User's Manual

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RH850 Evaluation Platform

RH850/U2A 292pin

User's Manual: Piggyback Board

Y-RH850-U2A-292PIN-PB-T1-V2

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Y-RH850-U2A-292PIN-PB-T1-V2

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General Precautions in the Handling of Microprocessing Unit and Microcontroller Unit Products

The following usage notes are applicable to all Microprocessing unit and Microcontroller unit products from Renesas. For detailed usage notes on the products covered by this document, refer to the relevant sections of the document as well as any technical updates that have been issued for the products.

1. Precaution against Electrostatic Discharge (ESD)

A strong electrical field, when exposed to a CMOS device, can cause destruction of the gate oxide and ultimately degrade the device operation. Steps must be taken to stop the generation of static electricity as much as possible, and quickly dissipate it when it occurs. Environmental control must be adequate. When it is dry, a humidifier should be used. This is recommended to avoid using insulators that can easily build up static electricity.

Semiconductor devices must be stored and transported in an anti-static container, static shielding bag or conductive material. All test and measurement tools including work benches and floors must be grounded. The operator must also be grounded using a wrist strap. Semiconductor devices must not be touched with bare hands. Similar precautions must be taken for printed circuit boards with mounted semiconductor devices.

2. Processing at power-on

The state of the product is undefined at the time when power is supplied. The states of internal circuits in the LSI are indeterminate and the states of register settings and pins are undefined at the time when power is supplied. In a finished product where the reset signal is applied to the external reset pin, the states of pins are not guaranteed from the time when power is supplied until the reset process is completed. In a similar way, the states of pins in a product that is reset by an on-chip power-on reset function are not guaranteed from the time when power is supplied until the power reaches the level at which resetting is specified.

3. Input of signal during power-off state

Do not input signals or an I/O pull-up power supply while the device is powered off. The current injection that results from input of such a signal or I/O pull-up power supply may cause malfunction and the abnormal current that passes in the device at this time may cause degradation of internal elements. Follow the guideline for input signal during power-off state as described in your product documentation.

4. Handling of unused pins

Handle unused pins in accordance with the directions given under handling of unused pins in the manual. The input pins of CMOS products are generally in the high-impedance state. In operation with an unused pin in the open-circuit state, extra electromagnetic noise is induced in the vicinity of the LSI, an associated shoot-through current flows internally, and malfunctions occur due to the false recognition of the pin state as an input signal become possible.

5. Clock signals

After applying a reset, only release the reset line after the operating clock signal becomes stable. When switching the clock signal during program execution, wait until the target clock signal is stabilized. When the clock signal is generated with an external resonator or from an external oscillator during a reset, ensure that the reset line is only released after full stabilization of the clock signal. Additionally, when switching to a clock signal produced with an external resonator or by an external oscillator while program execution is in progress, wait until the target clock signal is stable.

6. Voltage application waveform at input pin

Waveform distortion due to input noise or a reflected wave may cause malfunction. If the input of the CMOS device stays in the area between VIL (Max.) and VIH (Min.) due to noise, for example, the device may malfunction. Take care to prevent chattering noise from entering the device when the input level is fixed, and also in the transition period when the input level passes through the area between VIL (Max.) and VIH (Min.).

7. Prohibition of access to reserved addresses

Access to reserved addresses is prohibited. The reserved addresses are provided for possible future expansion of functions. Do not access these addresses as the correct operation of the LSI is not guaranteed.

8. Differences between products

Before changing from one product to another, for example to a product with a different part number, confirm that the change will not lead to problems.

The characteristics of a microprocessing unit or microcontroller unit products in the same group but having a different part number might differ in terms of internal memory capacity, layout pattern, and other factors, which can affect the ranges of electrical characteristics, such as characteristic values, operating margins, immunity to noise, and amount of radiated noise. When changing to a product with a different part number, implement a system-evaluation test for the given product.

Table of Contents

1. Overview

The RH850/U2A 292pin piggyback board is part of the RH850 Evaluation Platform and serves as a simple and easy to use platform for evaluating the features and performance of Renesas Electronics' 32-bit RH850/U2A 292pin microcontrollers.

Notes

1. This document describes the functionality of the piggyback board and guides the user through its operation.
   For details regarding the operation of the microcontroller, refer to the device's Hardware User's Manual.

2. In this document low active signals are marked by an appended 'Z' to the pin or signal name. E.g. the reset pin is named RESETZ.

3. In this document following abbreviations are used:
   - H level, L level: high or low signal level of a digital signal, the absolute voltage value depends on the signal

1.1 Package Components

The Y-RH850-U2A-292PIN-PB-T1-V2 product package consists of the following items. After you have unpacked the box, check if your Y-RH850-U2A-292PIN-PB-T1-V2 package contains all of these items. *Table 1.1 Package Components for the Y-RH850-U2A-292PIN-PB-T1-V2* shows the packing components of the Y-RH850-U2A-292PIN-PB-T1-V2 package.

Table 1.1 Package Components for the Y-RH850-U2A-292PIN-PB-T1-V2

Item	Description	Quantity
D018037	RH850/U2A 292pin piggyback board	1
D018332	Documentation CD	1
D010816-24	China RoHS document	1
D010818-24	WEEE+CE document	1
D018037-24	Product contents List	1
Jumpers (2-way, 0.1")	In the bag	44 (min. quantity)
Red Hirschmann 4 mm power lab sockets	In the bag	1 (3 for boards up to serial number 15005 only)
Black Hirschmann 4 mm power lab sockets	In the bag	--- (1 for boards up to serial number 15005 only)
Würth PCB Terminal Block connector	In the bag	1
TE MATEnet 1000BASE-T1 Ethernet Port connector	In the bag	1

TE MATEnet 1000BASE-T1 Ethernet connection cable [1m]	In the bag	1
16MHz Resonator	In the bag	1
20MHz Resonator	In the bag	1
24MHz Resonator	In the bag	1

Note

Please keep the Y-RH850-U2A-292PIN-PB-T1-V2 packing box at hand for later reuse in sending the product for repairs or for other purposes. Always use the original packing box when transporting the Y-RH850-U2A-292PIN-PB-T1-V2. If packing of your product is not complete, it may be damaged during transportation.

1.2   Supported Main Boards

This piggyback board can be used as a standalone board, or it can be mated with a main board. The following main boards are supported:

- Y-RH850-X1X-MB-T1-V1
- Y-RH850-X1X-MB-T2-Vx
- Y-RH850-X2X-MB-T1-Vx
- Y-COMMON-MB-T1-V1

1.3   Main Features

- Burn-in socket for mounting of the device
- Several power set-up options
    - Combined operation with powering from main board
    - Stand-alone operation with single power supply (e.g. 3.3 V or 5.0 V only)
    - Stand-alone operation with flexible, individual power supply (typ. 1.12 V, 3.3 V, 5.0 V)
      Refer to *3.4 Device Core Voltage (VDD) Selection* for further details about VDD voltage.
- Debugging and programming interface:
    - 14-pin LPD/JTAG Debug Connector (e.g. for using E2 OCD Emulator or PG-FP6 Flash Programmer)
- Pin headers for direct access to each device pin
- Reset switch
- External clock circuit with an exchangeable 16/20/24/40 MHz Crystal Resonator
- General purpose signaling LEDs
- Jumpers for device mode selection and other configuration options
- Automotive Ethernet Port 100/1000BASE-T1
- On-board interface connector for
    - Renesas High-Speed Serial I/F (RHSIF)
   or
    - Multichannel Serial Peripheral Interface (MSPI)
- Operating temperature from 0 °C to +40 °C

1.4 Piggyback Board Views

Following figures provide the top and bottom views of the piggyback board.
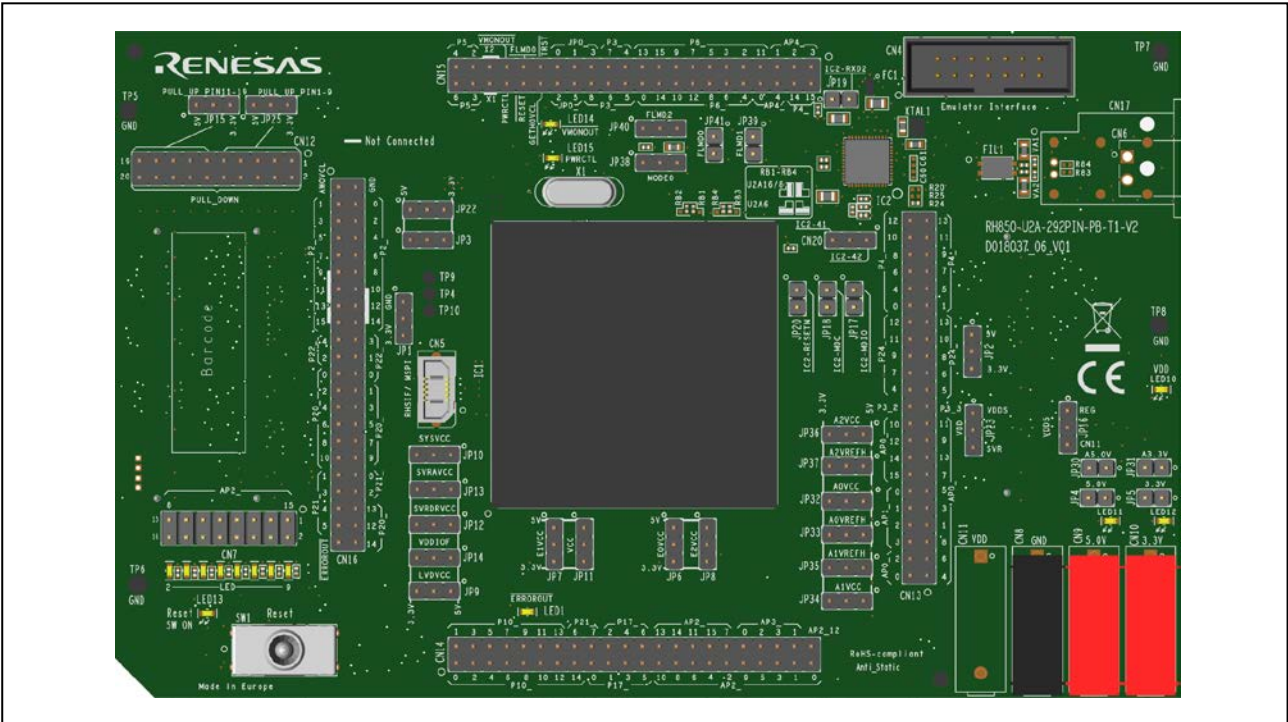
Figure 1.1 Piggyback board top view
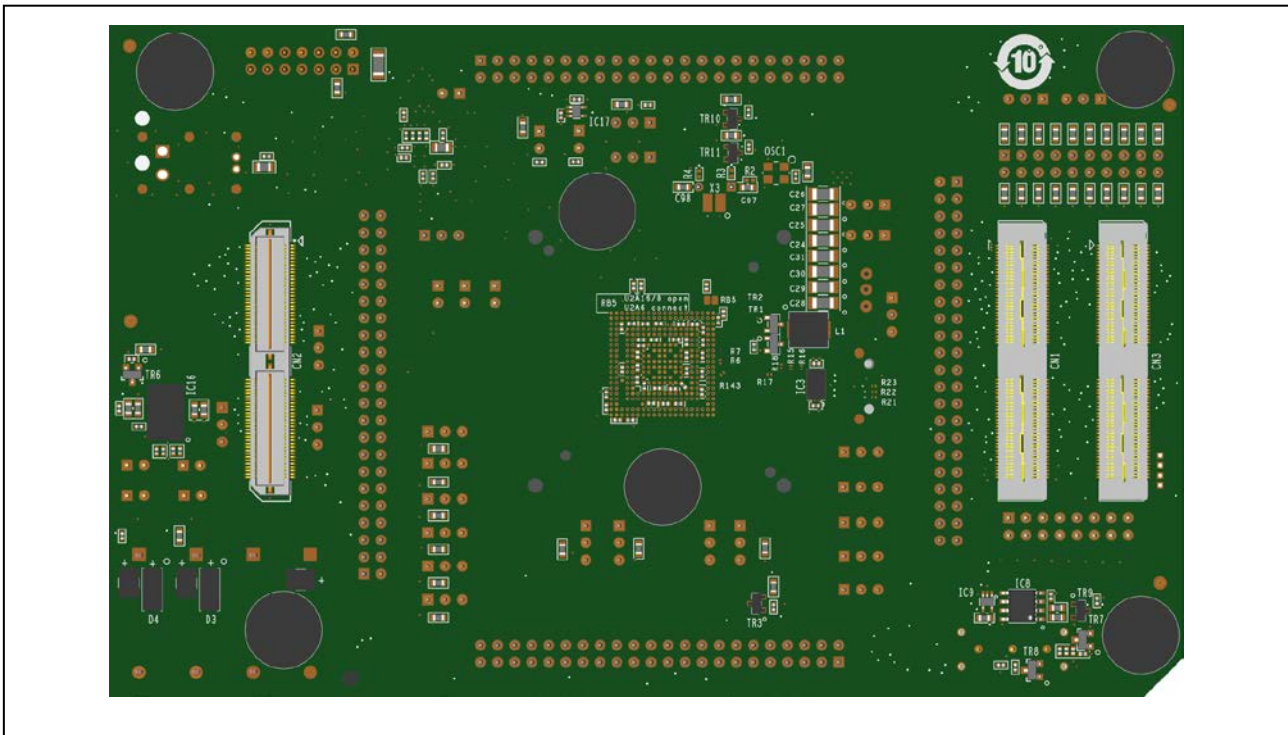
Figure 1.2 Piggyback board bottom view

Following figures provide the drawing of top and bottom views of the piggyback board.
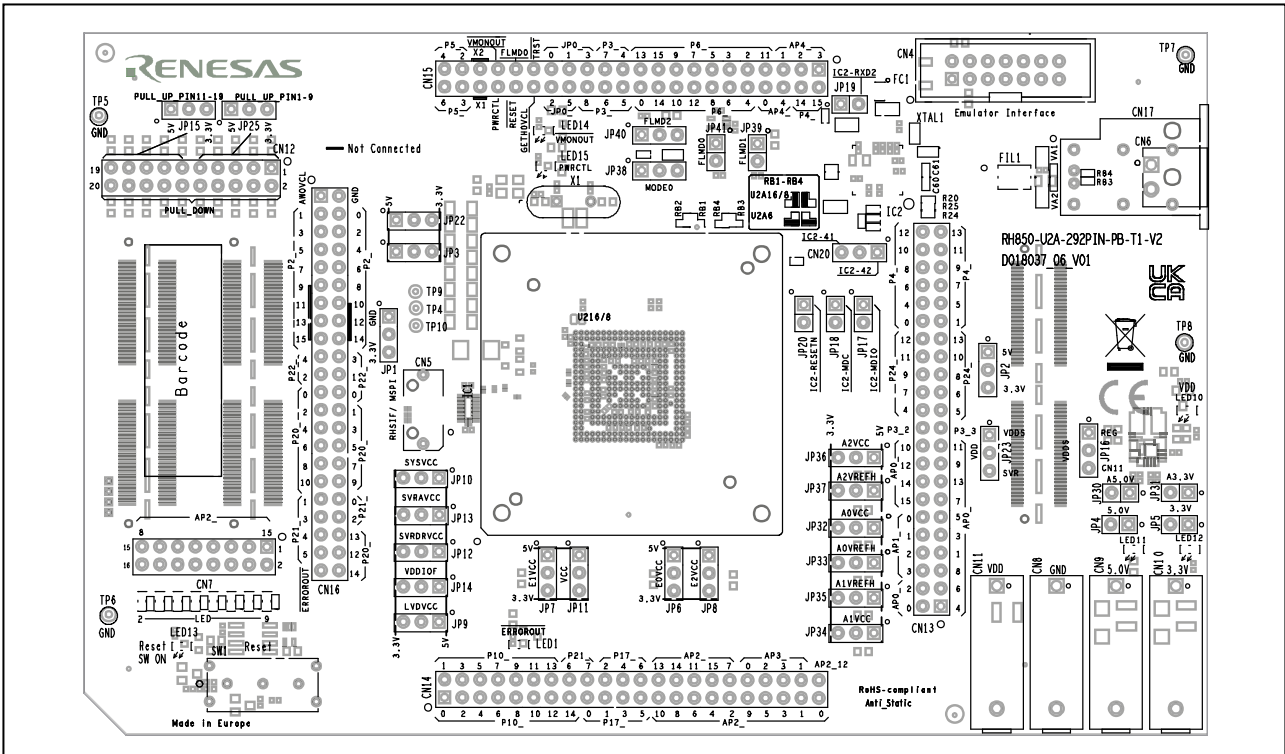
Figure 1.3 Piggyback Board top view
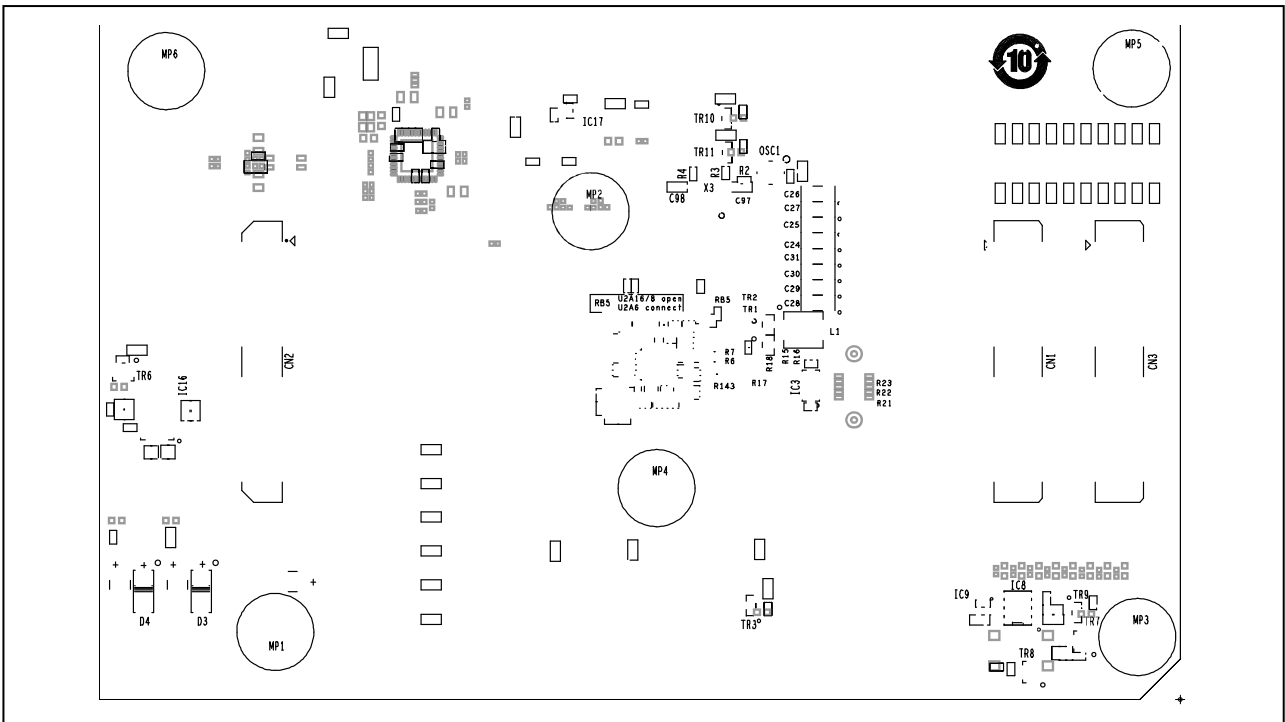
Figure 1.4 Piggyback Board bottom view

1.5   Mounting of the Device

The board is designed for use with the devices listed in table 1.2.

