RENESAS

2.5V SEQUENTIAL FLOW-CONTROL DEVICE

36 BIT WIDE CONFIGURATION

For use with 128Mb to 256Mb DDR SDRAM

IDT72T6360 **OBSOLETE PART**

FEATURES

- **• Product to be used with single or multiple external DDR SDRAM to provide significant storage capability of up to 1Gb density**
- **• 166MHz operation (6ns read/write cycle time)**
- **• User selectable input and output port bus-sizing**
	- *x36in to x36out*
	- *x36in to x18out*
	- *x36in to x9out*
	- *x18in to x36out*
	- *x18in to x18out*
	- *x18in to x9out*
	- *x9in to x36out*
	- *x9in to x18out*
	- *x9in to x9out*
- **• For other bus configurations see IDT72T6480 (x12, x24, or x48)**
- **• 2.5V-LVTTL or 3.3V-LVTTL configured ports**
- **• Independent and simultaneous read and write access**
- User selectable synchronous/asynchronous readeral w **port timing**
- **• IDT Standard mode or FWFT mode of operation**
- **• Empty and full flags for monitoring memory status**
- **• Programmable Almost-Empty and Almost-Full flags, each flag can default to one of four preselected offsets or serially programmed to a specific value**
- **• Selectable synchronous/asynchronous timing modes for Almost-Empty and Almost-Full flags**
- **• Master Reset clears all data and settings**
- **Partial Reset clears data, but retains programmable settings**
- **Depth expandable with multiple devices for densities greater than 1Gb**
- Width expandable with multiple devices for bus widths greater **than 36 bits**
	- **JTAG functionality (Boundary Scan)**
- **Available in a 324-pin PBGA, 1mm pitch, 19mm x 19mm**
- **HIGH performance 0.18μ***m* **CMOS technology**
- **Industrial temperature range (-40**°**C to +85**°**C) is available**
- Supports inductry standard DDR specifications, including **Samsung, Micron, and Infine and memories**

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DESCRIPTION

The IDT72T6360 sequential flow-control device is a device incorporating a seamless connection to external DDR SDRAM for significant storage capacity supporting high-speed applications. Both read and write ports of the sequential flow-control can operate independently at up to 166MHz. There is a user selectable correction feature that will correct any erroneous single data bit when reading from the SDRAM.

The independent read and write ports each has associated read and write clocks, enables, and chip selects. Both ports can operate either synchronously or asynchronously. Other features include bus-matching, programmable status flags with selectable synchronous/asynchronous timing modes, IDT Standard or FWFT mode timing, and JTAG boundary scan functionality.

The bus-matching feature will allow the inputs and outputs to be configured to x36, x18, or x9 bus width. There are four default offset values available for the programmable flags (PAE/PAF), as well as the option of serially programming the offsets to a specific value.

The device package is 19mm x 19mm 324-pin PBGA. It operates at a 2.5V core voltage with selectable 2.5V or 3.3V I/Os. The I/O interface to the SDRAM will be 2.5V SSTL_2 only and not 3.3V tolerant. Both industrial and commercial temperature ranges will be offered.

The sequential flow-control device controls individual DDR SDRAM of either 128Mb or 256Mb. The device will support industry standard DDR specification memories (note DDR II is not supported), which include vendors such as Samsung, Micron, and Infineon. The data bus connected to the DDR SDRAM can be 16-bit, 32-bit, or 64-bits wide. The sequential flow-control device can independently control up to four separate external memories for a maximum of density of 1Gb (128MB). Depth expansion mode is available for applications that require more than 1Gb of storage memory.

COMMERCIAL AND INDUSTRIAL TEMPERATURE RANGES

Figure 1. Sequential Flow-Control Device Block Diagram

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PIN CONFIGURATION

 \blacktriangleright

A1 BALL PAD CORNER

NOTE:

1. DNC = Do Not Connect.

PBGA (BB324-1, order code: BB) TOP VIEW

COMMERCIAL AND INDUSTRIAL TEMPERATURE RANGES

PIN DESCRIPTIONS (Continued)

PIN DESCRIPTIONS (Continued)

NOTE: 1. These pins should not change after master reset.

