic high. In Low-Power Shutdown the transceiver draws 50µA (max) of current.

A low level on the RS pin brings the device back to operation.

Using 3.3V Devices in 5V Systems

Looking at the differential voltage of both the 3.3V and 5V devices, the differential voltage is the same, the recessive common-mode output is the same. The dominant common-mode output voltage is slightly lower than the 5V counterparts. The receiver specifications are also the same. Though the electrical parameters appear compatible, it is advised that necessary system testing be performed to verify interchangeable operation.

Split Mode Termination

The VREF pin provides a $V_{CC}/2$ output voltage for Split mode termination. The VREF pin has the same ESD protection, short-circuit protection and common-mode operating range as the bus pins.

The Split mode termination technique is shown in Figure 18.

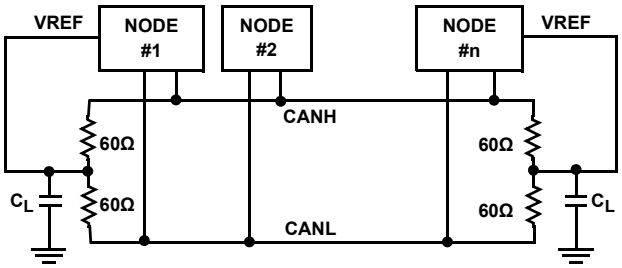


FIGURE 18. SPLIT TERMINATION

It is used to stabilize the bus voltage at $V_{CC}/2$ and prevent it from drifting to a high common-mode voltage during periods of inactivity. The technique improves the electromagnetic compatibility of a network. The Split mode termination is put at each end of the bus.

The C_L capacitor between the two 60Ω resistors, filters unwanted high frequency noise to ground. The resistors should have a tolerance of 1% or better and the two resistors should be carefully matched to provide the most effective EMI immunity. A typical value of C_L for a high speed CAN network is 4.7nF, which generates a 3dB point at 1.1Mbps. The capacitance value used is dependent on the signaling rate of the network.

Typical Performance Curves C_L = 15pF, T_A = +25°C; unless otherwise specified.