Table 1.2 Devices that can be used with Y-RH850-U2A-292PIN-PB-T1-V2

RH850/U2A6	RH850/U2A8	RH850/U2A16
R7F702302FABB-C *	R7F702301EABG-C	R7F702300EABA-C
	R7F702301AFABG-C	R7F702300AFABA-C
	R7F702301BFABG-C	R7F702300BFABA-C

Note: *   The piggyback board has to be modified in order to use a RH850/U2A6 device.
Please see chapter *1.6 Modifications for RH850/U2A6* device.

The device must be placed inside the socket IC1. To insert the device, align the device package A1 pin with the marking of the socket.
The A1pin of the socket is marked with a circle near to the "IC1" label (see also white point in *Figure 1.1 Piggyback board top view*).
On the device a triangle or the index area in the device marking is located on the corner near the A1 pin.
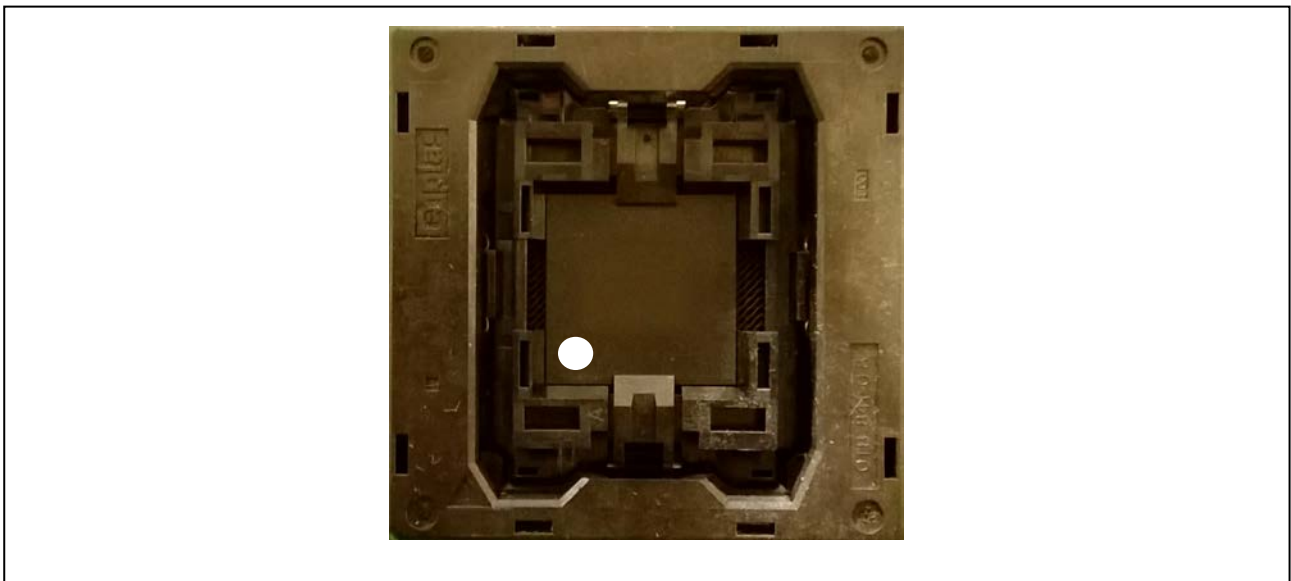
Figure 1.5 Enplas OTB-292(841R)-0.8-099-00 socket with mounted device

CAUTION

Be careful with the device placement in the socket to avoid damage to the device.

1.6 Modifications for RH850/U2A6 device

In order to use a RH850/U2A6 device with this piggyback board it is necessary to modify the board.

Following connections must be changed:

Device \\ Ball	U2A16/8	U2A/6	Item to be modified
J17	RX_DATA_P	VSS	RB2
K17	RX_DATA_N	VSS	RB1
H16	TX_DATA_P	E0VCC	RB3
J16	TX_DATA_N	E0VCC	RB3
K16	GETH0BVCC	E0VCC	JP2
G17	GETH0PVCC	E0VCC	JP3
H17	GETH0RVCC	E0VCC	JP22
E17	GETH0VCL	VSS	RB5

The jumpers JP2, JP3 and JP22 must have the same setting as JP6 (E0VCC).

The four 0R resistors RB1-RB4 are on the upper side of the pcb. The setting of RB1-RB4 for U2A16/8 or U2A6 use is printed on the pcb (Fig. 1.6).
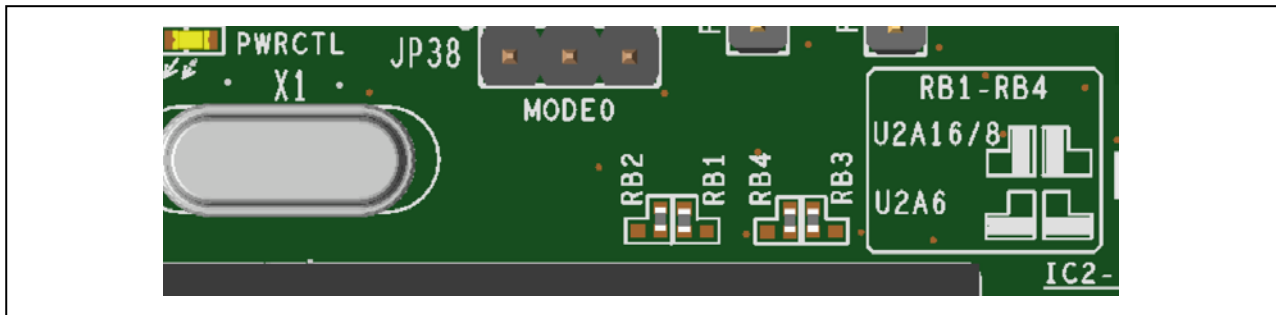
Figure 1.6 RB1-RB4 setting

On the lower side of the pcb there is preparation to add a solder bridge for the connection of RB5.
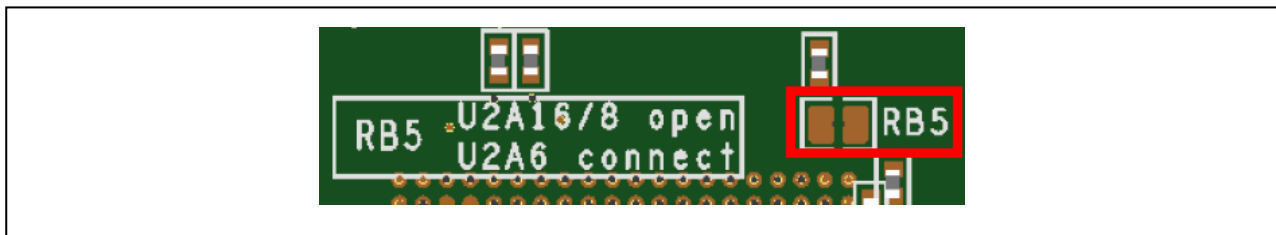
Figure 1.7 RB5 setting

1.7 Difference from Y-RH850-U2A-292PIN-PB-T1-V1 to Y-RH850-U2A-292PIN-PB-T1-V2

Several changes have been applied to the new version of the 292pin RH850/U2A piggyback board compared to the first version. The table below summarizes all modifications.

Table 1.3 Difference between Y-RH850-U2A-292PIN-PB-T1-V1 and Y-RH850-U2A-292PIN-PB-T1-V2

Item	Y-RH850-U2A-292PIN-PB-T1-V1	Y-RH850-U2A-292PIN-PB-T1-V2
Pin J17	Connected to RX_DATA_N	Connected to RX_DATA_P
Pin K17	Connected to RX_DATA_P	Connected to RX_DATA_N
Pin H16	Connected to TX_DATA_N	Connected to TX_DATA_P
Pin J16	Connected to TX_DATA_P	Connected to TX_DATA_N
Decoupling capacitors C41 and C44	Placed between Ethernet transceiver and bridges RB3/RB4	Placed between RH850/U2A and bridges RB3/RB4
Decoupling capacitors C41, C44, C47, C48	Value 100nF	Value 4.7nF
Resistor R34	Uses 100 Ohm resistor to connect RX_DATA_N and RX_DATA_P	The pcb provides soldering points to add a resistor between RX_DATA_N and RX_DATA_P, but by default this resistor is not fitted.
Pins A12/P12: AWOVCL	Both pins are directly connected to AWOVCL on the board.	A18 is connected to AWOVCL via 100 Ohm resistor. A18 and P12 are connected to VSS.
Pin E17: GETH0VCL	Connected directly to GETH0VCL on the board.	Connected to GETH0VCL via 100 Ohm resistor and has a 220nF capacitor to VSS. Provides the possibility to connect pin E17 to VSS via solder bridge RB5.
Supported devices	RH850/U2A16 RH850/U2A8	RH850/U2A16 RH850/U2A8 RH850/U2A6 (see *1.6 Modifications for U2A6 device*)

2.   Jumpers, Connectors and LEDs

This section provides complete lists of all jumpers, connectors and LEDs.

The placement of these components on the board is depicted in the figure below.
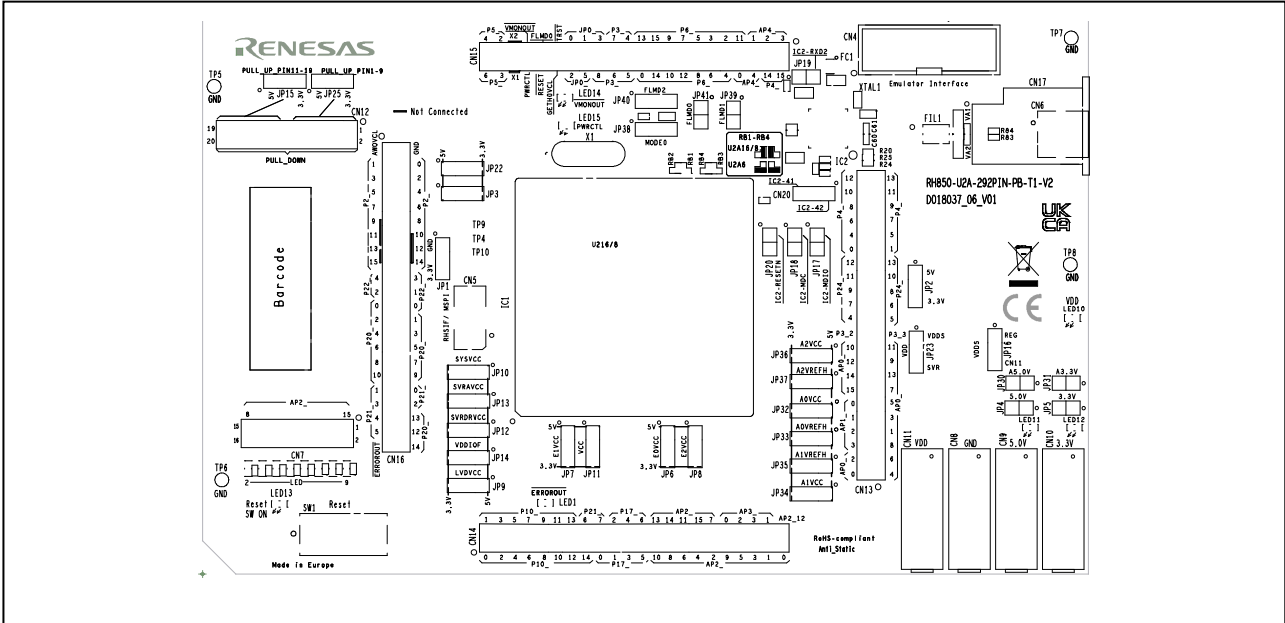
Figure 2.1 Placement of jumpers, connectors and LEDs
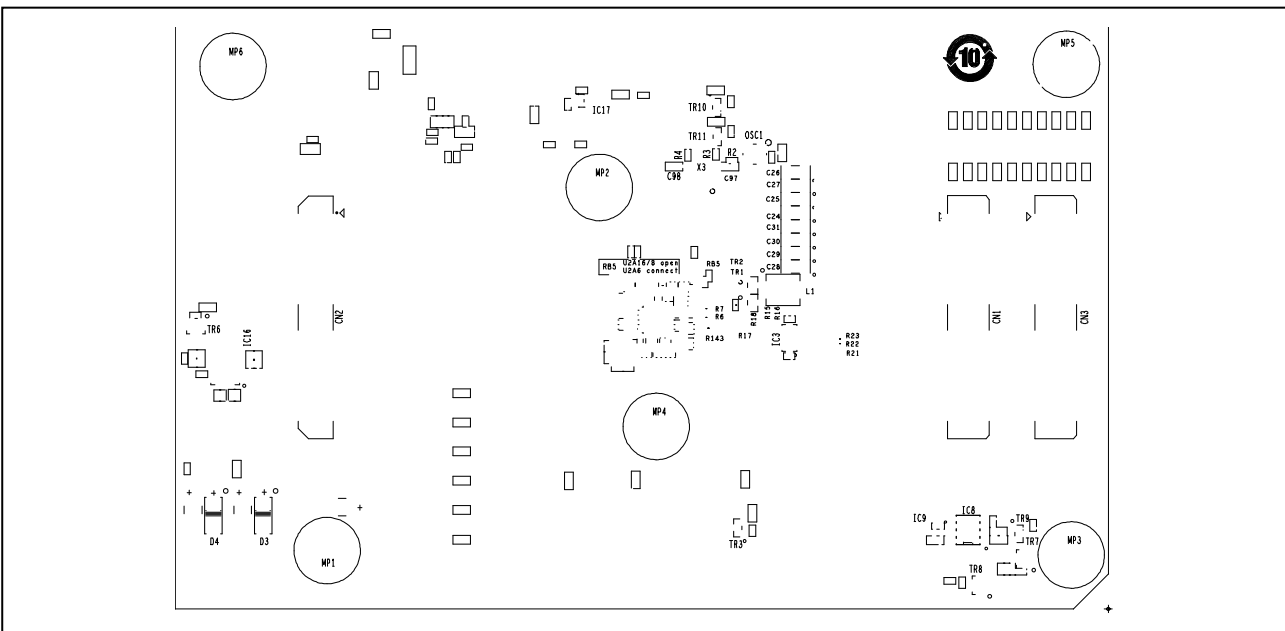
Figure 2.2 Placement of connectors on bottom side

2.1 Jumper Overview

The following table provides an overview of all jumpers.