Please see next page for Power & Ground pins and Pin Number Location Table.

PIN DESCRIPTIONS (Continued)

PIN NUMBER LOCATION TABLE

DETAILED DESCRIPTIONS

SEQUENTIAL FLOW-CONTROL STRUCTURE

The IDT sequential flow-control (SFC) device is comprised of three interfaces: input port, output port, and memory interface. The input and output port can operate independently of each other with selectable bus widths of x9, x18, or x36 bits wide. The third interface, or memory interface, is connected directly to an external memory, which can be used to offload data entering the SFC device.

WRITING AND READING FROM THE SEQUENTIAL FLOW-CONTROL DEVICE

Writing into the SFC device is accomplished by setting the write enable signal $(\overline{\text{WEN}})$ and write chip select $(\overline{\text{WCS}})$ low with a free running write clock (WCLK). Data will be written on the rising edge of every WCLK into the Quad-Port (QP) cache of the SFC device. The internal state machine of the device will determine whether to send the data to the DDR SDRAM or send it directly through to the output bus, depending on when the data is to be accessed. This provides "data coherency" and minimizes the path that the data has to travel.

Reading from the SFC device is accomplished by setting the read enable signal (REN) and read chip select (RCS) low with a free running read clock (RCLK). Data will be sent to the output bus on the rising edge of every RCLK. This data will be accessed either from the QP cache or the external DDR SDRAM.

EXTERNAL MEMORY SELECTION

The DDR SDRAM interface of the SFC device can support DDR SDRAM with standard DDR I specifications. The SFC device can support any external memory within the following characteristics:

- Bus width: 16-bit or 32-bit wide
- Speed: 133MHz or 166MHz
- Density: 128Mb or 256Mb

Table 1 lists the DDR SDRAM minimum specifications that are required to meet the sequential flow-control device requirements. Table 2 lists the memory vendors and associated part numbers of DDR SDRAMs that have been validated by IDT to meet the requirements for the DDR SDRAM interface.

TABLE 1 – DDR SDRAM MINIMUM SPECIFICATIONS

NOTE:

1. These are the minimum specifications that the DDR SDRAM must meet.

TABLE 2 – SUPPORTED MEMORY VENDORS

Density	Bus Width	Vendor	Part#
128Mb	32	Samsung	K4D263238"X"-GC45
256Mb	16	Samsung	K4H561638"X"-TCLB3 K4H561638"X"-GCLB3
256Mb	16	Micron	MT46V16M16TG-6T MT46V16M16TG-75
256Mb	16	Infineon	HYB25D256160BTL-6 HYB25D256160BTL-7
256Mb	32	Samsung	K4D553238"X"-JC50

NOTES:

1. The part numbers listed above include packages that are recommended and validated by IDT. Other packages (such as lead free PCB, FBGA, etc.) may also be used but have not been validated by IDT.

2. The letter "X" for Samsung memory part numbers denotes the latest die revision for that particular device. Check with Samsung for the latest updated part number.

EXTERNAL MEMORY CONFIGURATIONS

The DDR SDRAM interface of the sequential flow-control (SFC) device has a 64-bit output data bus that provides up to four (16-bit SDRAM) external DDR SDRAM connections. For multiple memory connections, they must be of the same density configuration and speed grade. For example, two device connected cannot consist of one 128Mb and one 256Mb memory nor two 128Mb with one at 133MHz and the other at 166MHz. Below is a summary of the possible configurations:

- One 16-bit device connecting a x16 interface to the DDR SDRAM
- One 32-bit device connecting a x32 interface to the DDR SDRAM
- Two 16-bit devices connecting a x32 interface to the DDR SDRAM
- Two 32-bit devices connecting a x36 interface to the DDR SDRAM
- Two 32-bit devices connecting a x64 interface to the DDR SDRAM
- Three 16-bit devices connecting a x36 interface to the DDR SDRAM
- Four 16-bit devices connecting a x64 interface to the DDR SDRAM

These various configurations determine the storage density of the SFC device. The storage density can range from a minimum of 128Mb to a maximum of 1Gb. Table 3 lists the possible ways to connect the DDR SDRAMs and the number of chipset solutions to obtain the various storage densities.