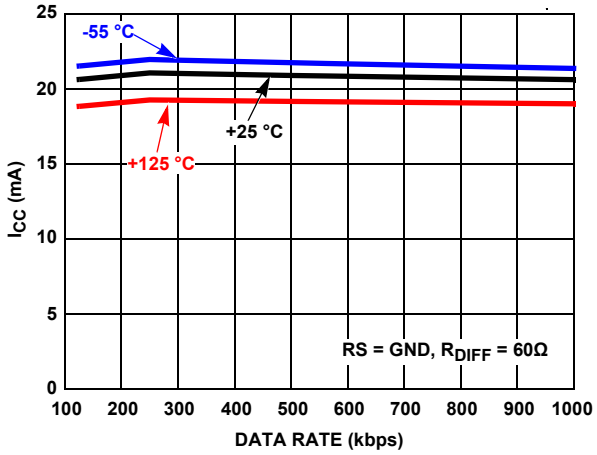


FIGURE 19. SUPPLY CURRENT vs FAST DATA RATE vs TEMPERATURE

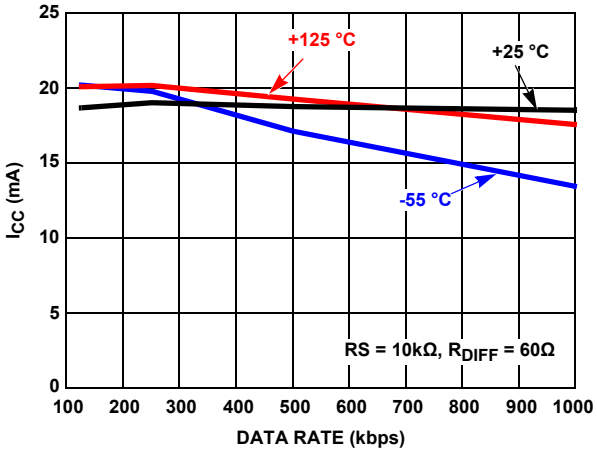


FIGURE 20. SUPPLY CURRENT vs MEDIUM DATA RATE vs TEMPERATURE

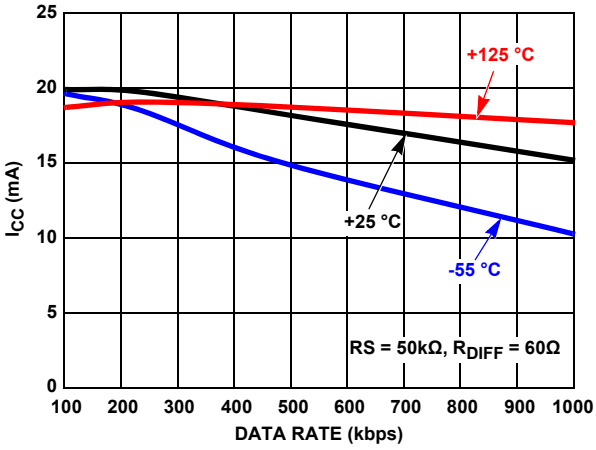


FIGURE 21. SUPPLY CURRENT vs SLOW DATA RATE vs TEMPERATURE

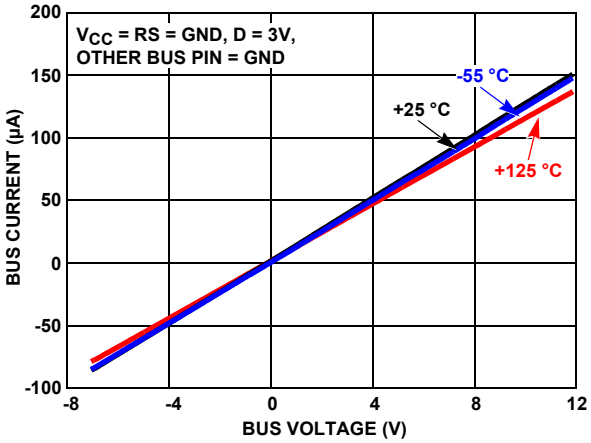


FIGURE 22. BUS PIN LEAKAGE vs V_{CM} AT V_{CC} = 0V

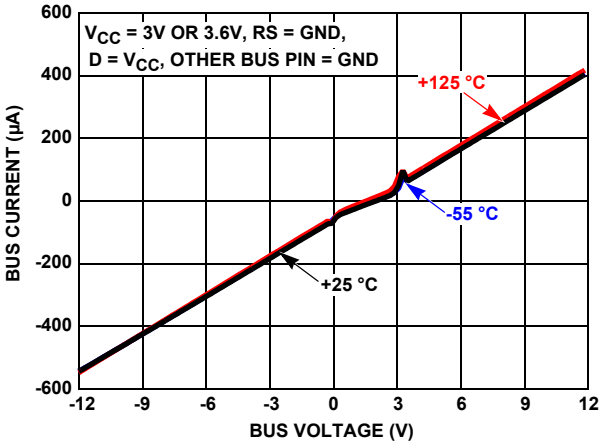


FIGURE 23. BUS PIN LEAKAGE vs ±12V VCM

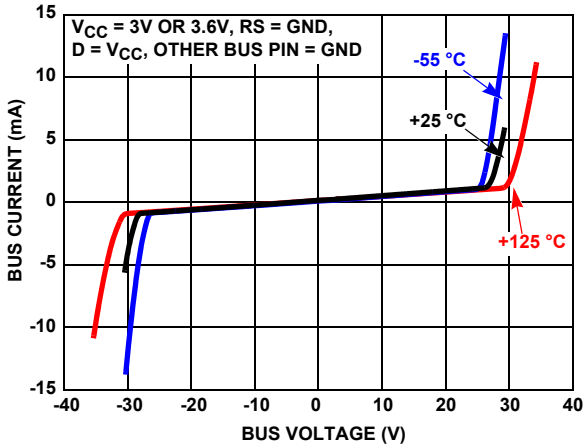


FIGURE 24. BUS PIN LEAKAGE vs ±35V VCM

Typical Performance Curves C_L = 15pF, T_A = +25°C; unless otherwise specified. **(Continued)**