Table 2.1 Jumper overview

Jumper	Function	Remark
JP1	RHSIF I/F Rx/Tx signals swap • JP1[2-1]: RXDP/RXDN at pins 7 and 9 of CN5, TXDP/TXDN at pins 1 and 3 of CN5 • JP1[2-3]: RXDP/RXDN at pins 1 and 3 of CN5, TXDP/TXDN at pins 7 and 9 of CN5	refer to *6.6 Renesas High-Speed Serial I/F (RHSIF) / Multichannel Serial Peripheral Interface (MSPI)*
JP2	For processor U2A16/8: Voltage selection for GETH0BVCC • JP2[2-3]: 3.3 V For processor U2A6: Voltage selection for E0VCC (must be same as JP6) • JP2[2-1]: 5.0 V • JP2[2-3]: 3.3 V	refer to *3.2 Voltage Distribution*
JP3	For processor U2A16: Voltage selection for GETH0PVCC • JP3[2-3]: 3.3 V For processor U2A8/6: Voltage selection for E0VCC (must be same as JP6) • JP3[2-1]: 5.0 V • JP3[2-3]: 3.3 V	
JP4	Current measurement bridge of 5.0 V power rail	refer to *3.3 Current Measurement Bridges*
JP5	Current measurement bridge of 3.3 V power rail	
JP6	Voltage selection for E0VCC • JP6[2-1]: 5.0 V • JP6[2-3]: 3.3 V	refer to *3.2 Voltage Distribution*
JP7	Voltage selection for E1VCC • JP7[2-1]: 5.0 V • JP7[2-3]: 3.3 V	
JP8	Voltage selection for E2VCC • JP8[2-1]: 5.0 V • JP8[2-3]: 3.3 V	
JP9	Voltage selection for LVDVCC • JP9[2-1]: 5.0 V • JP9[2-3]: 3.3 V	
JP10	Voltage selection for SYSVCC • JP10[2-1]: 5.0 V • JP10[2-3]: 3.3 V	
JP11	Voltage selection for VCC • JP11[2-1]: 5.0 V • JP11[2-3]: 3.3 V	
JP12	Voltage selection for SVRDRVCC • JP12[2-1]: 5.0 V • JP12[2-3]: 3.3 V	

Table 2.1 Jumper overview (cont'd)

Jumper	Function	Remark
JP13	Voltage selection for SVRAVCC • JP13[2-1]: 5.0 V • JP13[2-3]: 3.3 V	refer to *3.2 Voltage Distribution*
JP14	Voltage selection for VDDIOF • JP14[2-1]: 5.0 V • JP14[2-3]: 3.3 V	
JP15	Voltage selection for Pull-up/Pull-down pin header CN12 pins 11, 13, 15, 17, 19 • JP15[2-1]: 5.0 V • JP15[2-3]: 3.3 V	refer to *6.4 Pull-Up/Pull-Down Pin Header*
JP16	Voltage selection for 1.12 V VDDs * • JP16[2-1]: reg_vcc_VDD • JP16[2-3]: IN_1v12	refer to *3.4 Device Core Voltage (VDD) Selection*
JP17	Marvell MDIO – U2A P3_7 • JP17[2-1]: Connected • JP17[OPEN]: Open	
JP18	Marvell MDC – U2A P3_6 • JP18[2-1]: Connected • JP18[OPEN]: Open	
JP19	Marvel RxD2 Pull down • JP19[2-1]: Connected • JP19[OPEN]: Open	refer to *3.2 Voltage Distribution*
JP20	Marvell RESETn - U2A AP0_8 • JP20[2-1]: Connected • JP20[OPEN]: Open	
JP22	For processor U2A16: Voltage selection for GETH0RVCC • JP22[2-1]: 5.0 V • JP22[2-3]: 3.3 V For processor U2A8/6: Voltage selection for E0VCC (must be same as JP6) • JP22[2-1]: 5.0 V • JP22[2-3]: 3.3 V	refer to *3.2 Voltage Distribution*
JP23	Voltage selection for VDD • JP23[2-1]: VDDs • JP23[2-3]: SVR_OUTPUT	refer to *3.4 Device Core Voltage (VDD) Selection*
JP25	Voltage selection for Pull-up/Pull-down pin header CN12 pins 1, 3, 5, 7, 9 • JP25[2-1]: 5.0 V • JP25[2-3]: 3.3 V	refer to *6.4 Pull-Up/Pull-Down Pin Header*
JP30	Current measurement bridge of 5.0 V A/D Converter power supply	refer to *3.3 Current Measurement Bridges*
JP31	Current measurement bridge of 3.3 V A/D Converter power supply	
JP32	Voltage selection for A0VCC • JP32[2-1]: 5.0 V • JP32[2-3]: 3.3 V	refer to *3.2 Voltage Distribution*

Table 2.1 Jumper overview (cont'd)

Jumper	Function	Remark
JP33	Voltage selection for A0VREFH • JP33[2-1]: 5.0 V • JP33[2-3]: 3.3 V	refer to *3.2 Voltage Distribution*
JP34	Voltage selection for A1VCC • JP34[2-1]: 5.0 V • JP34[2-3]: 3.3 V	
JP35	Voltage selection for A1VREFH • JP35[2-1]: 5.0 V • JP35[2-3]: 3.3 V	
JP36	Voltage selection for A2VCC • JP36[2-1]: 5.0 V • JP36[2-3]: 3.3 V	
JP37	Voltage selection for A2VREFH • JP37[2-1]: 5.0 V • JP37[2-3]: 3.3 V	
JP38	MODE0 level selection • JP38[2-1]: H level • JP38[2-3]: L level	refer to *6.1 Operation Mode Selection*
JP39	FLMD1 level selection • JP39[2-1]: H level • JP39[OPEN]: L level	
JP40	FLMD2 level selection • JP40[2-1]: H level • JP40[2-3]: L level	

JP41	FLMD0 level selection
	• JP41[2-1]: H level
	• JP41[OPEN]:
	  – if no debug/programming tool connected: L level
	  – controlled by debug/programming tool, if tool connected:	

Note: *   Refer to *3.3 Device Core Voltage (VDD) Selection* for further details about VDD voltage.

2.2   Connectors Overview

The following table provides an overview of all connectors.

Table 2.2 Connectors overview

Connector	Function	Remark
CN1	Main Board connectors	refer to *7.1 Connectors to the Main Board CN1 to* CN3
CN2		
CN3		
CN4	Debug connector	refer to *5 Debug and Flash Programming Interfaces* and *7.2 Debug Connector CN4*
CN5	RHSIF & MSPI connector	refer to *6.6 Renesas High-Speed Serial I/F (RHSIF) / Multichannel Serial Peripheral Interface (MSPI)* and *7.3 RHSIF/MSIP Connector CN5*
CN6	Ethernet interface connector	refer to *6.5 Automotive Ethernet Interface* and *7.6 Ethernet Connectors CN6* and CN17
CN7	Signaling LEDs pin header	refer to *6.3 Signalling LEDs*
CN8	GND for external power supply	refer to *3.1 Board Power Connection,* connectors are not assembled on the board
CN9	+5.0 V external power supply	
CN10	+3.3 V external power supply	
CN11	+1.12 V external power supply *	
CN12	Pull-up/Pull-down pin header	*refer to 6.4 Pull-Up/Pull-Down Pin Header* and *7.5 Pull-Up/Pull-Down Pin Header CN12*
CN13	Device ports connectors	refer to *7.4 Device Ports Connectors CN13 to CN16*
CN14		
CN15		
CN16		
CN17	Ethernet interface connector	refer to *6.5 Automotive Ethernet Interface* and *7.6 Ethernet Connectors CN6* and CN17
CN20	GPIO/LED output	refer to *7.7 GPIO/LED Connector CN20*

Note: *   Refer to *3.3 Device Core Voltage (VDD) Selection* for further details about VDD voltage.

2.3 LED Overview

The following table provides an overview of all LED.

Table 2.3 LED overview

LED	Function	Color	Remark
LED1	Device ERROROUT signal	red	
LED2	Signaling LED	yellow	connection via CN7, refer to *6.3 Signalling LEDs*
LED3	Signaling LED		
LED4	Signaling LED		
LED5	Signaling LED		
LED6	Signaling LED		
LED7	Signaling LED		
LED8	Signaling LED		
LED9	Signaling LED		
LED10	1.12 V device core voltage VDD	green	refer to *3.5 Power Supply LEDs*
LED11	5.0 V power supply P5V0	green	
LED12	3.3 V power supply P3V3	green	
LED13	Reset switch SW1 on	red	
LED14	Device VMONOUTZ signal	red	
LED15	Device PWRCTL signal	red	

3. Power Supply

3.1   Board Power Connection

The device and the board require various power supply voltages:

- 3.3 V for most of the digital circuitry on the device and on the board

- 5 V in case some ports shall be operated with 5 V I/O voltage

- 1.12 V for the device's VDD core voltage supply
  Refer to *3.4 Device Core Voltage (VDD) Selection* for further details about VDD voltage.

Note

Within this document all voltage values are considered as 'typical'.

Refer to the 'Electrical Characteristics' section of the Hardware User's Manual for allowed voltage ranges.

The following connectors are available to supply external voltages:

- Four 4 mm 'banana-type' connectors are used to connect external power supplies:
  - black connector CN8 for GND (VSS)
  - red connector CN9 for 5 V
  - red connector CN10 for 3.3 V
  - red connector CN11 for 1.12 V
    Refer to *3.4 Device Core Voltage (VDD) Selection* for further details about VDD voltage.

The connectors CN8, CN9 and CN10 are assembled in production.

Connector CN11 is not assembled in production but separately supplied with the board package.

In case the piggyback board is mounted on a Main Board, all voltages except for 1.12 V (VDD) are supplied by the Main Board.

CAUTION

Do not power on the piggyback board when no RH850 microcontroller is installed in socket IC1 because the switching regulator in the SVR power supply circuit doesn't have defined control signals when the microcontroller is not installed and may be damaged.

If you want to power on the piggyback board without microcontroller, make sure jumper JP12[1-2-3] (SVRDRVCC) is open.

Do not supply the 5 V (CN9) and 3.3 V (CN10) voltage directly to the piggyback board in case it is mounted on the Main Board.

Connecting external 1.12 V via CN11 (and GND via CN8) is still an option also in this case.

For some general power supply scenarios, the jumper settings are described in *8 Jumper Configuration Examples*.

3.2   Voltage Distribution

The following table shows the required device power supply pins and their function:

Table 3.1 Device power supply pins

Device power supply pin	Voltage	Function
E0VCC, E1VCC, E2VCC	3.3 V, 5 V	Power supply for I/O ports
LVDVCC	3.3 V, 5 V	Power supply for LVDS ports
SYSVCC	3.3 V, 5 V	Power supply for • System Logic and internal voltage regulator power • I/O ports
VCC	3.3 V, 5 V	Power supply for on-chip flash memory
SVRDRVCC	3.3 V, 5 V	Power supply for on-chip Switching Voltage Regulator (SVR)
SVRAVCC	3.3 V, 5 V	
VDDIOF	3.3 V, 5 V	I/O voltage supply for the Main Board
GETH0PVCC	3.3 V, 5V	Power supply for Ethernet domain (for U2A16 only)
GETH0BVCC	3.3 V, 5V	
GETH0RVCC	3.3 V, 5V	
A0VCC, A1VCC, A2VCC	3.3 V, 5 V	A/D Converter's power supplies and reference voltages
A0VREFH, A1VREFH, A2VREFH,	3.3 V, 5 V	
VDD	1.12 V *	Core supply voltage

Note: *   Refer to *3.4 Device Core Voltage (VDD) Selection* for further details about VDD voltage.

Each of the above voltages can be selected from

• 5.0 V, 3.3 V (where applicable, see table above)

by a set of jumpers. For details refer to the figure below and *Table 2.1 Jumper overview*
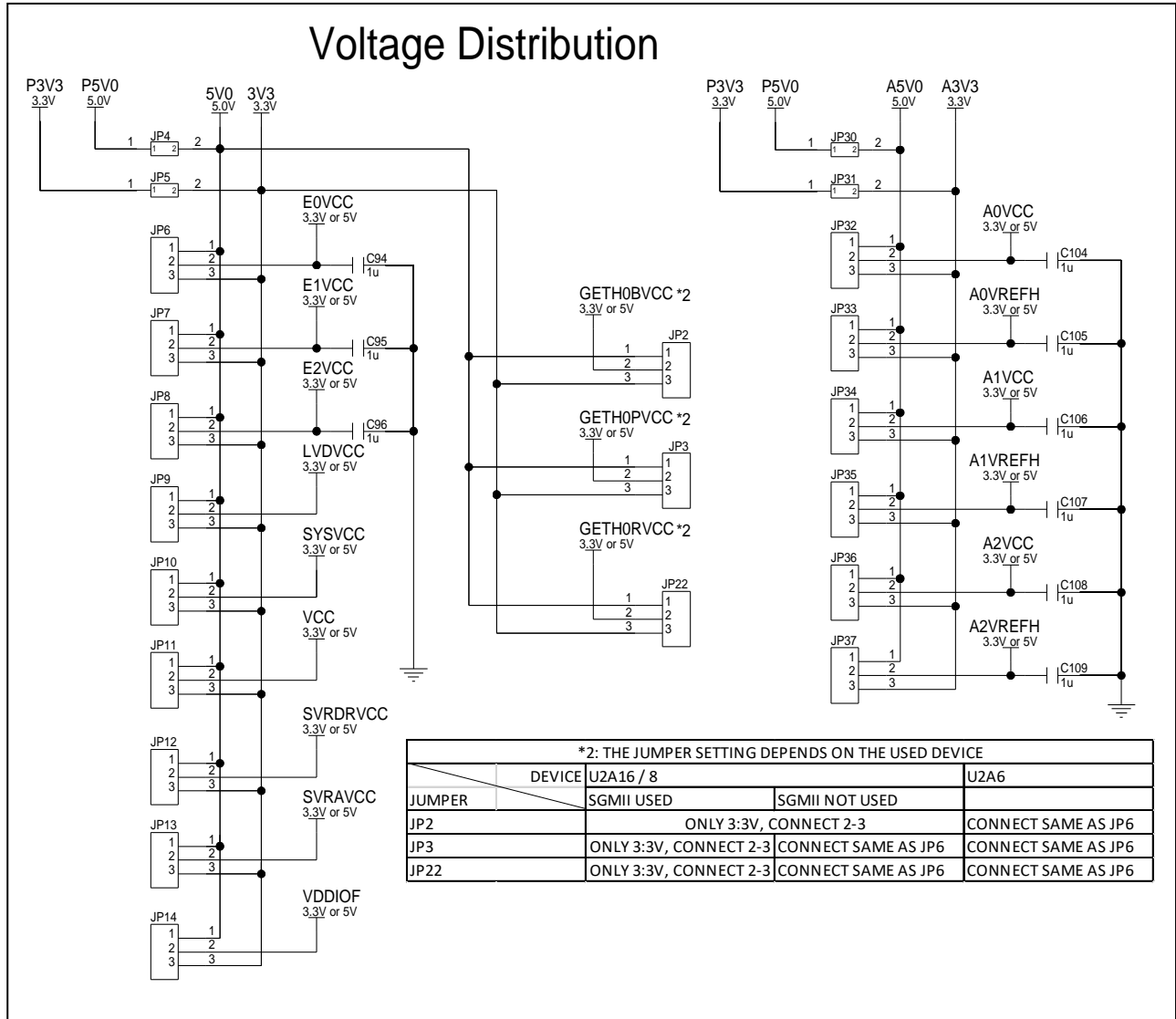
Figure 3.1 Voltage distribution

3.3   Current Measurement Bridges

The total current of the 5V0 and 3V3 power rails can be measured by replacing the jumpers JP4 and JP5 with a current meter.

Accordingly, the total current via the A/D Converter's supply voltages A5V0 and A3V3 can be measured via the jumpers JP30 and JP31 respectively.

The current of particular power supply pins of the device can be measured via their respective supply selection jumpers, refer to *Figure 3.1 Voltage distribution*.

3.4   Device Core Voltage (VDD) Selection

The device core voltage VDD (typ.1.12 V) can be

- supplied from external via CN11 (voltage IN_1v12)

- generated from the P3V3 power rail by use of the on-board voltage regulator IC16 (voltage reg_vcc_VDD)

- generated by the on-chip Switching Voltage Regulator (SVR) in combination with device external power transistors TR1, TR2 (voltage SVR_OUTPUT)

Note

The IN_1v12 and reg_vcc_VDD voltages have a level of typical 1.12 V, which is higher than the typical device core voltage VDD of 1.09 V. The 30 mV difference is supposed to compensate voltage drops over the power rails on the board, in particular over the jumpers.

Selection of the VDD source is achieved by use of the jumpers JP23 and JP16:

- JP23[2-1]: VDD = 1.12 V (VDDs) from
  - JP16[2-1]: VDDs = reg_vcc_VDD from on-board voltage regulator IC16
  - JP16[2-3]: VDDs = IN_1v12 from external supply CN11

- JP23[2-3]: VDD = 1.09 V (SVR_OUTPUT)

Note

If *JP23[2-3]: VDD = 1.09 V (SVR_OUTPUT)* is selected as core voltage it is not possible to operate the device in DeepSTOP mode. Please refer to the precaution in *9.3 DeepSTOP Mode when using SVR* for details.
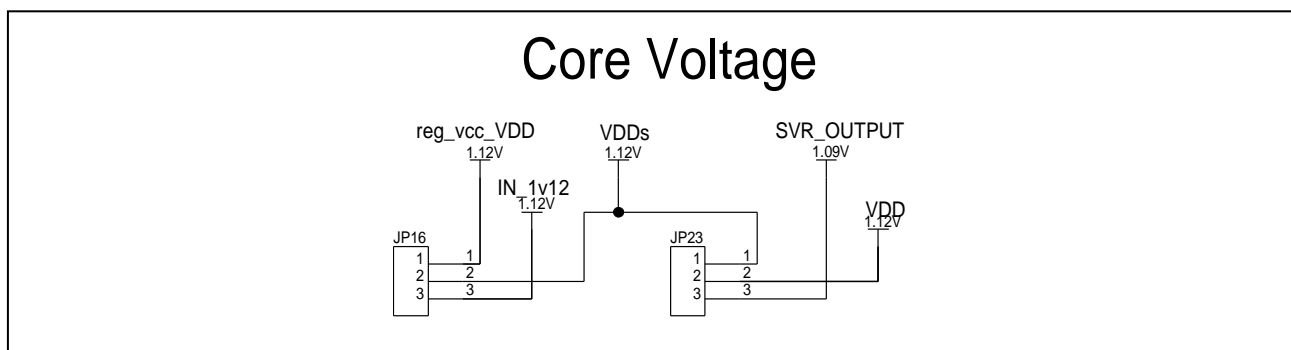
Figure 3.2 Device core voltage (VDD) selection

3.5   Power Supply LEDs

The following green LEDs indicate the presence of various voltages on the piggyback board:

- LED11 for 5.0 V power rail P5V0

- LED12 for 3.3 V power rail P3V3

- LED10 for 1.12 V device core voltage VDD

4. Clock Supply

The device's operation clock can be generated by

- the on-chip main oscillator circuit in combination with an off-chip resonator, connected to the X1, X2 terminals.