TABLE 3 – TOTAL POSSIBLE EXTERNAL MEMORY CONFIGURATIONS

NOTES:

1. The chip solution number includes the sequential flow-control device and external DDR SDRAM

2. See Figure 2a-2g for the 7 different configurations referenced in the table above.

COMMERCIAL AND INDUSTRIAL TEMPERATURE RANGES

CONNECTING THE DDR SDRAM

Below are the various chipset solution configurations available to the sequential flow-control device (see Figure 2a-2g). The external memory interface is designed to seamlessly connect one or more DDR SDRAMs. The output signal names should be connected directly to its corresponding input signal on the DDR SDRAM. There are three signals on the DDR SDRAM that must be tied to a static state. CKE, $\overline{\text{CS}}$, and DM. Table 4 outlines how to connect the many interface pins to the DDR SDRAM(s). Figure 3 and 4 are some examples of the memory interface connections for various density configurations. For information on DDR SDRAM layout recommendations, please see IDT application note AN-423.

> **DDR SDRAM:** 128Mb [4Mb x 32] or 256Mb [8Mb x 32] **Total Memory Density:** 128Mb or 256Mb **Useable Memory(2):** 108Mb or 252Mb

Figure 2a. Configuration 1 - Two Chip Solution

Figure 2b(1). Configuration 2 - Two Chip Solution

DDR SDRAM: 128Mb [4Mb x 32] or 256Mb [8Mb x 32] **Total Memory Density:** 256Mb or 512Mb **Useable Memory(2):** 216Mb or 504Mb

Figure 2c. Configuration 3 - Three Chip Solution

NOTES:

- 1. 12-bit address bus for 8Mb x16
- 13-bit address bus for 16Mb x16
- 2. Refer to Total Available Memory Usage section for details.

DDR SDRAM: 128Mb [4Mb x 32] or 256Mb [8Mb x 32] **Total Memory Density:** 256Mb or 512Mb **Useable Memory(2):** 108Mb or 252Mb

Figure 2d. Configuration 4 - Three Chip Solution

Figure 2e(1). Configuration 5 - Three Chip Solution

DDR SDRAM: 256Mb [16Mb x 16] **Total Memory Density:** 768Mb **Useable Memory(2):** 567Mb

Figure 2f(1). Configuration 6 - Four Chip Solution

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TABLE 4 – SFC TO DDR SDRAM INTERFACE CONNECTIONS

CONFIGURATION 1

CONFIGURATION 2

CONFIGURATION 3

CONFIGURATION 4

TABLE 4 – SFC TO DDR SDRAM INTERFACE CONNECTIONS(Continued)

CONFIGURATION 5

CONFIGURATION 6

TABLE 4 – SFC TO DDR SDRAM INTERFACE CONNECTIONS(Continued)

CONFIGURATION 7

Figure 3. Memory Interface Connection (Single Chip)

Figure 4. Memory Interface Connection (Two Chip)

COMMERCIAL AND INDUSTRIAL TEMPERATURE RANGES

TOTAL AVAILABLE MEMORY USAGE

 The sequential flow-control (SFC) is designed to efficiently use as much of the DDR SDRAM memory as possible, but due to the discontinuity between the SFC bus width (x36) and the DDR SDRAM interface (x16 or x32), some columns in a row of the SDRAM will not be used. As a result, the total usable memory will be slightly less than the total available memory in the SDRAM. Table 5 outlines the total usable memory for the various configurations depending on whether or not the Error Detection and Correction (EDC) feature is selected. If the EDC feature is selected, 8 syndrome bits will be generated per every 64 bits of data. Therefore every third write burst to the SDRAM will send out the 8 syndrome bits, resulting in 24 unused bits inthe column. Therefore, using the EDC feature, there will be significantly less usable memory of data storage. The EDC function is described in the Error Detection and Correction section of this datasheet.