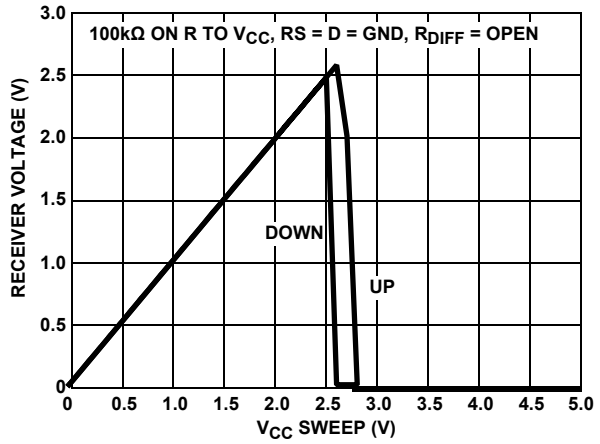


FIGURE 25. V_{CC} UNDERVOLTAGE LOCKOUT

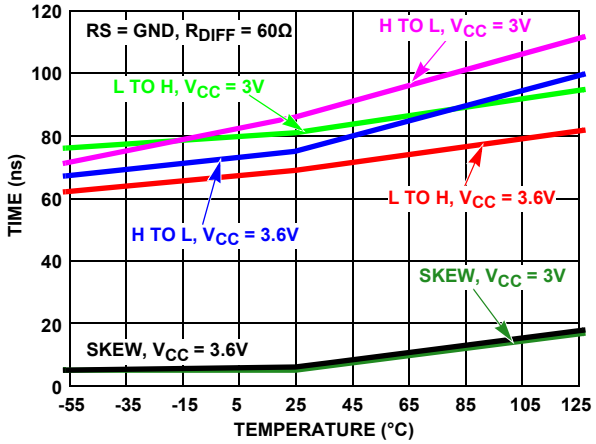


FIGURE 26. TRANSMITTER PROPAGATION DELAY AND SKEW vs TEMPERATURE AT FAST SPEED

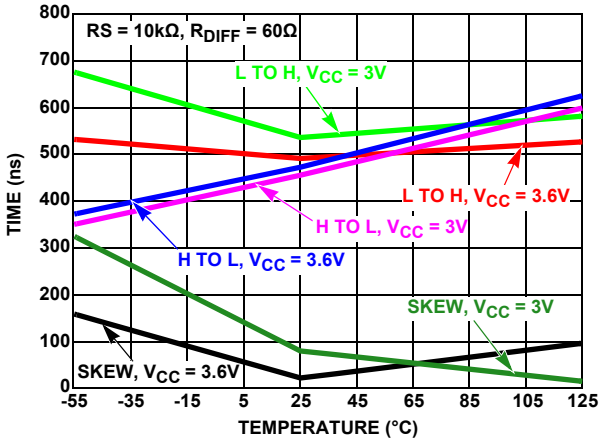


FIGURE 27. TRANSMITTER PROPAGATION DELAY AND SKEW vs TEMPERATURE AT MEDIUM SPEED

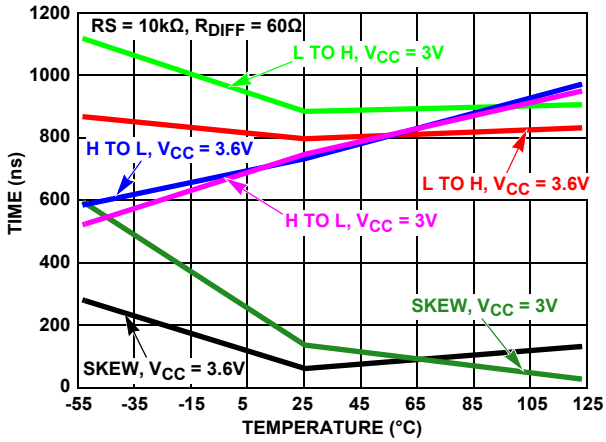


FIGURE 28. TRANSMITTER PROPAGATION DELAY AND SKEW vs TEMPERATURE AT SLOW SPEED

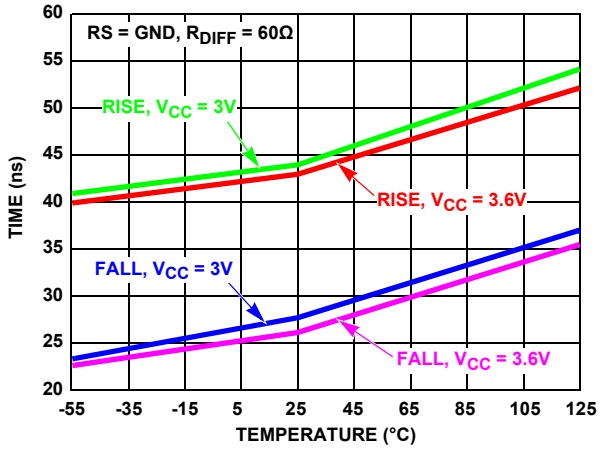


FIGURE 29. TRANSMITTER RISE AND FALL TIMES vs TEMPERATURE AT FAST SPEED

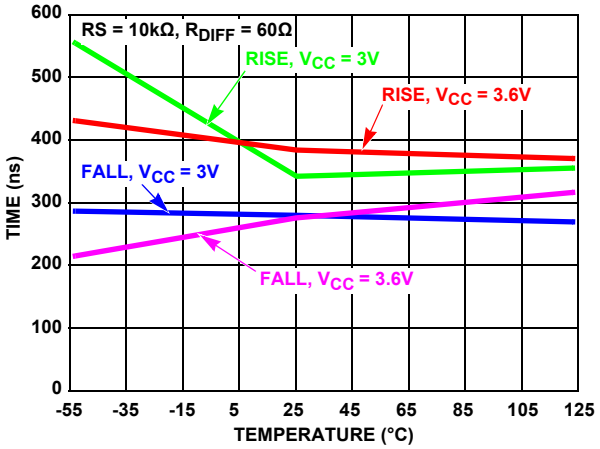


FIGURE 30. TRANSMITTER RISE AND FALL TIMES vs TEMPERATURE AT MEDIUM SPEED

Typical Performance Curves C_L = 15pF, T_A = +25°C; unless otherwise specified. **(Continued)**