- an off-chip oscillator where the clock is fed into the X1 terminal.
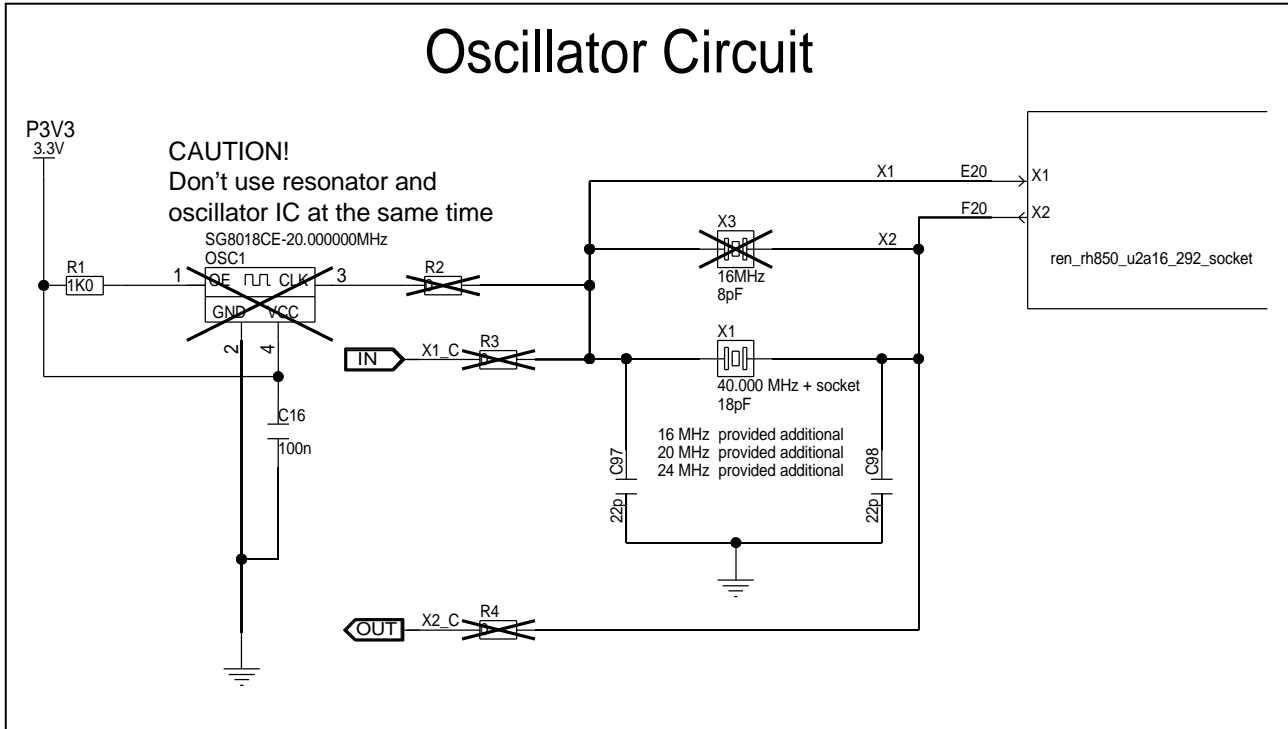
Figure 4.1 Clock supply

4.1   Main Oscillator

For operating the on-chip main oscillator the piggyback board provides a socket (X1) for a resonator.

Optionally a resonator (X3) can be soldered on the board, refer to the figure above.

Crystal resonators for various main oscillator frequencies (16 MHz, 20 MHz, 24 MHz, 40 MHz) are included in the board package.

The 40MHz crystal resonator is by default mounted to X1.

For package content please refer to *1.1 Package Components*

CAUTION

Only one oscillator, either X1 or X3, can be used at any one time for the main oscillator.

4.2   Programmable Oscillator

Instead of using the on-chip main oscillator a programmable crystal oscillator (OSC1) circuit can be soldered on the board.

The available footprint and circuitry is designed for a SG-8002CE programmable crystal oscillator from Epson Toyocom. The output of this oscillator can be connected to X1 terminal via resistor R2.

The SG-8002CE is neither mounted on nor provided with the board. For details about the available circuitry, refer to *Figure 4.1 Clock supply*.

CAUTION

A resonator mounted on socket X1 or soldered on X3 must not be used in parallel to another clock source.

4.3   X1 and X2 on CN15

To minimize disturbance on the resonator signal the signals X1 and X2 are by default not connected to a pin header. If needed the signals can be connected to CN15 via 0 Ω resistors:

- X1: Pin 40 of CN15 to supply an external clock to the device via R3
- X2: Pin 39 of CN15 for measurement purposes of the clock via R4

5. Debug and Flash Programming Interfaces

For debugging and flash programming purposes debug and flash programming tools can be connected to the CN4 connector.

Refer to *7.2 Debug Connector CN4* for details about the CN4 pin assignment.

The Renesas standard emulator for RH850/U2A is the E2 emulator. This can be used as emulator for debugging or as flash programmer.
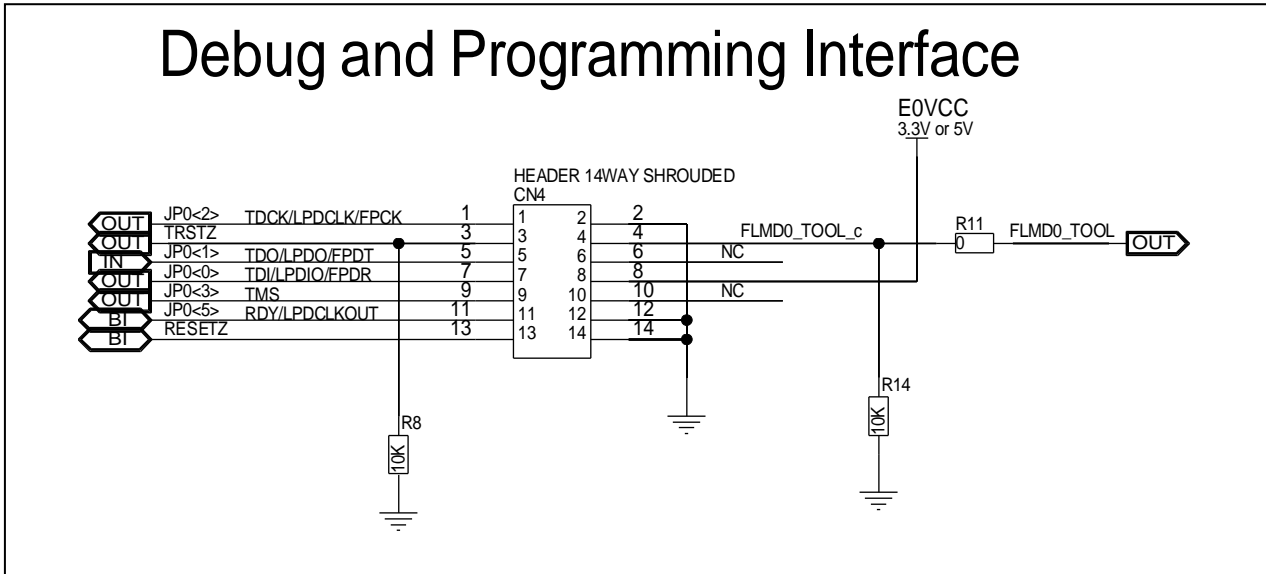
Figure 5.1 Connection for debugger and flash programmer

6.   Other Circuitry

6.1   Operation Mode Selection

The piggyback board gives the possibility to configure the following jumpers for selection of the device operation mode:

Table 6.1 Device operation mode selection jumpers

Jumper	Function
JP38	MODE0 pin level • JP38[2-1]: MODE0 = H level • JP38[2-3]: MODE0 = GND

JP41	FLMD0 pin level
	
	• JP41[SHORT]: FLMD0 = H level
	
	• JP41[OPEN]: FLMD0
	
	   − controlled by debugger or programming tool, if a tool is connected via CN4
	
	   − GND, if no tool connected

JP39	FLMD1 pin level
	
	• JP39[SHORT]: FLMD1 = H level
	   − Port function of port P6_13 can be used
	• JP39[OPEN]: FLMD1 = L level
	   − JP39 must be open if Serial Programming Mode is used by a debugger or flash programming tool, that is connected to the board

JP40	FLMD2 pin level • JP40[2-1]: FLMD2 = H level • JP40[2-3]: FLMD2 = GND

CAUTION

Be careful in configuration of the operation mode related pins. The wrong configuration and operation of the device outside of its specification can cause irregular behavior of the device and long-term damage cannot be excluded. Be sure to check the corresponding Hardware User's Manual for details, which modes are specified for the used device.

Note

In most cases the 'normal operating mode' of the device will be used.
This mode is for execution of the user program. The on-chip debug functions also use this mode.

To select the 'normal operating mode' of the device, the FLMD0 pin must be pulled low. To do so, remove the jumper JP41.

All other jumpers related to the mode selection can be left open.

6.2   RESET Switch

The SW1 is used to issue a RESET to the device.

The SW1 toggle switch allows to activate the RESET in two different ways:

- SW1 in left '2-1(ON)' position: temporary reset
  Releasing the switch's lever returns the switch to its middle 'OFF' position and thus releases the reset.

- SW1 in right '2-3 ON' position: permanent reset
  For reset release the switch has to be moved back manually to its middle 'OFF' position.
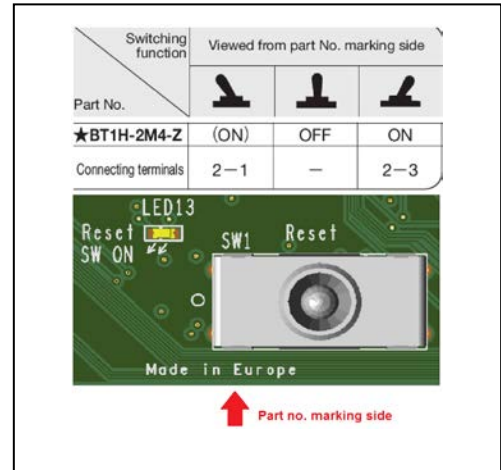
Figure 6.1 Reset switch

The left and right switch position is defined from the side of the part number marking, which is highlighted with a red arrow in *Figure 6.1*.

The lighted red LED13 indicates that SW1 is "on", i.e. in position '2-1 (ON)' or '2-3 ON'.

Note

LED13 does not light up when RESET is asserted by any other means than SW1.

Figure 6.2 shows the complete RESET circuit.
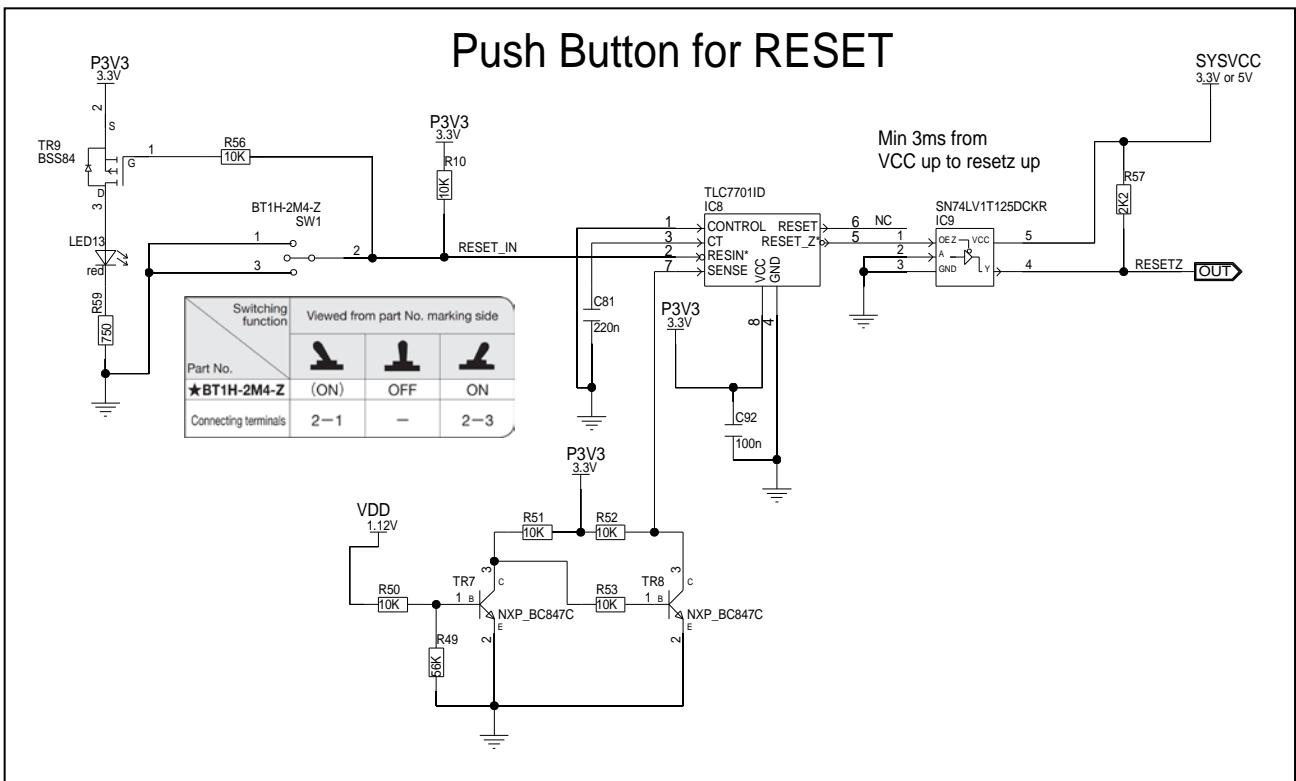
Figure 6.2 Reset circuit

6.3   Signalling LEDs

Eight LEDs are provided to allow visual observation of the output state of device port pins.

Device pins AP2_8 to AP2_15 are connected to the odd pins of the pin header CN7, while the LEDs 2 to 9 are connected to the even CN7 pins.

Thus, the LEDs can be either connected to

- the device port pins Ap2_8 to AP2_15 by closing the connection on CN7 using a jumper, or
- any device pin by connecting directly with the even CN7 pins using a separate cable.

Figure 6.3 shows the circuit for the signalling LEDs.
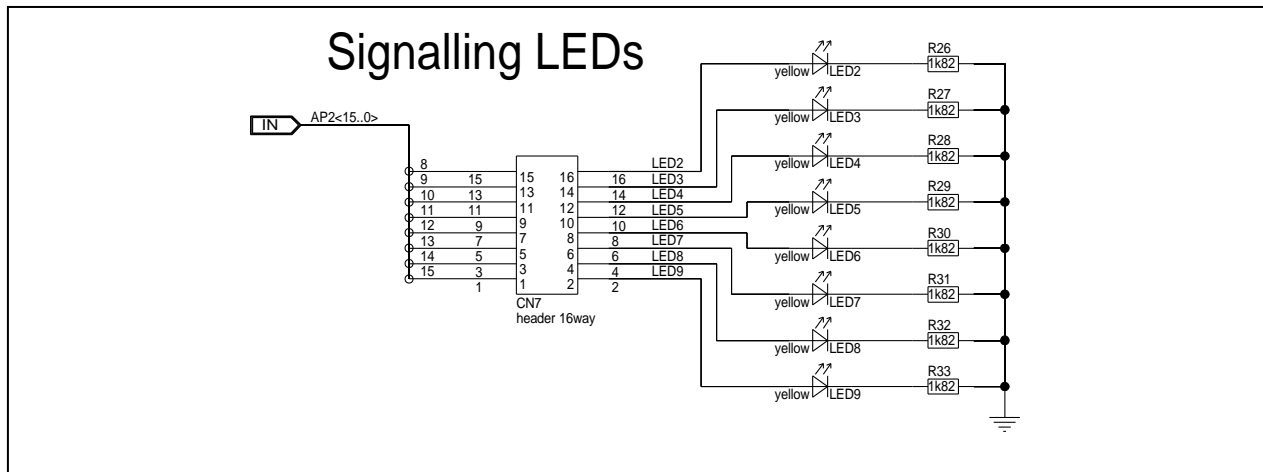
Figure 6.3 Signalling LEDs

6.4   Pull-Up/Pull-Down Pin Header

The Pull-up/Pull-down pin header CN12 provides fixed voltage levels at its pins, that can be used to pull-up/pull-down a signal on the board or the device, respectively, by connecting a CN12 pin to the signal via a separate cable.

The CN12 pins have following pull-up or pull-down voltage levels:

- all even numbered pins are connected to L level, i.e. to GND
- odd numbered pins 1, 3, 5, 7, 9 can be connected to
  - 5.0 V, if JP25[2-1] is set
  - 3.3 V, if JP25[2-3] is set
- odd numbered pins 11, 13, 15, 17, 19 can be connected to
  - 5.0 V, if JP15[2-1] is set
  - 3.3 V, if JP15[2-3] is set

Refer to *7.5 Pull-Up/Pull-Down Pin Header CN12* for CN12 details.

Figure 6.4 shows the circuit for the pull-up an pull-own resistors.
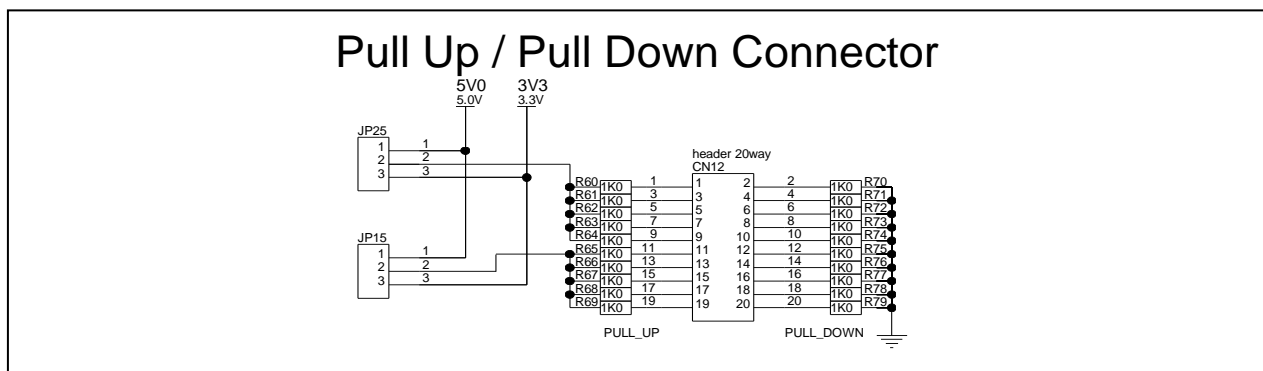
Figure 6.4 Pull-Up/Pull-own resistor circuit

6.5   Automotive Ethernet Interface

The piggyback board features a Marvell 88Q2112 Automotive Ethernet PHY (IC2) for using the device's SGMII interface (ETNB1) via the TE MateNet connector on CN17 or straight wires on block connector CN6.

If the TE MateNet connector should be used connector CN17 has to be assembled with the connector included in the delivery.