TABLE 5 – TOTAL USEABLE MEMORY BASED ON VARIOUS CONFIGURATIONS

COMMERCIAL AND INDUSTRIAL TEMPERATURE RANGES

MAXIMUM I/O OPERATING FREQUENCY

The sequential flow-control (SFC) device is designed to operate at the maximum frequency of 133MHz. There are certain configurations however, that can increase or decrease the maximum frequency of the input and output ports. In some configurations (e.g. x24 I/O width), the I/O speeds can run up to

166MHz. The main factors that determine the usable memory are the I/O buswidth of the SFC, the density and number of DDR SDRAMs connected, and whether or not EDC is used. Tables 6 and 7 lists the maximum frequency for the input and output ports of the SFC based on the various configurations.

TABLE 6 – IDT72T6360 MAXIMUM FREQUENCY BASED ON 166MHz DDR SDRAM

TABLE 7 – IDT72T6360 MAXIMUM FREQUENCY BASED ON 133MHz DDR SDRAM

ERROR DETECTION AND CORRECTION

The Error Detection and Correction (EDC) feature is available to ensure data integrity between the DDR SDRAM interface and the SFC. The EDC corrects all single bit hard and soft errors that are accessed from the DDR SDRAM. Multiple bit errors are not detected nor corrected.

The EDC logic blocks consist of a check bit generator and error detection correction logic. When the EDC is enabled, the check bit generator will generate 8 syndrome bits on the 8-byte boundary. The 8 syndrome bits are written into the DDR SDRAM along with the data. The SFC will burst write two cycles for data, and one cycle for syndrome bits. In order to minimize overhead and increase throughput, not all memory in the DDR SDRAM is utilized. Table 5 lists the total usable memory for all 7 configurations when the EDC is enabled.

When a read operation is performed, the syndrome bits will be transferred to the error detection correction logic block and decoded to determine whether there are any single bit errors on the data. Single bit errors will be corrected and data is passed through to the QP cache.

The EDC is enabled using the MIC[2:0] pins. When the EDC is enabled, the dynamics of the total usable memory in the DDR SDRAM and the SFC operating speed will vary, listed in Tables 6 and 7. Table 8 shows how to enable the EDC feature for the 7 configurations

TABLE 8 – MIC[2:0] CONFIGURATIONS

SETTING THE MEMORY INTERFACE SIGNALS

The configurations listed in Figure 2a-2g can be programmed into the sequential flow-control device by using the MIC[2:0], MTYPE[1:0], and MSPEED. For information about these signals, please refer to the Signal Description section. Table 9 is a list that shows the settings for the different configurations.

TABLE 9 – MEMORY CONFIGURATIONS SETTINGS

TABLE 10 – DEVICE CONFIGURATION

TABLE 11– DEFAULT PROGRAMMABLE FLAG OFFSETS

FUNCTIONAL DESCRIPTIONS

MASTER RESET AND DEVICE CONFIGURATION

During master reset the sequential flow-control configuration and settings are determined, this includes the following:

- 1. Synchronous or Asynchronous read and write port operation
- 2. Bus-width configuration
- 3. Default offset register values
- 4. IDT standard or first word fall through (FWFT) timing mode
- 5. Depth expansion in IDT standard or FWFT mode
- 6. I/O voltage set to 2.5V or 3.3V levels
- 7. JTAG function enabled or disabled
- 8. Configuration of the external memory interface

 The state of the configuration inputs during master reset will determine which of the above modes are selected. A master reset comprises of pulsing the MRS input pin from high to low for a period of time (tRS) with the configuration inputs held in their respective states. Table 10 summarizes the configuration modes available during master reset. These signals are described in detail in the signal description section.