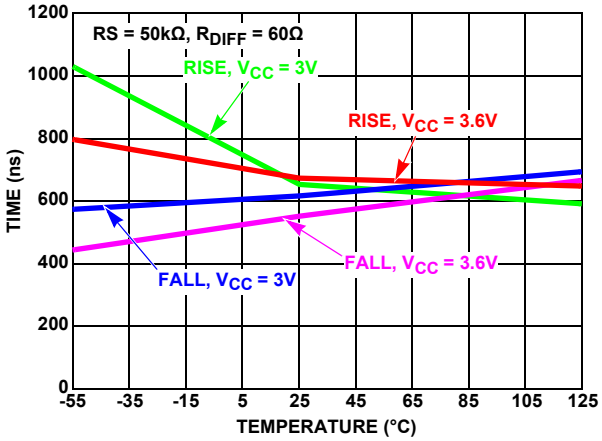


FIGURE 31. TRANSMITTER RISE AND FALL TIMES vs TEMPERATURE AT SLOW SPEED

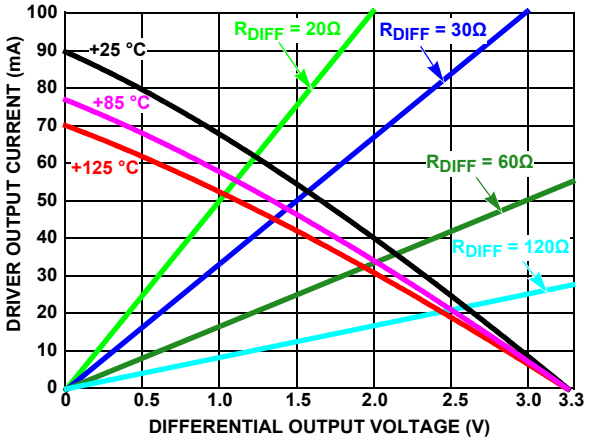


FIGURE 32. DRIVER OUTPUT CURRENT vs DIFFERENTIAL OUTPUT VOLTAGE

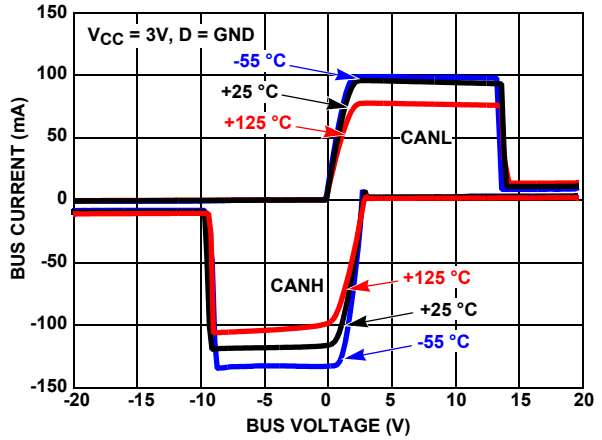


FIGURE 33. DRIVER OUTPUT CURRENT vs SHORT-CIRCUIT VOLTAGE vs TEMPERATURE

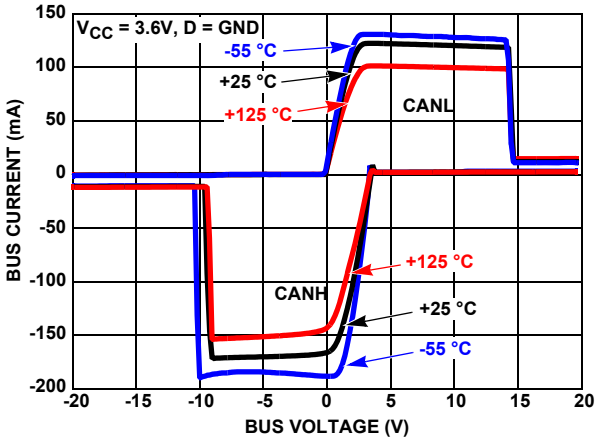


FIGURE 34. DRIVER OUTPUT CURRENT vs SHORT-CIRCUIT VOLTAGE vs TEMPERATURE

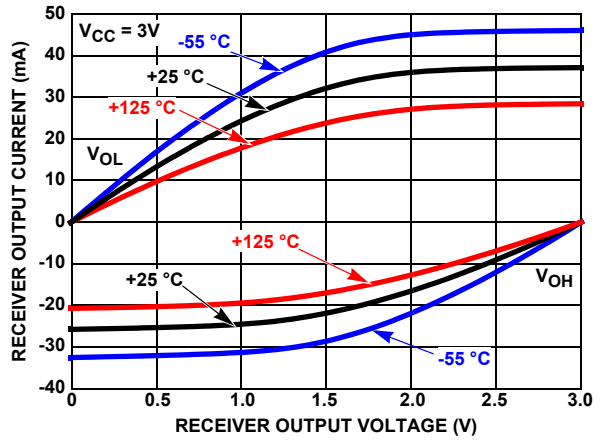


FIGURE 35. RECEIVER OUTPUT CURRENT vs RECEIVER OUTPUT VOLTAGE AT V_{CC} = 3V

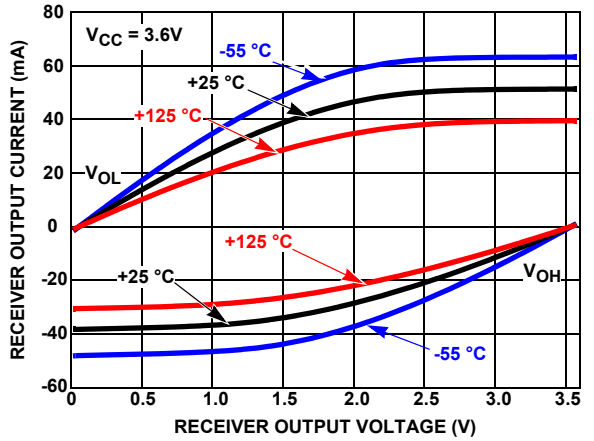


FIGURE 36. RECEIVER OUTPUT CURRENT vs RECEIVER OUTPUT VOLTAGE AT V_{CC} = 3.6V

Typical Performance Curves C_L = 15pF, T_A = +25°C; unless otherwise specified. **(Continued)**