Please refer to *Figure 6.5 Ethernet connector CN17* for the placement of the connector.
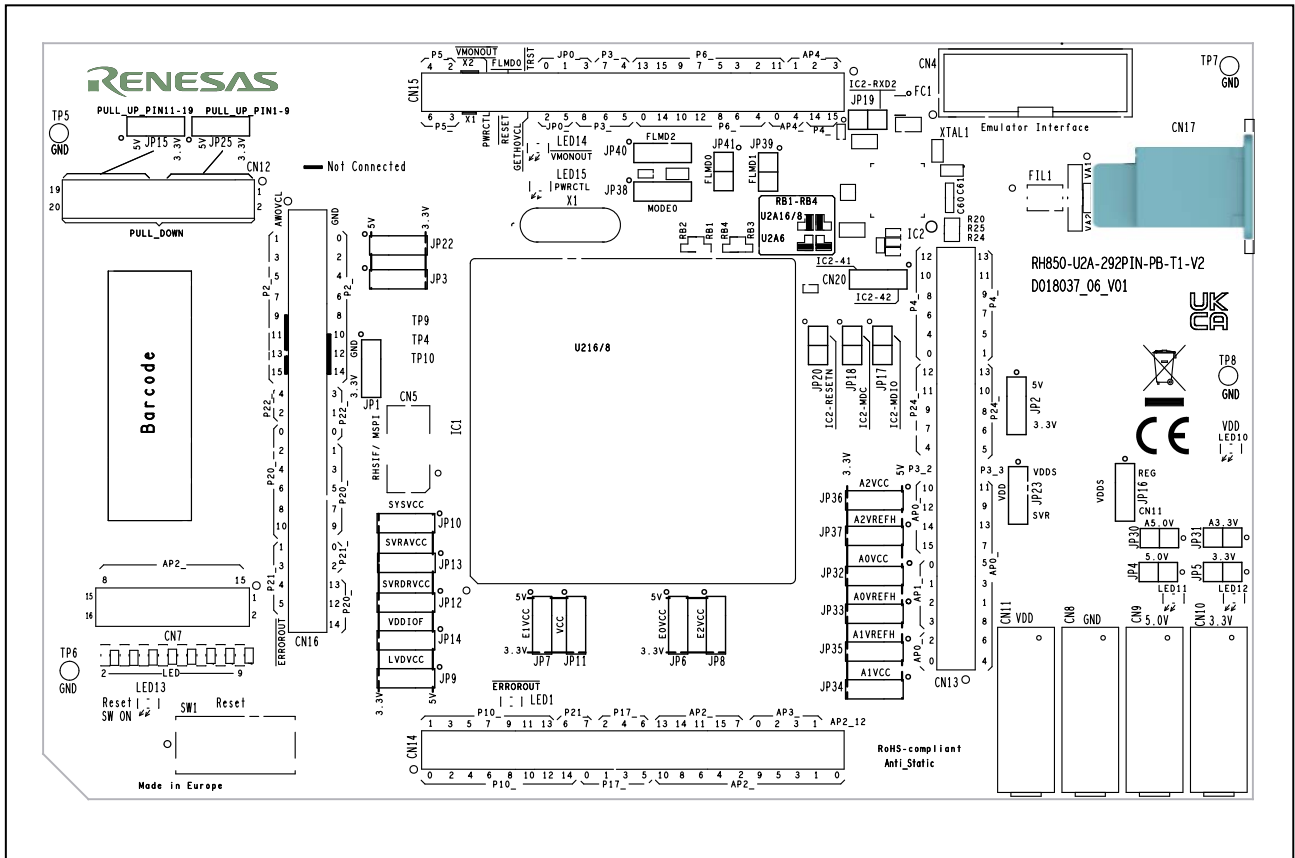
 Figure 6.5 Ethernet connector CN17

If a 2-wire connection should be used connector CN6 has to be assembled with the Würth block connector included in the delivery.

In order to use CN6 it is necessary to populate the resistors R83 and R84 with 0 Ω resistors.

Please refer to *Figure 6.6 Ethernet connector CN6* for the placement of the connector.
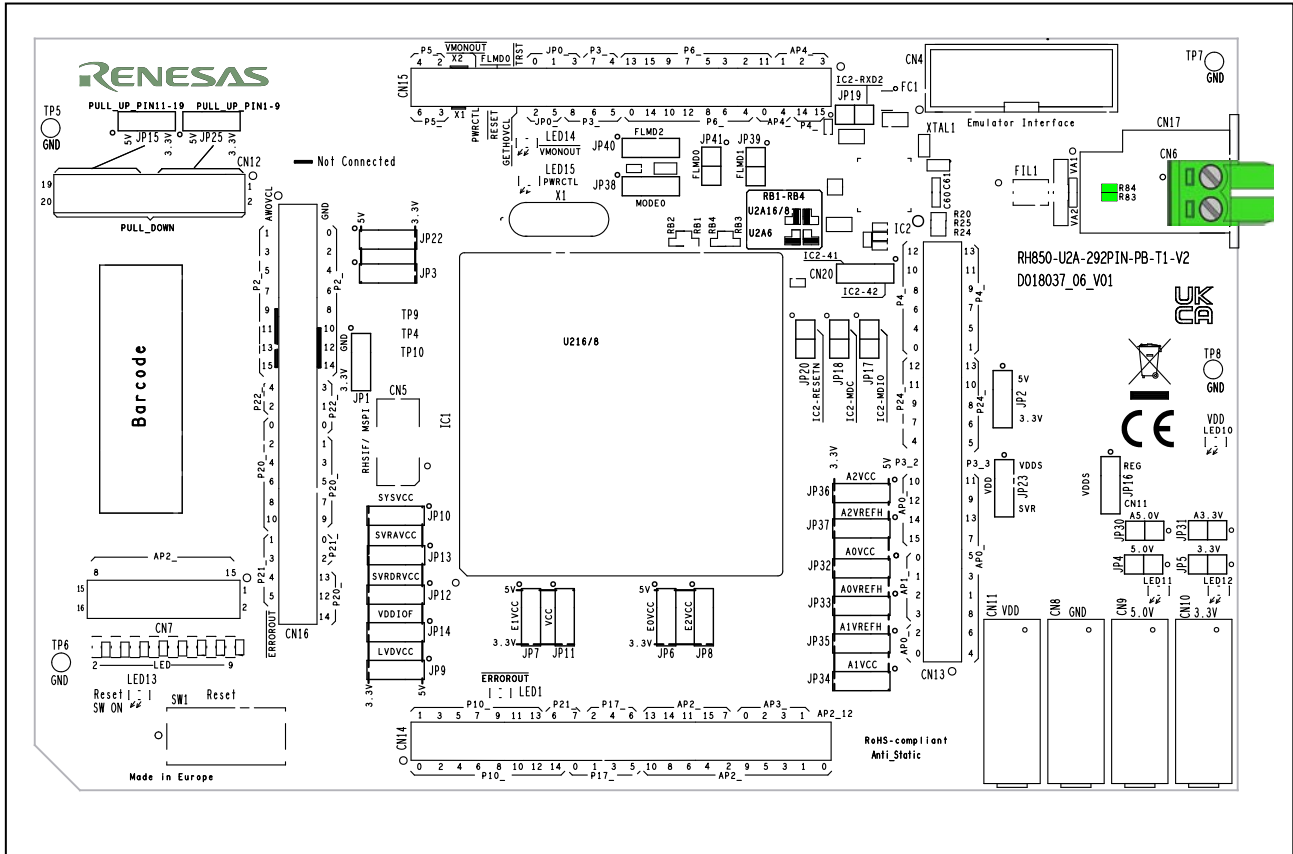
Figure 6.6 Ethernet connector CN6

Notes

1. For ETNBx initial setup please refer to the device UM. For ETNB1 operation the ETNB1SGCLKSEL register must be set to ETNB1SGCLKSEL=0x01 to select the Internal MOSC clock of 20MHz.
    For an internal MOSC clock of 20MHz the crystal X1 has to be replaced by the 20MHz crystal included in the package.
    For package content please refer to *Table 1.1 Package Components for the Y-RH850-U2A-292PIN-PB-T1-V2*

2. The signals of the device's Fast Ethernet (R)MII interface (ETNB0) are available on the Main Board connectors. Thus, ETNB0 can control an Ethernet PHY on the Main Board.

3. Alternatively, ETNB1 can also be used to operate the Main Board's 100 MB Ethernet PHY. In this case the ETNB1 Fast Ethernet mode is selected by Option Bytes settings and the pin multiplexing needs to be configured accordingly.

Refer to *7.6 Ethernet Connectors CN6 and CN17* for the CN6 and CN17 pin assignment.

6.6   Renesas High-Speed Serial I/F (RHSIF) / Multichannel Serial Peripheral Interface (MSPI)

The CN5 connector can be used to connect to the device's RHSIF and MSPI0 interface.

Refer to *7.3 RHSIF/MSIP Connector CN5* for the CN5 pin assignment.

RHSIF and MSPI0 interface at CN5 are operated in LVDS mode.

Rx and Tx signals available at CN5 can be swapped by setting the jumper JP1:

- JP1[2-1]:
  - RXDP/RXDN at CN5 pins 7 and 9
  - TXDP/TXDN at CN5 pins 1 and 3
- JP1[2-3]:
  - RXDP/RXDN at CN5 pins 1 and 3
  - TXDP/TXDN at CN5 pins 7 and 9

Figure 6.7 shows the circuit diagram for RHSIF an MSPI interface.
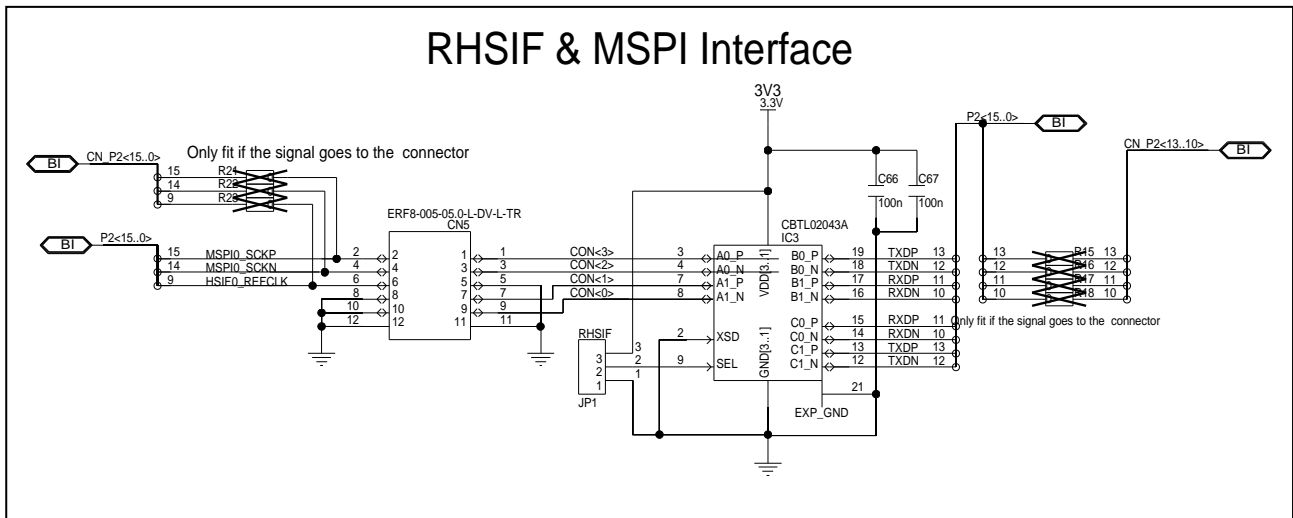
Figure 6.7 RHSIF and MSPI interface circuit

Notes

1. In order to minimize signal interference no signals from CN5 are connected to CN16. If required they can be connected via 0 Ω resistors R15 to R18 and R21 to R23.

2. Swapping the Rx/Tx signals allows board-to-board communication e.g. with another piggyback board via separate cables.

7. Connectors

7.1 Connectors to the Main Board CN1 to CN3

Three connectors (CN1 to CN3) are available to connect the piggyback board to a Main Board.

The signals of each connector are summarized in the following tables.

Note

Regarding the function on the Main Board, please refer to the User's Manual of any supported Main Board.
Refer to *1.2 Supported Main Boards* for a list of supported Main Boards.

7.1.1 Main Board Connector CN1

Table 7.1 Main board connector CN1

Pin	Main Board function	Piggyback board device port	Pin	Main Board function	Piggyback board device port
1	VDDA	–	2	VDDA	–
3	VDDA	–	4	VDDA	–
5	RESET	RESETZ	6	NMI	P4_7
7	WAKE	–	8	–	–
9	INT0	P10_12	10	INT1	P22_0
11	INT2	P21_7	12	INT3	P2_8
13	–	–	14	–	–
15	UART0TX	P6_6	16	UART1TX	P6_3
17	UART0RX	P6_5	18	UART1RX	P6_2
19	LIN0TX	P4_8	20	LIN1TX	P2_5
21	LIN0RX	P4_9	22	LIN1RX	P2_4
23	IIC0SCL	P17_3	24	IIC1SCL	P22_4
25	IIC0SDA	P17_2	26	IIC1SDA	P22_3
27	CAN0TX	P6_14	28	CAN1TX	P6_8
29	CAN0RX	P6_13	30	CAN1RX	P6_7
31	SENT0RX	P21_1	32	SENT1RX	P21_0
33	SENT0SPCO	P24_6	34	SENT1SPCO	P24_7

Table 7.1 Main board connector CN1 (cont'd)

Pin	Main Board function	Piggyback board device port	Pin	Main Board function	Piggyback board device port
35	PSI5SRX0	P3_6	36	PSI5RX0	P5_4
37	PSI5STX0	P3_7	38	PSI5TX0	P5_6
39	PSI5SCLK0	P3_8	40	–	–
41	FLX0TX	P20_7	42	FLX0EN	P20_5
43	FLX0RX	P20_2	44	FLXSTPWT	P20_4
45	FLX1TX	P20_6	46	FLX1EN	P20_8
47	FLX1RX	P20_3	48	FLX CLK	P10_8
49	–	–	50	–	–
51	ETH0MDIO	P20_3	52	ETH0MDC	P20_6
53	ETH0RXD0	P10_3	54	ETH0TXD0	P20_9
55	ETH0RXD1	P10_4	56	ETH0TXD1	P20_10
57	ETH0RXD2	P10_5	58	ETH0TXD2	P20_12
59	ETH0RXD3	P10_6	60	ETH0TXD3	P20_13
61	ETH0RXCLK	P10_2	62	ETH0TXCLK	P10_1
63	ETH0RXER	P10_0	64	ETH0TXER	P20_8
65	ETH0CRSDV	P20_7	66	ETH0TXEN	P20_14
67	ETH0RXDV	P10_7	68	ETH0COL	–
69	ETH0RESET	P20_0	70	ETH0LINK	P20_1
71	–	–	72	–	–
73	USB0UDMF	–	74	USB0UDMH	–
75	USB0UDPF	–	76	USB0UDPH	–
77	–	–	78	–	–
79	–	–	80	–	–
81	–	–	82	–	–
83	–	–	84	–	–

Table 7.1 Main board connector CN1 (cont'd)

Pin	Main Board function	Piggyback board device port	Pin	Main Board function	Piggyback board device port
85	DIGIO_0	P21_2	86	DIGIO_1	P21_3
87	DIGIO_2	P21_4	88	DIGIO_3	P21_5
89	DIGIO_4	P21_6	90	DIGIO_5	P21_7
91	DIGIO_6	P22_0	92	DIGIO_7	P22_1
93	DIGIO_8	P22_2	94	DIGIO_9	P22_3
95	DIGIO_10	P10_8	96	DIGIO_11	P10_9
97	DIGIO_12	P10_10	98	DIGIO_13	P10_11
99	DIGIO_14	P10_12	100	DIGIO_15	P10_13
101	–	–	102	–	–
103	MUX0	P6_0	104	MUX1	P6_2
105	MUX2	P6_3	106	–	–
107	ADC0	AP4_0	108	ADC1	AP4_1
109	ADC2	AP4_2	110	ADC3	AP4_3
111	ADC4	AP4_4	112	ADC5	AP3_1
113	ADC6	AP3_2	114	ADC7	AP3_3
115	VDDIOF	–	116	VDDIOF	–
117	VDDB	–	118	VDDB	–
119	VDDB	–	120	VDDB	–

7.1.2   Main Board Connector CN2

Table 7.2 Main board connector CN2

Pin	Function	Device port	Pin	Function	Device port
1	CAN2TX	P3_2	2	CAN3TX	P4_4
3	CAN2RX	P3_3	4	CAN3RX	P4_5
5	CAN4TX	P4_6	6	CAN5TX	P4_11
7	CAN4RX	P4_7	8	CAN5RX	P4_12
9	LIN2TX	P2_0	10	LIN3TX	P4_14
11	LIN2RX	P2_1	12	LIN3RX	P4_15
13	LIN4TX	P6_12	14	LIN5TX	P2_2
15	LIN4RX	P6_15	16	LIN5RX	P2_3
17	LIN6TX	P2_7	18	LIN7TX	P3_5
19	LIN6RX	P2_6	20	LIN7RX	P3_4
21	LIN8TX	P4_0	22	LIN9TX	P5_3
23	LIN8RX	P4_1	24	LIN9RX	P5_2
25	LIN10TX	P6_5	26	LIN11TX	P3_8
27	LIN10RX	P6_4	28	LIN11RX	P3_7
29	LIN12TX	–	30	LIN13TX	–
31	LIN12RX	–	32	LIN13RX	–
33	LIN14TX	–	34	LIN15TX	–
35	LIN14RX	–	36	LIN15RX	–
37	–	–	38	–	–
39	CAN12TX	P24_10	40	CAN13TX	P24_12
41	CAN12RX	P24_11	42	CAN13RX	P24_13
43	CAN14TX	P17_3	44	CAN15TX	P17_5
45	CAN14RX	P17_4	46	CAN15RX	P17_6
47	CAN6TX	P4_14	48	CAN7TX	P3_4

Table 7.2 Main board connector CN2 (cont'd)