PROGRAMMABLE ALMOST EMPTY/ALMOST FULL FLAGS

The SFC has a set of programmable flags (PAE/PAF) that can be used as an early indicator for the empty and full boundary conditions. These flags have an offset value (n, m) that will determine the almost empty and almost full boundary conditions. There are four default offset values selectable during master reset, these values are shown in Table 11, Default Programmable Flag Offsets.

Offset values can also be programmed using the serial programming pins (SCLK, SI, and SWEN). The SFC has two internal offset registers that are used to store the specific offset value, one for the $\overline{\mathsf{PAE}}$ and one for the $\overline{\mathsf{PAF}}$. The total number of bits (shown in Table 12, Number of Bits Required for Offset Registers) must be completely programmed to the offset registers. The serial programming sequence begins by writing data into the PAE register followed by the PAF register. See Figure 29, *Serial Loading of Programmable Flag Registers* for the associated timing diagram. The total number of bits required to program the offset registers will vary depending on the type of configuration that is shown in Figure 2a-2g, the bus-width selected, and whether EDC is used.

The values of n, m are used such that the PAE will become active (LOW) when there are at least one to n words written in the device. Similarly PAF will become active (LOW) when there are at least D – M words or more in the device, where D is the density of the SFC.

TABLE 12– NUMBER OF BITS REQUIRED FOR OFFSET REGISTERS

SIGNAL DESCRIPTIONS INPUTS

DATA INPUTS (D0 - D35)

Data inputs for 36-bit wide data (D0 - D35), data inputs for 18-bit wide data (D0 - D17) or data inputs for 9-bit wide data (D0 - D8).

CONTROLS

MASTER RESET (**MRS**)

A Master Reset is accomplished whenever the MRS input is toggled LOW then HIGH. This operation sets the internal read and write pointers to the first location of the RAM array. PAE will go LOW, PAF will go HIGH.

 If FWFT is LOW during Master Reset then the IDT Standard mode, along with EF and FF are selected. EF will go LOW and FF will go HIGH. If FWFT is HIGH, then the First Word Fall Through mode (FWFT), along with $\overline{\mathsf{IR}}$ and \overline{OR} , are selected. \overline{OR} will go HIGH and \overline{IR} will go LOW.

All configuration control signals must be set prior to the LOW to HIGH transition of MRS.

During a Master Reset, the output register is initialized to all zeroes. A Master Reset is required after power up, before a write operation can take place. MRS is an asynchronous function.

See Figure 6, *Master Reset and Initialization*, for the relevant timing diagram.

PARTIAL RESET (PRS)

A Partial Reset is accomplished whenever the PRS input is toggled LOW then HIGH. As in the case of the Master Reset, the internal read and write pointers are set to the first location of the RAM array, PAE goes LOW, and PAF goes HIGH.

Whichever mode is active at the time of Partial Reset, IDT Standard mode or First Word Fall Through, that mode will remain selected. If the IDT Standard mode is active, then FF will go HIGH and EF will go LOW. If the First Word Fall Through mode is active, then \overline{OR} will go HIGH, and \overline{IR} will go LOW.

Following Partial Reset, all values held in the offset registers remain unchanged. The output register is initialized to all zeroes. PRS is asynchronous.

A Partial Reset is useful for resetting the device during the course of operation, when reprogramming programmable flag offset settings may not be convenient.

See Figure 7, *Partial Reset*, for the relevant timing diagram.

ASYNCHRONOUS WRITE (ASYW)

The write port can be configured for either synchronous or asynchronous mode of operation. If during Master Reset the \overline{ASYW} input is LOW, then asynchronous operation of the write port will be selected. During asynchronous operation of the write port the WCLK input becomes WR input, this is the asynchronous write strobe input. A rising edge on WR will write data present on the data inputs into the sequential flow-control device (SFC). (WEN must be LOW when using the write port in asynchronous mode).