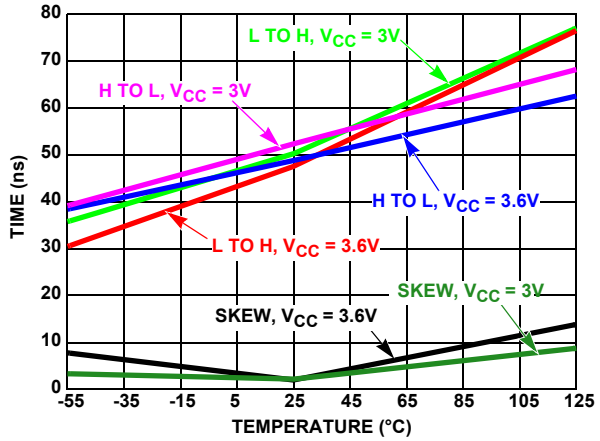


FIGURE 37. RECEIVER PROPAGATION DELAY AND SKEW vs TEMPERATURE

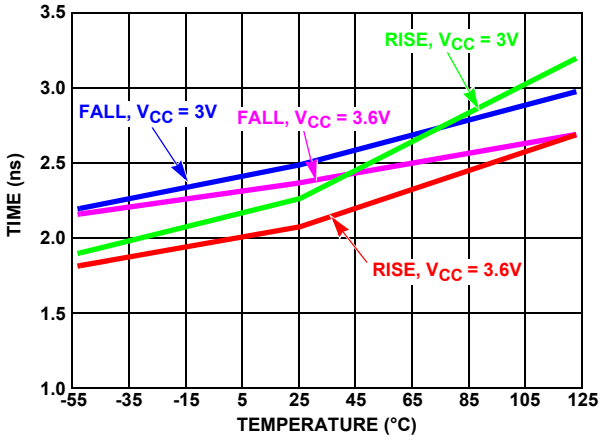


FIGURE 38. RECEIVER RISE AND FALL TIMES vs TEMPERATURE

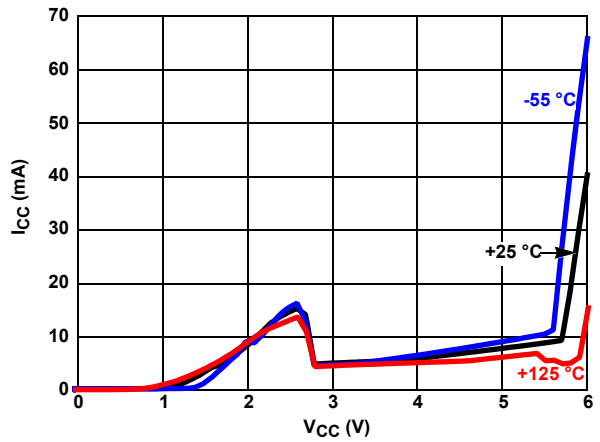


FIGURE 39. SUPPLY CURRENT vs SUPPLY VOLTAGE vs TEMPERATURE

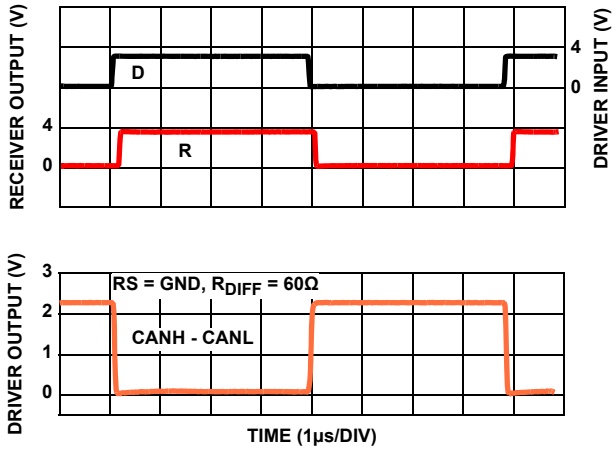


FIGURE 40. FAST DRIVER AND RECEIVER WAVEFORMS

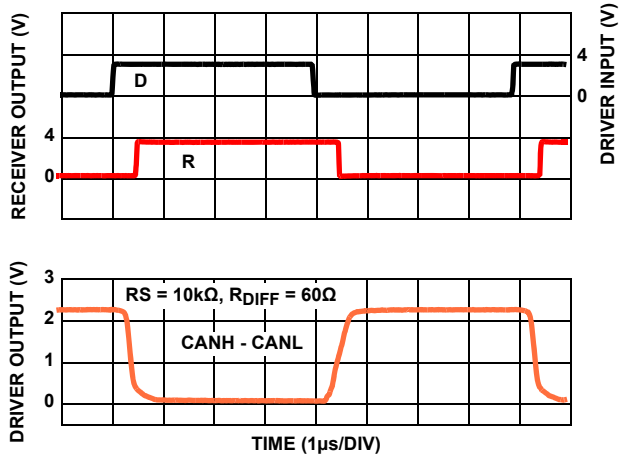