Pin	Function	Device port	Pin	Function	Device port
49	CAN6RX	P4_15	50	CAN7RX	P3_5
51	CAN8TX	P10_6	52	CAN9TX	P24_4
53	CAN8RX	P10_5	54	CAN9RX	P24_5
55	CAN10TX	P24_6	56	CAN11TX	P24_8
57	CAN10RX	P24_7	58	CAN11RX	P24_9
59	–	–	60	–	–
61	LIN16TX	–	62	LIN17TX	–
63	LIN16RX	–	64	LIN17RX	–
65	LIN18TX	–	66	LIN19TX	–
67	LIN18RX	–	68	LIN19RX	–
69	LIN20TX	–	70	LIN21TX	–
71	LIN20RX	–	72	LIN21RX	–
73	LIN22TX	–	74	LIN23TX	–
75	LIN22RX	–	76	LIN23RX	–
77	–	–	78	–	–
79	SFMA0CLK	P17_5	80	SFMA0SSL	P17_4
81	SFMA0IO0	P17_3	82	SFMA0IO1	P17_2
83	SFMA0IO2	P17_1	84	SFMA0IO3	P17_0
85	–	–	86	–	–
87	MMCA0CLK	P24_4	88	MMCA0CMD	P24_5
89	MMCA0DAT0	P24_6	90	MMCA0DAT1	P24_7
91	MMCA0DAT2	P24_8	92	MMCA0DAT3	P24_9
93	MMCA0DAT4	P24_10	94	MMCA0DAT5	P24_11
95	MMCA0DAT6	P24_12	96	MMCA0DAT7	P24_13
97	–	–	98	–	–

Table 7.2 Main board connector CN2 (cont'd)

Pin	Function	Device port	Pin	Function	Device port
99	ETH1MDIO	–	100	ETH1MDC	–
101	ETH1RXD0	–	102	ETH1TXD0	–
103	ETH1RXD1	–	104	ETH1TXD1	–
105	ETH1RXD2	–	106	ETH1TXD2	–
107	ETH1RXD3	–	108	ETH1TXD3	–
109	ETH1RXCLK	–	110	ETH1TXCLK	–
111	ETH1RXER	–	112	ETH1TXER	–
113	ETH1CRSDV	–	114	ETH1TXEN	–
115	ETH1RXDV	–	116	ETH1COL	–
117	ETH1RESET	–	118	ETH1LINK	–
119	–	–	120	–	–

7.1.3   Main Board Connector CN3

Table 7.3 Main board connector CN3

Pin	Function	Device port	Pin	Function	Device port
1	CSI0CS0	P21_7	2	CSI0CLK	P22_4
3	CSI0CS1	P21_6	4	CSI0SI	P22_1
5	CSI0CS2	P21_5	6	CSI0SO	P22_0
7	CSI0CS3	P21_4	8	–	–
9	–	–	10	CSI1CS1	P24_8
11	–	–	12	–	–
13	PSI5SRX1	P6_13	14	PSI5RX1	P5_2
15	PSI5STX1	P6_14	16	PSI5TX1	P5_3
17	PSI5SCLK1	P6_15	18	–	–
19	–	–	20	–	–
21	CSI1CS2	P24_9	22	CSI1CS3	P4_8

Table 7.3 Main board connector CN3 (cont'd)

Pin	Function	Device port	Pin	Function	Device port
23	–	–	24	CSI1CS0	P24_7
25	–	–	26	DIGIO_24	P17_6
27	–	–	28	CSI1SO	P24_6
29	CSI1SCLK	P24_4	30	CSI1SI	P24_5
31	–	–	32	–	–
33	–	–	34	–	–
35	–	–	36	–	–
37	–	–	38	–	–
39	–	–	40	–	–
41	–	–	42	–	–
43	–	–	44	–	–
45	–	–	46	–	–
47	–	–	48	–	–
49	–	–	50	–	–
51	–	–	52	–	–
53	–	–	54	–	–
55	AD1_0	AP2_0	56	AD1_1	AP2_1
57	AD1_2	AP2_2	58	AD1_3	AP2_3
59	AD1_4	AP2_4	60	AD1_5	AP2_5
61	AD1_6	AP2_6	62	AD1_7	AP2_7
63	PWM0	P24_4	64	PWM1	P24_5
65	PWM2	P24_6	66	PWM3	P24_7
67	PWM4	P24_8	68	PWM5	P24_9
69	PWM6	P24_10	70	PWM7	P24_11
71	DIGIO16	AP0_0	72	DIGIO17	AP0_1

Table 7.3 Main board connector CN3 (cont'd)

Pin	Function	Device port	Pin	Function	Device port
73	DIGIO18	AP0_2	74	DIGIO19	AP0_3
75	DIGIO20	AP0_4	76	DIGIO21	AP0_5
77	DIGIO22	AP0_6	78	DIGIO23	AP0_7
79	ENC0	P10_8	80	ENC1	P10_9
81	–	–	82	–	–
83	–	–	84	–	–
85	–	–	86	–	–
87	–	–	88	–	–
89	–	–	90	–	–
91	–	–	92	–	–
93	–	–	94	–	–
95	–	–	96	–	–
97	–	–	98	–	–
99	–	–	100	–	–
101	–	–	102	–	–
103	–	–	104	–	–
105	–	–	106	–	–
107	–	–	108	–	–
109	–	–	110	–	–
111	–	–	112	–	–
113	–	–	114	–	–
115	–	–	116	–	–
117	–	–	118	–	–
119	–	–	120	–	–

7.2 Debug Connector CN4

Table 7.4 On-chip debug connector CN4

Pin	Function	Device port	Pin	Function	Device port
1	TDCK / LPDCLK / FPCK	JP0_2	2	GND	
3	TRSTZ		4	FLMD0	
5	TDO / LPDO / FPDT	JP0_1	6	–	
7	TDI / LPDIO / FPDR	JP0_0	8	E0VCC	
9	TMS	JP0_3	10	–	
11	RDY / LPDCLKOUT	JP0_5	12	GND	
13	RESETZ		14	GND	

7.3 RHSIF/MSIP Connector CN5

Table 7.5 RHSIF/MISP connector CN5

Pin	JP1[2-1]		JP1[2-3]	
	Device port	Function	Device port	Function
1	P2_13	HSIF0_TXDP / MSPI0_SOP	P2_11	HSIF0_RXDP / MSPI0_SIP
2	P2_15	MSPI0_SCKP	P2_15	MSPI0_SCKP
3	P2_12	HSIF0_TXDN / MSPI0_SON	P2_10	HSIF0_RXDN / MSPI0_SIN
4	P2_14	MSPI0_SCKN	P2_14	MSPI0_SCKN
5	–	GND	–	GND
6	P2_9	HSIF0_REFCLK / MSPI0CSS4	P2_9	HSIF0_REFCLK / MSPI0CSS4
7	P2_11	HSIF0_RXDP / MSPI0_SIP	P2_13	HSIF0_TXDP / MSPI0_SOP
8	–	GND	–	GND
9	P2_10	HSIF0_RXDN / MSPI0_SIN	P2_12	HSIF0_TXDN / MSPI0_SON
10	–	GND	–	GND
11	–	GND	–	GND
12	–	GND	–	GND

Note

In order to minimize signal interference no signals from CN5 are connected to CN16. If required they can be connected via 0 Ω resistors R15 to R18 and R21 to R23.

7.4   Device Ports Connectors CN13 to CN16

The device port connectors enable easy connection to almost all ports of the device.

CAUTION

The pin headers are directly connected to the pins, therefore special care must be taken to avoid any electrostatic or other damage to the device.

7.4.1   Device Ports Connector CN13

Pin	Device port	Pin	Device port
1	AP0_4	2	AP0_0
3	AP0_6	4	AP0_2
5	AP0_8	6	AP1_3
7	AP0_1	8	AP1_2
9	AP0_3	10	AP1_1
11	AP0_5	12	AP1_0
13	AP0_7	14	AP0_15
15	AP0_13	16	AP0_14
17	AP0_9	18	AP0_12
19	AP0_11	20	AP0_10
21	P3_3	22	P3_2
23	P24_5	24	P24_4
25	P24_6	26	P24_7
27	P24_8	28	P24_9
29	P24_10	30	P24_11
31	P24_13	32	P24_12
33	P4_1	34	P4_0
35	P4_5	36	P4_4
37	P4_7	38	P4_6
39	P4_9	40	P4_8
41	P4_11	42	P4_10
43	P4_13	44	P4_12

7.4.2 Device Ports Connector CN14

Table 7.6 Device ports connector CN14

Pin	Device port	Pin	Device port
1	P10_0	2	P10_1
3	P10_2	4	P10_3
5	P10_4	6	P10_5
7	P10_6	8	P10_7
9	P10_8	10	P10_9
11	P10_10	12	P10_11
13	P10_12	14	P10_13
15	P10_14	16	P21_6
17	P17_0	18	P21_7
19	P17_1	20	P17_2
21	P17_3	22	P17_4
23	P17_5	24	P17_6
25	AP2_10	26	AP2_13
27	AP2_8	28	AP2_14
29	AP2_6	30	AP2_11
31	AP2_4	32	AP2_15
33	AP2_2	34	AP2_7
35	AP2_9	36	AP3_0
37	AP2_5	38	AP3_2
39	AP2_3	40	AP3_3
41	AP2_1	42	AP3_1
43	AP2_0	44	AP2_12

7.4.3   Device Ports Connector CN15

Table 7.7 Device ports connector CN15

Pin	Device port	Pin	Device port
1	AP4_3	2	P4_15
3	AP4_2	4	P4_14
5	AP4_1	6	AP4_4
7	P6_11	8	AP4_0
9	P6_2	10	P6_4
11	P6_3	12	P6_6
13	P6_5	14	P6_8
15	P6_7	16	P6_12
17	P6_9	18	P6_10
19	P6_15	20	P6_14
21	P6_13	22	P6_0
23	P3_4	24	P3_5
25	P3_7	26	P3_6
27	JP0_3	28	P3_8
29	JP0_1	30	JP0_5
31	JP0_0	32	JP0_2
33	TRSTZ	34	GETH0VCL
35	FLMD0	36	RESETZ
37	VMONOUTZ	38	PWRCTL
39	X2_C *	40	X1_C *
41	P5_2	42	P5_3
43	P5_4	44	P5_6

Note   *   By default these signals are not connected to CN15 in order to minimize signal interference. If required they can be connected via 0 Ω resistors R3 and R4.

7.4.4   Device Ports Connector CN16

Table 7.8 Device ports connector CN16

Pin	Device port	Pin	Device port
1	AWOVCL	2	GND
3	P2_1	4	P2_0
5	P2_3	6	P2_2
7	P2_5	8	P2_4
9	P2_7	10	P2_6
11	CN_P2_9 *	12	P2_8
13	CN_P2_11 *	14	CN_P2_10 *
15	CN_P2_13 *	16	CN_P2_12 *
17	CN_P2_15 *	18	CN_P2_14 *
19	P22_4	20	P22_3
21	P22_2	22	P22_1
23	P20_0	24	P22_0
25	P20_2	26	P20_1
27	P20_4	28	P20_3
29	P20_6	30	P20_5
31	P20_8	32	P20_7
33	P20_10	34	P20_9
35	P21_1	36	P21_0
37	P21_3	38	P21_2
39	P21_4	40	P20_13
41	P21_5	42	P20_12
43	ERROROUTZ	44	P20_14

Note   *   By default these signals are not connected to CN16 in order to minimize signal interference. If required they can be connected via 0 Ω resistors R15 to R18 and R21 to R23.

7.5 Pull-Up/Pull-Down Pin Header CN12

Please refer to *6.4 Pull-Up/Pull-Down Pin Header* for details on the function of these pins.

Table 7.9 Ethernet connector CN6

Pin	Function	Pin	Function
1	fixed H level, depends on JP25:	2	fixed L level
3	• JP25[2-1]: 5.0 V	4	
5	• JP25[2-3]: 3.3 V	6	
7		8	
9		10	
11	fixed H level, depends on JP15:	12	
13	• JP15[2-1]: 5.0 V	14	
15	• JP15[2-3]: 3.3 V	16	
17		18	
19		20	

7.6 Ethernet Connectors CN6 and CN17

Please refer to *6.5 Automotive Ethernet Interface* for details on the function of these pins.

Table 7.10 Ethernet connector CN17

Pin	Function
1	MDIN_cn
2	MDIP_cn
3	GND
4	GND
5	GND
6	GND
7	GND

Table 7.11 Ethernet connector CN6

Pin	Function
1	MDIN_cn
2	MDIP_cn

7.7   GPIO/LED Connector CN20

Please refer to the data sheet of "Marvell 88Q2112 Automotive 100/1000BASE-T1 Transceiver" for details on the function of these pins.

Table 7.12 GPIO/LED connector CN20

Pin	JP1[2-1]	
	Device port	Function
1	GPIO, pin 42	GPIO output of Marvell PHY
2	NC	Not connected
3	LED, pin 41	LED output of Marvell PHY

8. Jumper Configuration Examples

Several functions of the board can be configured via jumpers.
The board is shipped without any jumpers set.

For a complete list of jumpers refer to *2.1 Jumper Overview*.

For jumper settings related to the device operation mode, refer to *6.1 Operation Mode Selection*.

The following sections show some jumper settings, that allow to operate the piggyback board in different power supply configurations.

8.1   Stand-Alone Operation with Power Supply by Debugger

Basically the piggyback board can solely be powered by a connected debugger. Please make sure the debug tool is able to provide sufficient current on the power supply rails in order to operate the board in a useful manner.

Due to the limited current capability of Renesas' E2 Emulator, powering the board only via this debugger is not feasible.

In case of using another debug tool check its specification whether powering the piggyback board with the tool is possible.

8.2   Configuration Examples

8.2.1   General Settings
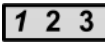
All of the following board configurations are based on these conditions:

- Normal device operation mode (JP41[OPEN]: FLMD0 = L).
    - When using Serial Programming Mode by a debugger or programming tool, that is connected to the board, make sure to open jumper JP39 (JP39[OPEN]: FLMD1 = GND).

- All voltages for all functions are activated.

- Current measurements are not carries out, hence JP4, JP5, JP30 and JP31 are set.

- Clock supply: assuming one of the resonators, coming with the board, are plugged into X1 socket.

- For connection to external power supplies the 'banana-type' connectors CN8 to CN11 must be assembled on the board.

8.2.2   Jumper Indicators

- The green jumper JP41 for FLMDO0 must always be open for a 'normal' (user mode and debug) operation of the device.

- The red jumpers are related to the power supply configuration.

Following jumper symbols are used:

- [ ] : open jumper
- [1 2] : jumper must be set in the indicated position
- [1 2 3] : jumper must be set, *italic* position indicator is optional, see description above the figure

Note

The pin 1 of a jumper can be identified by a

- small circle near the jumper

- square soldering pad.

8.2.3 Stand-Alone Operation with Single External Power Supply: Minimum Configuration

This example enables to operate the board with only the 3.3 V external power supply. Since no 5 V voltage is available, all I/O ports can only use 3.3 V.

- CN8: GND connection

- CN9: not connected, no 5.0 V
    - jumpers JP2, JP3, JP6 to JP14, JP22 and JP32 to JP37 are set to 3.3 V position [2-3]

- CN10: 3.3 V

- CN11: not connected, no IN_1v12
    - JP16[2-1]: use reg_vcc_VDD from on-board voltage regulator for supply of VDD voltage
    - VDD from reg_vcc_VDD (JP23[2-1]) or from SVR_OUTPUT (JP23[2-3]) from on-chip Switching Voltage Regulator

    Refer to *3.3 Device Core Voltage (VDD) Selection* for further details about VDD voltage.
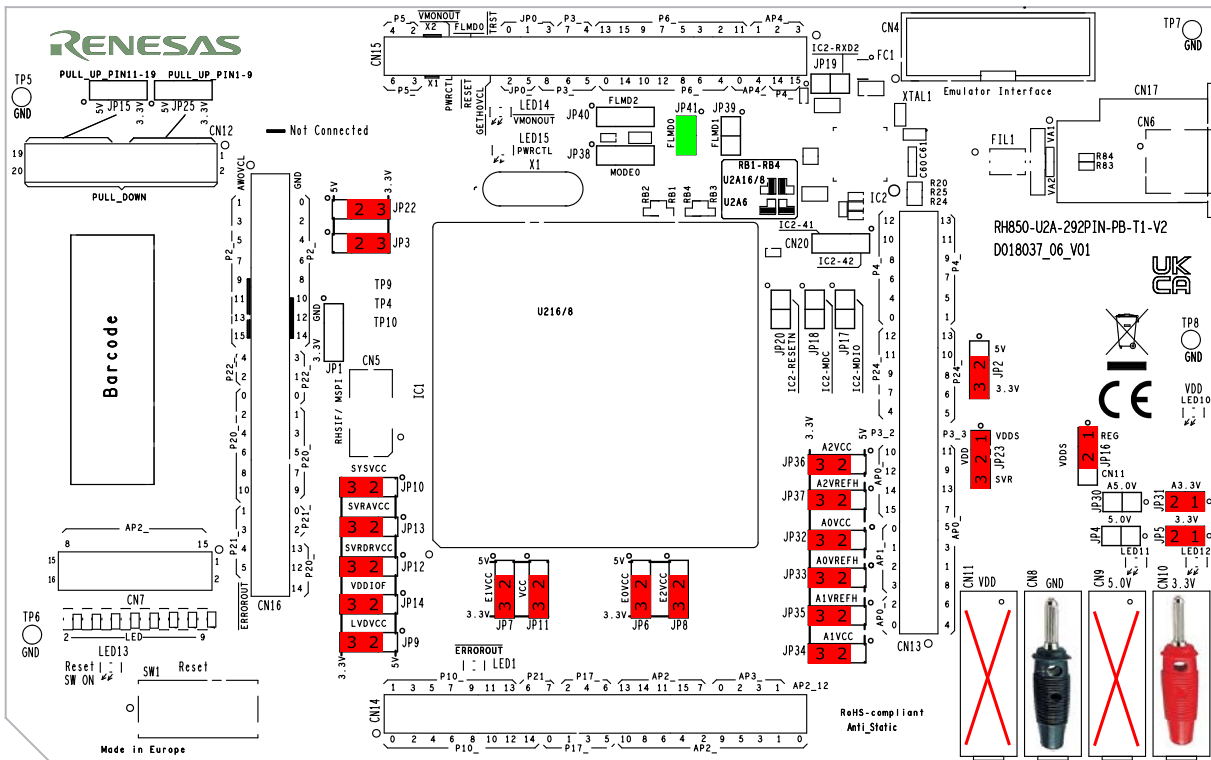
Figure 8.1 Stand-alone operation with minimum external power supply

8.2.4   Stand-Alone Operation with All External Power Supplies: Maximum Configuration

This example assumes all external power supplies are connected and used.