When the write port is configured for asynchronous operation the device must be operating on IDT standard mode, FWFT mode is not permissable. The full flag (FF) and programmable almost full flag (PAF) operates in an asynchronous manner, that is, the full flag and $\overline{\mathsf{PAF}}$ flag will be updated based in both a write operation and read operation. Note, if asynchronous mode is selected, FWFT is not permissible. Refer to Figure 24, *Asynchronous Write and* PAE *flag – IDT Standard mode* and Figure 25, *Asynchronous Write and* PAF *flag – IDT Standard mode* for relevant timing and operational waveforms.

ASYNCHRONOUS READ (ASYR)

The read port can be configured for either synchronous or asynchronous mode of operation. If during a Master Reset the ASYR input is LOW, then asynchronous operation of the read port will be selected. During asynchronous operation of the read port the RCLK input becomes RD input, this is the asynchronous read strobe input. A rising edge on RD will read data from the SFC via the output register and data output port. (REN must be tied LOW during asynchronous operation of the read port).

The OE input provides three-state control of the Qn output bus, in an asynchronous manner.

When the read port is configured for asynchronous operation the device must be operating on IDT standard mode, FWFT mode is not permissible if the read port is asynchronous. The Empty Flag (EF) and programmable almost empty flag (PAF) operates in an asynchronous manner, that is, the empty flag and PAE will be updated based on both a read operation and a write operation. Refer to Figure 23, *Asynchronous Read and* PAF *flag – IDT Standard mode*, Figure 26, *Asynchronous Empty Boundary – IDT Standard mode*, Figure 27, *Asynchronous Full Boundary – IDT Standard mode*,, and Figure 28, *Asynchronous Read and* PAE *flag – IDT Standard mode*, for relevant timing and operational waveforms.

FIRST WORD FALL THROUGH (**FWFT**)

During Master Reset, the state of the FWFT input determines whether the device will operate in IDT standard mode or First Word Fall Through (FWFT) mode.

If, at the time of Master Reset, FWFT is LOW, then IDT Standard mode will be selected. This mode uses the Empty Flag (EF) to indicate whether or not there are any words present in the SFC. It also uses the Full Flag function (FF) to indicate whether or not the SFC has any free space for writing. In IDT Standard mode, every word read from the SFC, including the first, must be requested using the Read Enable (REN) and RCLK.

If, at the time of Master Reset, FWFT is HIGH, then FWFT mode will be selected. This mode uses Output Ready (OR) to indicate whether or not there is valid data at the data outputs (Q_n) . It also uses Input Ready (\overline{IR}) to indicate whether or not the SFC has any free space for writing. In the FWFT mode, the first word written to an empty SFC goes directly to Qn after three RCLK rising edges, \overline{REN} = LOW is not necessary. Subsequent words must be accessed using the Read Enable (REN) and RCLK.

WRITE STROBE AND WRITE CLOCK (WR/WCLK)

If synchronous operation of the write port has been selected via ASYW, this input behaves as WCLK.

A write cycle is initiated on the rising edge of the WCLK input. Data setup and hold times must be met with respect to the LOW-to-HIGH transition of the WCLK. It is permissible to stop the WCLK. Note that while WCLK is idle, the FF/IR, and PAF flags will not be updated. The Write and Read Clocks can either be independent or coincident.

If asynchronous operation has been selected this input is WR (write strobe). Data is asynchronously written into the SFC via the Dn inputs whenever there is a rising edge on WR. In this mode the WEN input must be LOW.

WRITE ENABLE (WEN)

When the WEN input is LOW, data may be loaded into the SFC on the rising edge of every WCLK cycle if the device is not full. Data is stored in the RAM array sequentially and independently of any ongoing read operation.

When WEN is HIGH, no new data is written in the SFC.

To prevent data overflow in the IDT Standard mode, FF will go LOW, inhibiting further write operations. Upon the completion of a valid read cycle, FF will go HIGH allowing a write to occur. The $\overline{\text{FF}}$ is updated by two WCLK cycles + tskEw after the RCLK cycle.

To prevent data overflow in the FWFT mode, IR will go HIGH, inhibiting further write operations. Upon the completion of a valid read cycle, $\overline{\mathsf{IR}}$ will go LOW allowing a write to occur. The \overline{IR} flag is updated by two WCLK cycles + tskEW after the valid RCLK cycle.