FIGURE 41. MEDIUM DRIVER AND RECEIVER WAVEFORMS

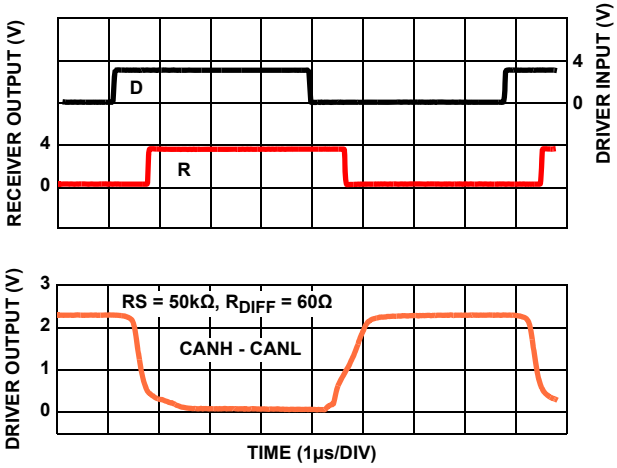


FIGURE 42. SLOW DRIVER AND RECEIVER WAVEFORMS

Die Characteristics

Die Dimensions

2413µm x 3322µm (95 mils x 130.79 mils)
Thickness: 305µm ±25µm (12 mils ±1 mil)

Interface Materials

GLASSIVATION

Type: 12kÅ Silicon Nitride on 3kÅ Oxide

TOP METALLIZATION

Type: 300Å TiN on 2.8µm AlCu
In Bondpads, TiN has been removed.