- CN8: GND connection

- CN9: 5 V
    - select desired 3.3 V/5.0 V via jumpers JP2, JP3, JP6 to JP14, JP22 and JP32 to JP3

    Refer to *3.2Voltage Distribution* for further details about VDD voltage and possible settings of jumpers JP2, JP3 and JP22.

- CN10: 3.3 V

- CN11: 1.12 V (IN_1v12)
    - JP16[2-3], JP23[2-1]: use IN_1v12 for VDD voltage

    Refer to *3.3 Device Core Voltage (VDD) Selection* for further details about VDD voltage.
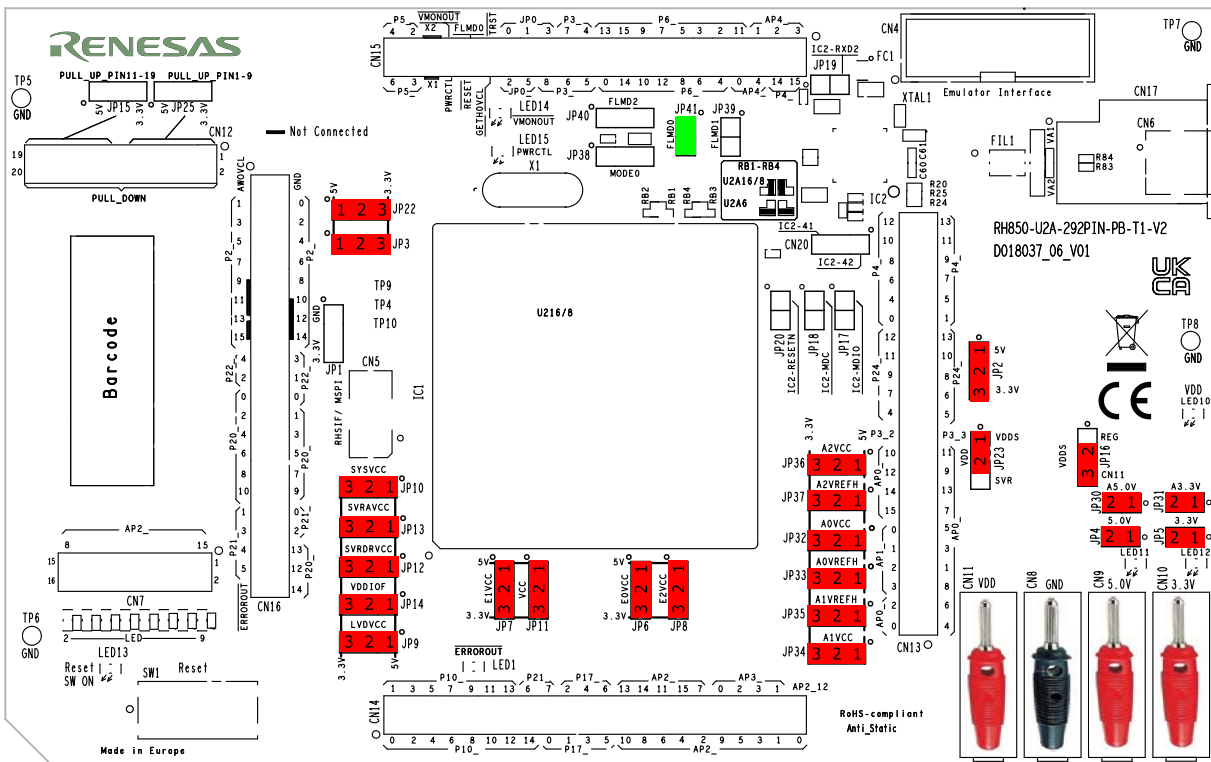
Figure 8.2 Stand-alone operation with maximum external power supply

8.2.5   Operation on the Main Board: No External Supply

This example assumes the piggyback board is plugged onto a Main Board, which provides 3.3 V and 5.0 V.

Do not supply the 5V (CN9) and 3.3V (CN10) voltage directly to the piggyback board

- CN8 to CN11: not connected, no external 5.0 V, 3.3 V, 1.12 V

- select desired 3.3 V/5.0 V via jumpers JP2, JP3, JP6 to JP14, JP22 and JP32 to JP3
  Refer to *3.2Voltage Distribution* for further details about VDD voltage and possible settings of jumpers JP2, JP3 and JP22.

- VDD supply:
  - JP16[2-1]: use reg_vcc_VDD from on-board voltage regulator for supply of VDD voltage
  - VDD from reg_vcc_VDD (JP23[2-1]) or SVR_OUTPUT (JP23[2-3]) from on-chip Switching Voltage Regulator
  Refer to *3.3 Device Core Voltage (VDD) Selection* for further details about VDD voltage.

Note

This configuration still allows to utilize an external IN_1v12 voltage (connected to CN8, CN11) as the source for VDD voltage. In this case set JP16[2-3] and JP23[2-1].

CAUTION

Do not supply 5V (CN9) and 3.3V (CN10) directly to the piggyback board if these voltages are already supplied by the main board.
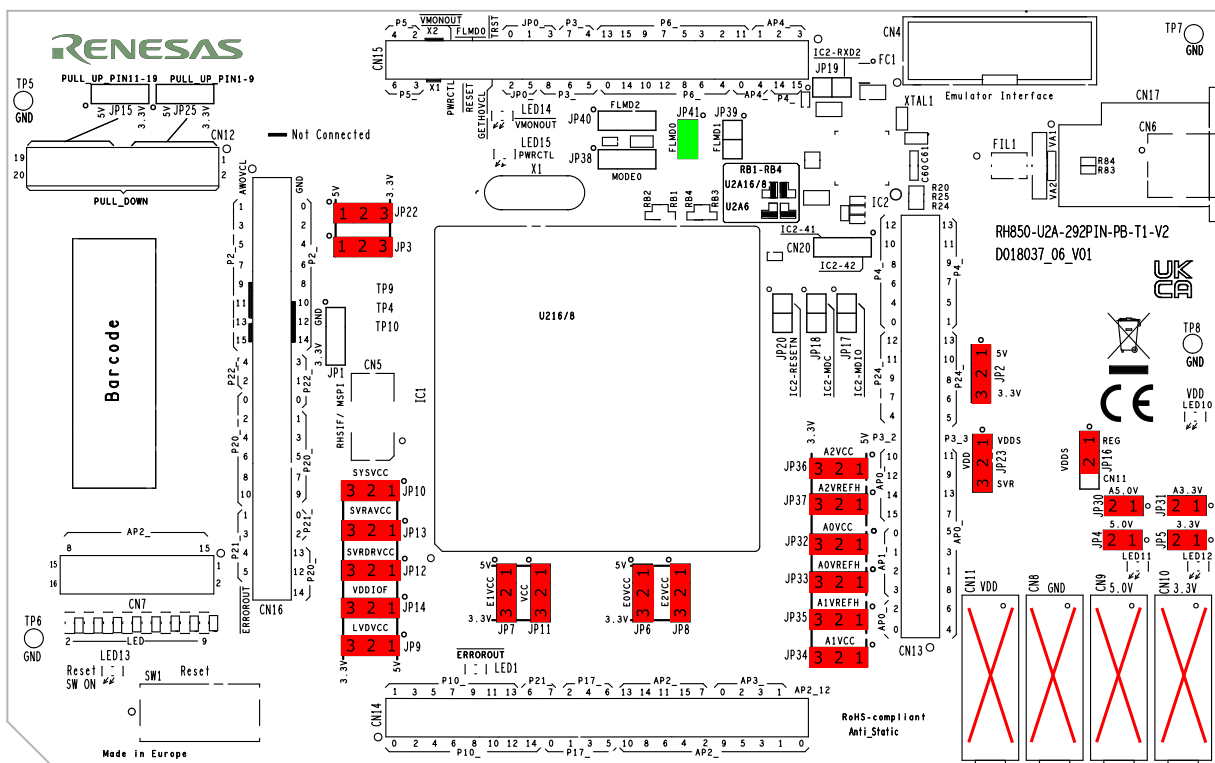
Figure 8.3 Main board operation without external power supply

9.   Precautions

9.1   Power-Off Sequence

A dedicated sequence needs to be applied, when the power supply to the board is turned off.

Please follow the below sequence:

1. At first turn the RESET switch SW1 into '2-3 ON' position, so that RESET is permanently asserted. Alternatively keep SW1 manually in' 2-1 (ON)' position.

1. Turn off the board power supply.

2. After the power supply has shut down, release RESET by returning SW1 into the 'OFF' position.
For details how to apply a RESET, please refer to section *6.2 RESET Switch*.

9.2   CAN0RX is Shared with FLASH Programmer Signal FLMD1

When using this product plugged into a motherboard where CAN0 is connected to the CAN-transceiver the FLASH programmer will not work.

This is because the CAN0RX function is shared with the FLMD1 function on the same device PIN.

Most CAN-transceiver are driving the RX line actively and the FLASH programmer then is not able to change signal level as required for flashing.

9.3   DeepSTOP Mode when using SVR

It is not possible to use the SVR function (JP23[2-3]: VDD = 1.09 V (SVR_OUTPUT)) together with DeepSTOP mode operation.

If DeepSTOP mode operation is needed, please use JP23[1-2]: VDD = 1.12 V (VDDs) for core voltage.

Please refer to *3.3 Device Core Voltage (VDD) Selection* for further details about VDD voltage setting.

9.4 Assembly of Oscillator X3

On boards up to serial number 15005 the oscillator X3 (located at the bottom side of the pcb, see figure 9.1) is wrongly populated with a 16MHz ceramic resonator.

This resonator works in parallel to the 40MHz ceramic resonator mounted in socket X1 on the upper side of the pcb.

The intended oscillator source for RH850/U2A is the 40MHz ceramic resonator mounted in socket X1. Experience shows that the 16MHz resonator on the bottom side of the pcb does not disturb the clock signal of the resonator on the upper side of the pcb.
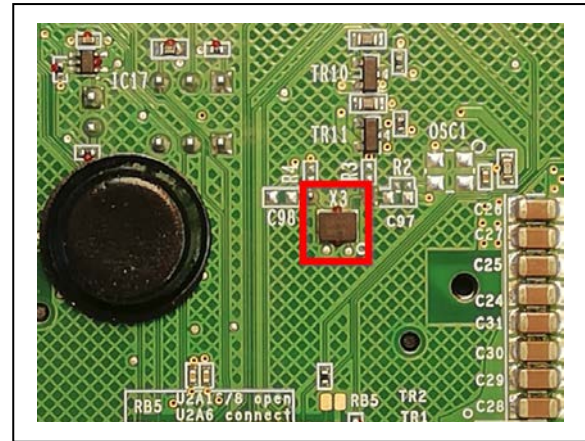
Figure 9.1 Ceramic resonator mounted for oscillator X3

If you experience problems with the oscillator (e.g. processor running at the wrong operating frequency or problems with the oscillation build-up at power on) the ceramic resonator on X3 should be desoldered.

9.5 Oscillator X1 Works at Wrong Frequency

This applies to boards with serial numbers 14936 – 15005.

The piggyback board Y-RH850-U2A-292PIN-PB-T1-V2 is delivered with a 40MHz crystal resonator assembled as oscillator X1.
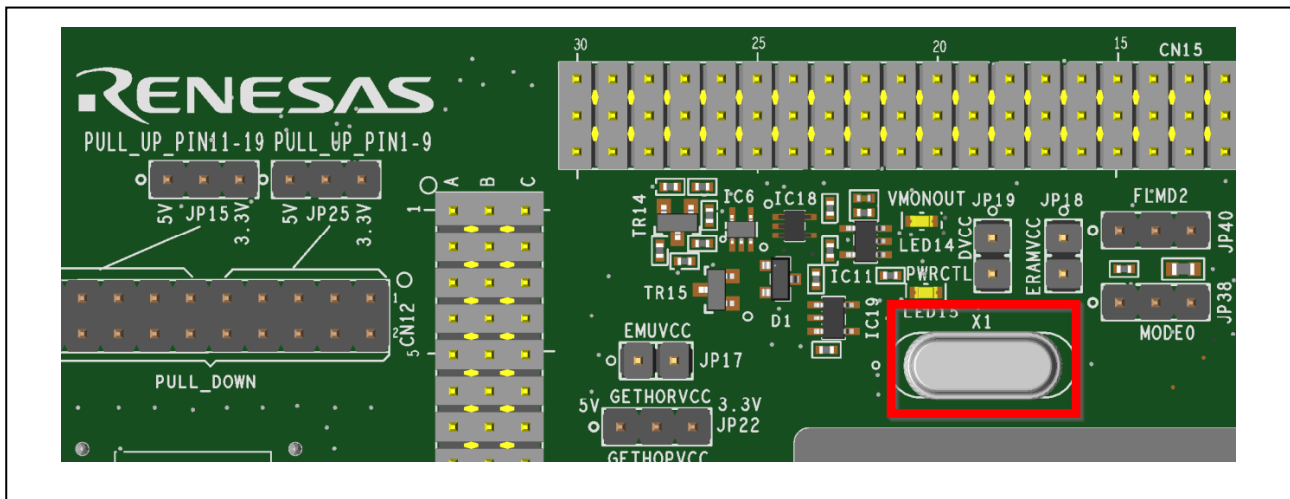
Figure 9.2: Oscillator socket X1

We have three manufacturers for the crystal resonators that are used in our RH850 boards (please see *Table 9.1 Crystal resonator manufacturer overview*).

We found that the crystal resonators from TXC and ABRACON work properly on the piggyback board Y-RH850-U2A-292PIN-PB-T1-V2 at 40MHz.

The crystal resonator from ECS does not work at 40MHz. It oscillates only at 13.3MHz, which is the fundamental frequency of the crystal. The ECS oscillator is an oscillator, where the operating frequency is the 3rd harmonic of the fundamental frequency. For some reason this

does not work on this piggyback board. However, crystal resonators from ECS work fine at frequencies up to 25MHz.

Thus the board was not planned to be equipped with the 40MHz crystal resonator from ECS.

The boards with serial numbers 14936 – 15005 are wrongly equipped with the ECS oscillator. Please replace this with the oscillator from TXC or ABRACON.

Table 9.1 Crystal resonator manufacturer overview

Manufacturer	Device Name	Usability on this piggyback board	Oscillator Picture
TXC	9B-40.000MAAJ-B	GOOD	
ABRACON	ABL-40.000MHZ-B2F	GOOD	
ECS	ECS-400-18-4XEN	NOT GOOD	

9.6   Assembly of Power Supply Sockets

In the first production lots the power supply sockets (CN8, CN9, CN10, CN11) were not assembled in production. All sockets were included in the accessory bag. Table 9.2 lists all serial numbers of boards where the power supply sockets were not assembled.

Table 9.2 Board serial numbers

FROM serial number	TO serial number	Quantity	Power supply sockets assembled
13759	13803	45	No
14309	14348	40	No
14524	14563	40	No
14614	14633	20	No
14634	14653	20	No
14936	15005	70	No

From board serial number 15404 onwards the sockets for CN8 (GND), CN9 (5.0V) and CN10 (3.3V) are assembled in production, and only one red socket is included in the box for connector CN11 (1.12V).

9.7   Power On Piggyback Board Without RH850 Microcontroller installed

The piggyback board Y-RH850-U2A-292PIN-PB-T1-V2 is not designed to be powered on when the RH850 microcontroller is not installed in socket IC1.

If the microcontroller is not installed the SVR power supply circuit does not have the control signals SVRNGATE and SVRPGATE and may be damaged.

If for some reason the board has to be powered on without a microcontroller mounted in socket IC1 please make sure the jumper JP12[1-2-3] (SVRDRVCC) is open. In this case no power is supplied to the SVR control circuit, and it will not be damaged.

10. Mechanical Dimensions
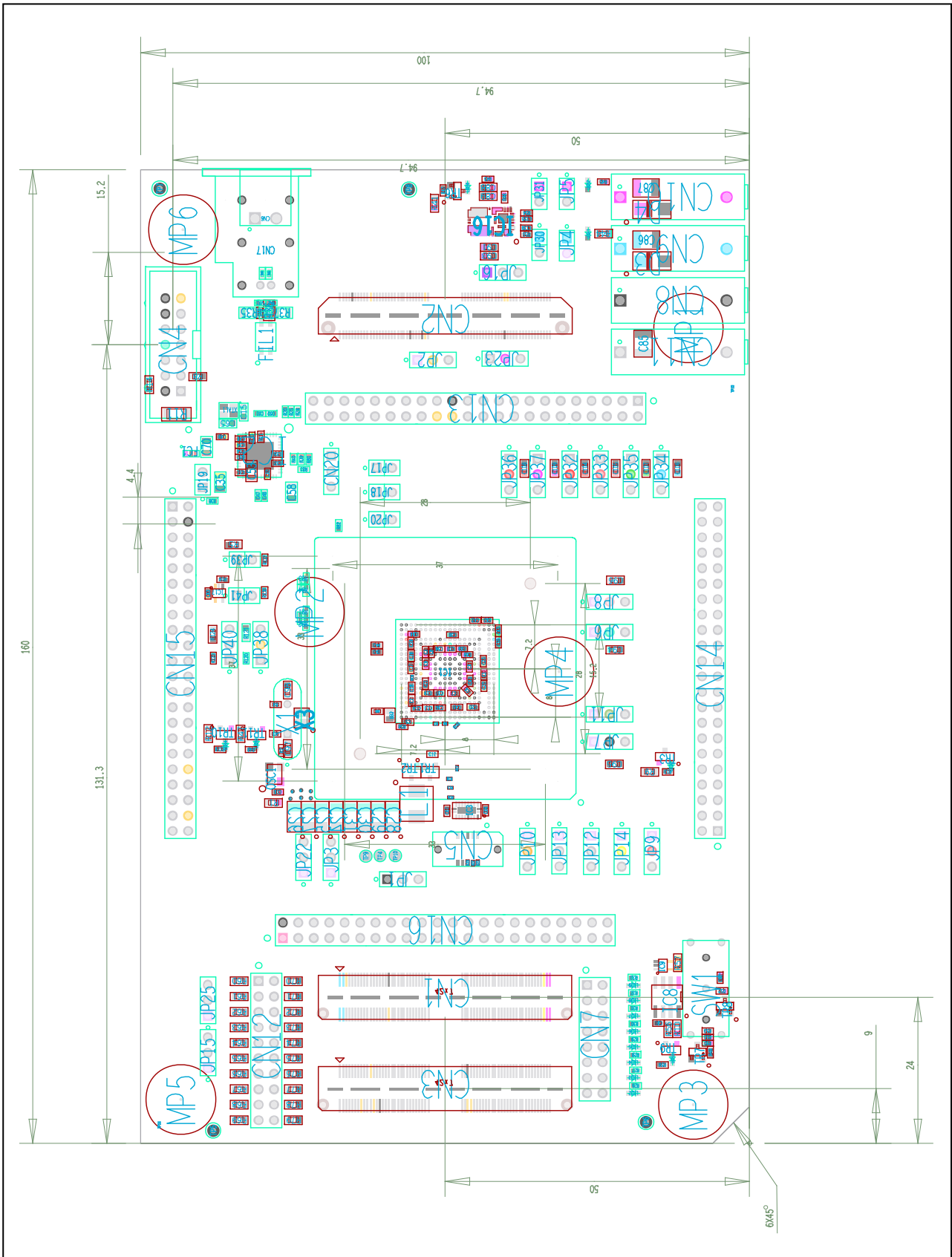
Figure 9.1 Mechanical dimensions

11. Schematics

CAUTION

The schematics shown in this document are not intended to be used as a reference for mass production. Any usage in an application design is in sole responsibility of the customer.