BACKSIDE FINISH

Silicon

PROCESS

P6SOI

Assembly Related Information

SUBSTRATE POTENTIAL

Floating

Additional Information

WORST CASE CURRENT DENSITY

$1.6 \times 10^5 A/cm^2$

TRANSISTOR COUNT

4055

Weight of Packaged Device

0.31 grams

Lid Characteristics

Finish: Gold
Potential: Grounded, tied to package pin 2

Metalization Mask Layout

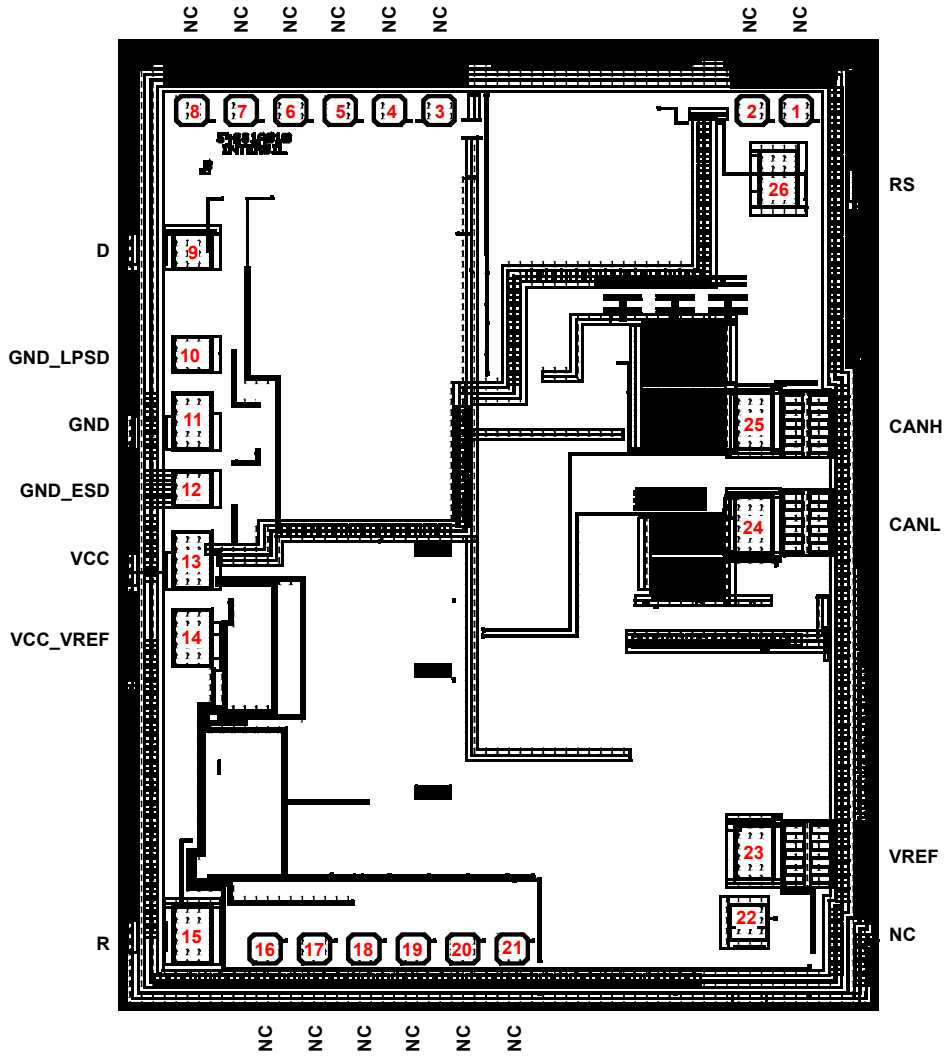


TABLE 3. ISL72028BSEH DIE LAYOUT X-Y COORDINATES

PAD NUMBER	PAD NAME	X (µm)	Y (µm)	X	Y
1	NC	90.0	90.0	901.4	1365.6
2	NC	90.0	90.0	767.4	1365.6
3	NC	90.0	90.0	-183.23	1365.6
4	NC	90.0	90.0	-333.25	1365.6
5	NC	90.0	90.0	-483.25	1365.6
6	NC	90.0	90.0	-633.25	1365.6
7	NC	90.0	90.0	-783.25	1365.6
8	NC	90.0	90.0	-933.25	1365.6
9	D	110.0	110.0	-931.1	901.85
10	GND_LSPD	110.0	110.0	-931.1	563.25
11	GND	110.0	180.0	-931.1	342.25
12	GND_ESD	110.0	110.05	-931.1	119.42
13	VCC	110.0	180.0	-931.1	-115.05
14	VCC_VREF	110.0	180.05	-931.1	-371.08
15	R	110.0	180.0	-931.1	-1350.0
16	NC	90.0	90.0	-711.1	-1394.95
17	NC	90.0	90.0	-561.1	-1394.95
18	NC	90.0	90.0	-411.1	-1394.95
19	NC	90.0	90.0	-261.1	-1394.95
20	NC	90.0	90.0	-111.1	-1394.95
21	NC	90.0	90.0	38.9	-1394.95
22	NC	110.0	110.0	756.9	-1307.3
23	VREF	110.0	180.0	775.3	-1072.3
24	CANL	110.0	180.0	772.1	2.15
25	CANH	110.0	180.05	772.1	343.33
26	RS	110.0	180.0	848.1	1140.6

NOTE: Origin of coordinates is the center of the die. NC - No Connect

Revision History

The revision history provided is for informational purposes only and is believed to be accurate, but not warranted. Please visit our website to make sure that you have the latest revision.