Not all components shown in the schematic are populated in production.

Components, which are not populated, are crossed out in the schematic like this:

The following components, which are described in the schematics, are provided with the board but not mounted on the board upon delivery. These components have no special marking in the schematics other than that they are crossed out as not assembled components.

- One Hirschmann 4 mm power lab socket, red, for CN11

- For boards with serial numbers earlier than 15404 only:

    o   Two Hirschmann 4 mm power lab socket, red, for CN9 and CN10

    o   One Hirschmann 4 mm power lab socket, black, for CN8

- One TE MATEnet 1000BASE-T1 Ethernet Port connector

- One Würth PCB Terminal Block connector

- Three resonators HC49 (16/20/24 MHz)

- 44 jumpers, 2.54 mm, black

Note

On boards up to serial number 15005 no power supply socket (CN8, CN9, CN10, CN11) is assembled in production. Thus the box includes 3 red Hirschmann sockets for CN9, CN10 and CN11, and one black Hirschmann socket for CN8.

From board serial number 15404 onwards the sockets for CN8 (GND), CN9 (5.0V) and CN10 (3.3V) are assembled in production, and only one red socket is included in the box for CN11.
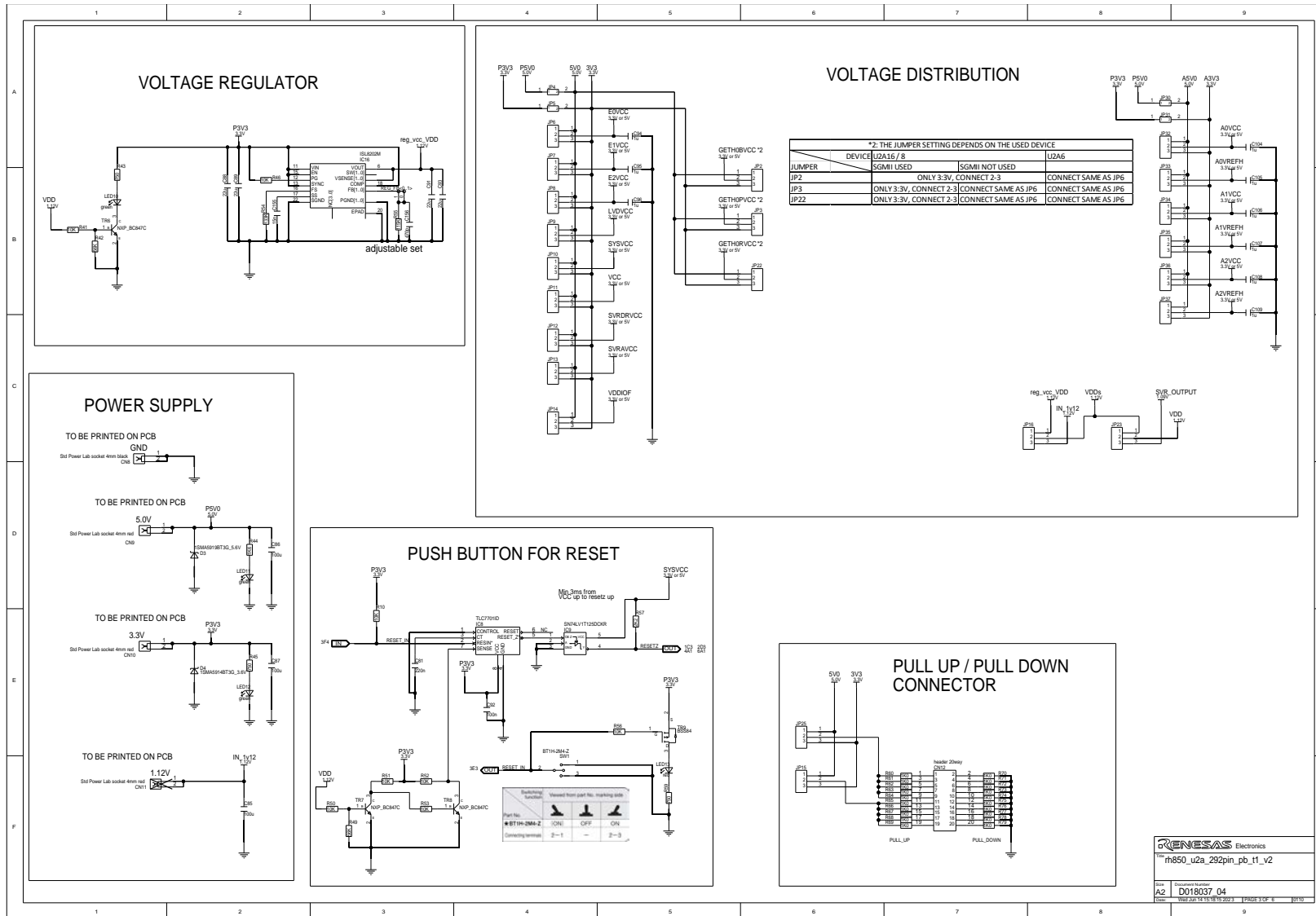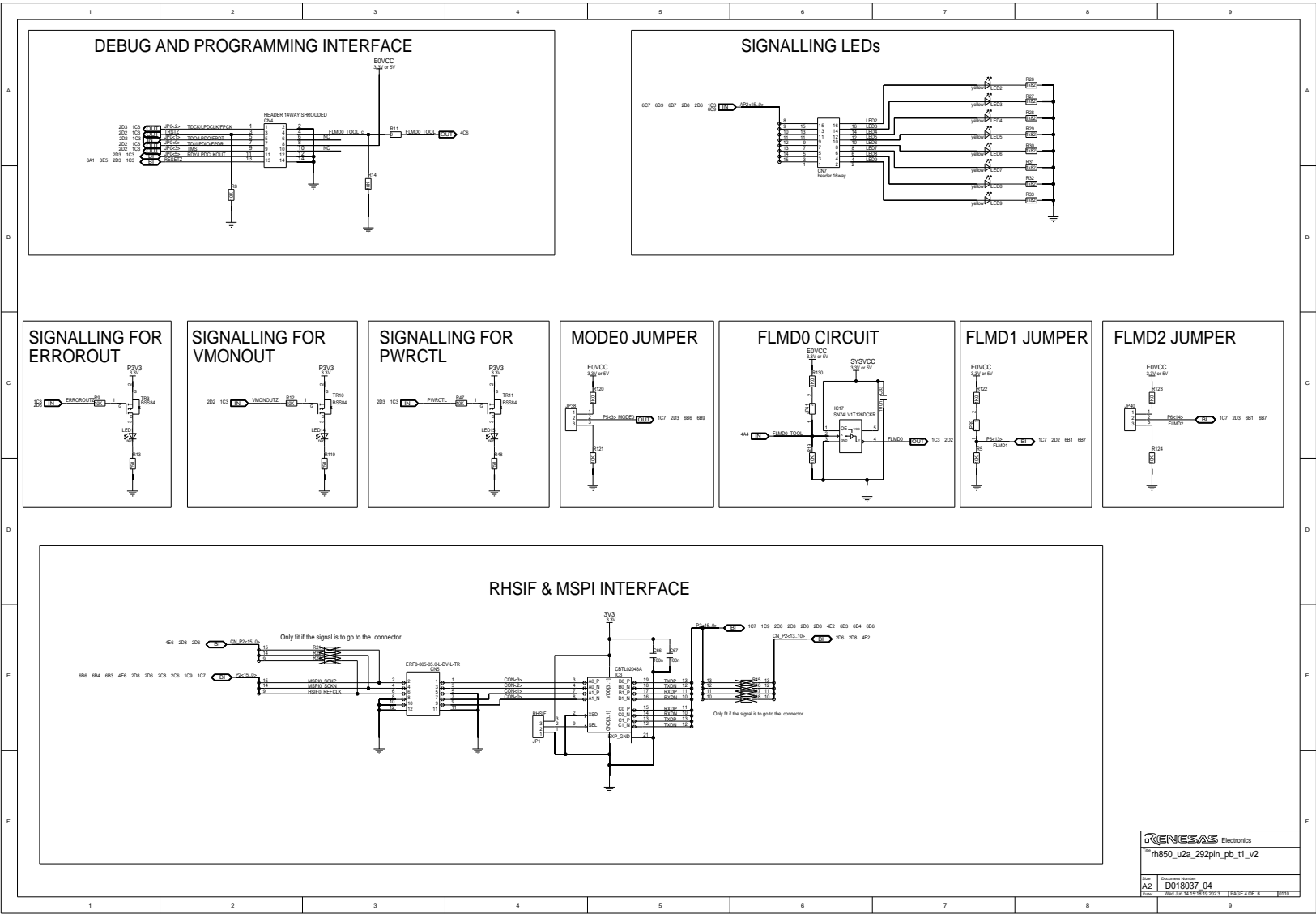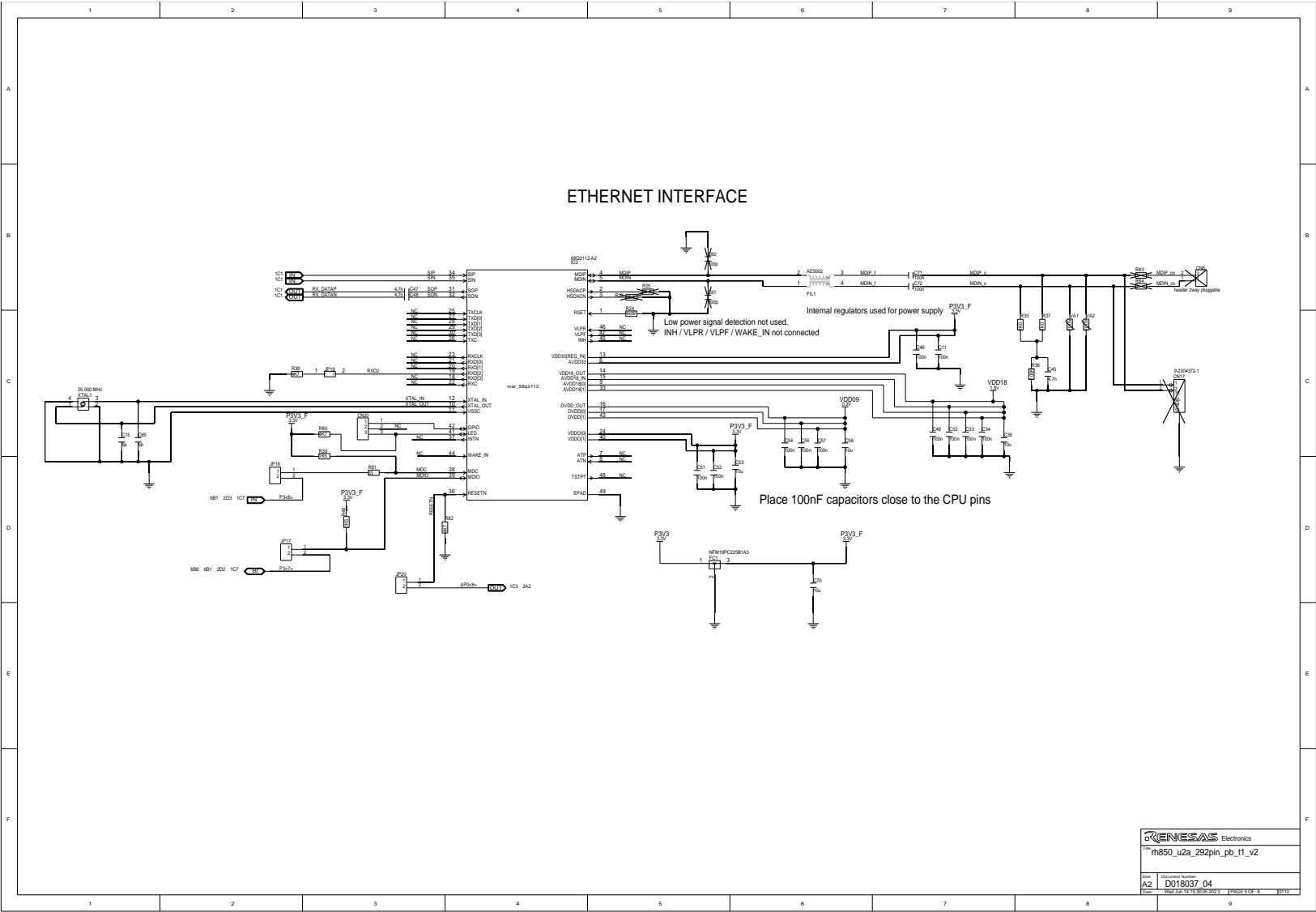
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()*1 NAME IN PARENTHESIS DESCRIBES THE FUNKTION VALID FOR U2A6

DEVICE BALL	U2A16/8	U2A6
J17	RX_DATA_P	VSS
K17	RX_DATA_N	VSS
H16	TX_DATA_P	E0VCC
J16	TX_DATA_N	E0VCC
K16	GETH0BVCC	E0VCC
G17	GETH0PVCC	E0VCC
H17	GETH0RVCC	E0VCC
E17	GETH0VCL	VSS

REV	COMMENT	DATE	DRAWN BY
1.0	Initial Release	01.02.2023	WR
1.10	Changed X3 to DNF, changed CN8, CN9, CN10 from DNF to assembled.	14.06.2023	WR

U2A16/8: set RB1-4 to PIN 2 and PIN 3
U2A6: set RB1-4 to PIN 1 and PIN 2

CAUTION!
Don't use resonator and oscillator IC at the same time

Leave E2 open for U2A16/8
Connect E2 with solder for U2A6

16 MHz provided additional
20 MHz provided additional
24 MHz provided additional

resistors close to MCU pin

ESR<10mOhm @ 0.5&1MHZ

Each capacitor ESR
5mOhm @ 500kHz
9mOhm @ 1Hz

Connect VSS per via to SVRDRVSS

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11.3　Page 3

VOLTAGE REGULATOR

VOLTAGE DISTRIBUTION

*2: THE JUMPER SETTING DEPENDS ON THE USED DEVICE			
DEVICE	U2A16 / 8		U2A6
JUMPER	SGMII USED	SGMII NOT USED	
JP2	ONLY 3:3V, CONNECT 2-3		CONNECT SAME AS JP6
JP3	ONLY 3:3V, CONNECT 2-3	CONNECT SAME AS JP6	CONNECT SAME AS JP6
JP22	ONLY 3:3V, CONNECT 2-3	CONNECT SAME AS JP6	CONNECT SAME AS JP6

POWER SUPPLY

PUSH BUTTON FOR RESET

PULL UP / PULL DOWN CONNECTOR

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11.4　Page 4

DEBUG AND PROGRAMMING INTERFACE

SIGNALLING LEDs

SIGNALLING FOR ERROROUT

SIGNALLING FOR VMONOUT

SIGNALLING FOR PWRCTL

MODE0 JUMPER

FLMD0 CIRCUIT

FLMD1 JUMPER

FLMD2 JUMPER

RHSIF & MSPI INTERFACE

11.5 Page 5

ETHERNET INTERFACE

Internal regulators used for power supply

Low power signal detection not used.
INH / VLPR / VLPF / WAKE_IN not connected

Place 100nF capacitors close to the CPU pins

11.6 Page 6

Revision History

| Rev. | Date | Description | |
		Page	Summary
V1.06	2024-06-07	10	Updated information about devices that can be used with the piggyback board in *1.5 Mounting of the Device.*
V1.05	2024-05-02	26, 50	Added explanation for FLMD1 setting in Serial Programming Mode.
V1.04	2023-10-26	56	Added more details to the description of power supply socket assembly.in *9.6 Assembly of Power Supply Sockets.*
		19, 57	Added precaution about power on of piggyback board without a microcontroller mounted. Added a caution in *3.1 Board Power Connection* and added *9.7 Power On Piggyback Board Without RH850 Microcontroller installed.*
V1.03	2023-06-15	19	The part assembly for power supply connectors changed. This is described in *3.1 Board Power Connection.*
		59	The schematics in *11 Schematics* have been updated reflecting the change in the assembled parts.
V1.02	2023-06-07	55	Added precaution about wrongly assembled ceramic resonator X3 in *9.4 Assembly of Oscillator X3.*
			Added precaution about wrongly assembled crystal resonator X1 in *9.5 Oscillator X1 Works at Wrong Frequency.*
V1.01	2022-07-08	51 - 53	Corrected jumper JP41 setting in *Figure 8.1 Stand-alone operation with minimum external power supply*, *Figure 8.2 Stand-alone operation with maximum external power supply* and *Figure 8.3 Main board operation without external power supply.*
V1.00	2021-05-21	–	Initial release

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RH850/U2A 292pin

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