DATE	REVISION	CHANGE
November 30, 2016	FN8902.0	Initial Release

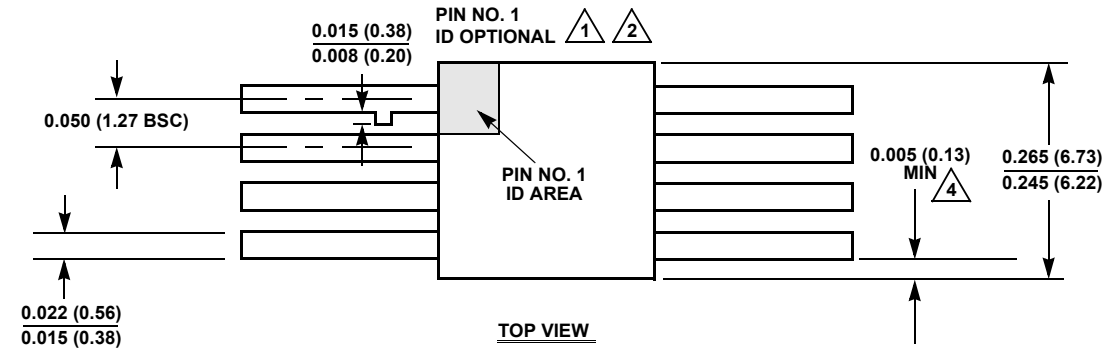
Package Outline Drawing

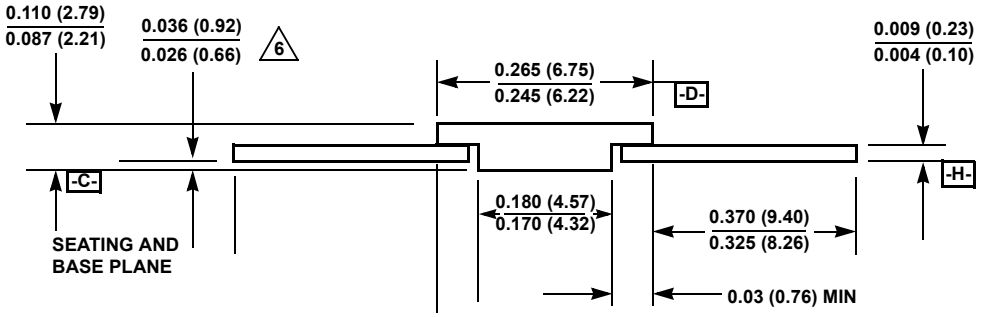
For the most recent package outline drawing, see K8.A.

K8.A

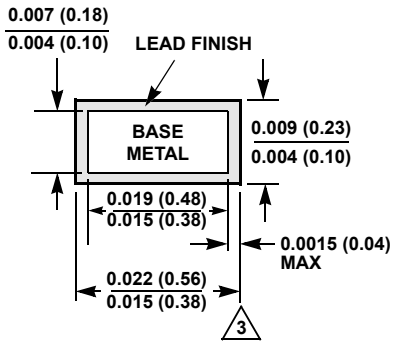
8 LEAD CERAMIC METAL SEAL FLATPACK PACKAGE

Rev 4, 12/14





SIDE VIEW



SECTION A-A

NOTES:

1. Index area: A notch or a pin one identification mark shall be located adjacent to pin one and shall be located within the shaded area shown. The manufacturer's identification shall not be used as a pin one identification mark. Alternately, a tab may be used to identify pin one.
2. If a pin one identification mark is used in addition to or instead of a tab, the limits of the tab dimension do not apply.
3. The maximum limits of lead dimensions (section A-A) shall be measured at the centroid of the finished lead surfaces, when solder dip or tin plate lead finish is applied.
4. Measure dimension at all four corners.
5. For bottom-brazed lead packages, no organic or polymeric materials shall be molded to the bottom of the package to cover the leads.
6. Dimension shall be measured at the point of exit (beyond the meniscus) of the lead from the body. Dimension minimum shall be reduced by 0.0015 inch (0.038mm) maximum when solder dip lead finish is applied.
7. Dimensioning and tolerancing per ANSI Y14.5M - 1982.
8. Controlling dimension: INCH.

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