WEN is ignored when the SFC is full in either FWFT or IDT Standard mode. If asynchronous operation of the write port has been selected, then WEN must be held active.

READ STROBE AND READ CLOCK (RD/RCLK)

If synchronous operation of the read port has been selected via ASYR, this input behaves as RCLK. A read cycle is initiated on the rising edge of the RCLK input. Data can be read on the outputs, on the rising edge of the RCLK input. It is permissible to stop the RCLK. Note that while RCLK is idle, the $\overline{\text{EF}/\text{OR}}$ and PAE flags will not be updated. The Write and Read Clocks can be independent or coincident.

If asynchronous operation has been selected this input is RD (Read Strobe). Data is asynchronously read from the SFC whenever there is a rising edge on RD. In this mode the REN and RCS inputs must be tied LOW. The OE input is used to provide asynchronous control of the three-state Qn outputs.

WRITE CHIP SELECT (WCS)

The WCS disables all Write data operations (data only) if it is held HIGH. To perform normal operations on the write port, the WCS must be enabled, held LOW.

READ ENABLE (REN)

When Read Enable is LOW, data is loaded from the RAM array into the output register on the rising edge of every RCLK cycle if the device is not empty.

When the REN input is HIGH, the output register holds the previous data and then no new data is loaded into the output register. The data outputs Q0-Qn maintain the previous data value.

In the IDT Standard mode, every word accessed at Qn, including the first word written to an empty cache, must be requested using REN provided that RCS is LOW. When the last word has been read from the SFC, the Empty Flag (\overline{EF}) will go LOW, inhibiting further read operations. REN is ignored when the SFC is empty. Once a write is performed, EF will go HIGH allowing a read to occur. The EF flag is updated by two RCLK cycles + tSKEW after the valid WCLK cycle. Both RCS and REN must be active, LOW for data to be read out on the rising edge of RCLK.

In the FWFT mode, the first word written to an empty SFC automatically goes to the outputs Qn, on the third valid LOW-to-HIGH transition of RCLK + tSKEW after the first write. REN and RCS do not need to be asserted LOW for the First Word to fall through to the output register. In order to access all other words, a read must be executed using REN and RCS. The RCLK LOW-to-HIGH transition after the last word has been read from the SFC, Output Ready \overline{OR}) will go HIGH with a true read (RCLK with $\overline{REN} = LOW; \overline{RCS} = LOW$), inhibiting further read operations. REN is ignored when the SFC is empty.

If asynchronous operation of the Read port has been selected, then REN must be held active, (LOW).

OUTPUT ENABLE (OE)

When Output Enable is enabled (LOW), the parallel output buffers receive data from the output register. When \overline{OE} is HIGH, the output data bus (Q_n) goes into a high impedance state. During Master or a Partial Reset the \overline{OE} is the only input that can place the output bus Qn, into High-Impedance. During Reset the RCS input can be HIGH or LOW, it has no effect on the Qn outputs.

READ CHIP SELECT (RCS)

The Read Chip Select input provides synchronous control of the Read output port. When RCS goes LOW, the next rising edge of RCLK causes the Qn outputs to go to the Low-Impedance state. When RCS goes HIGH, the next RCLK rising edge causes the Qn outputs to return to HIGH Z. During a Master or Partial Reset the RCS input has no effect on the Qn output bus, OE is the only input that provides High-Impedance control of the Qn outputs. If OE is LOW the Qn data outputs will be Low-Impedance regardless of RCS until the first rising edge of RCLK after a Reset is complete. Then if RCS is HIGH the data outputs will go to High-Impedance.

The RCS input does not effect the operation of the flags. For example, when the first word is written to an empty SFC, the $\overline{\mathsf{EF}}$ will still go from LOW to HIGH based on a rising edge of RCLK, regardless of the state of the RCS input.

Also, when operating the SFC in FWFT mode the first word written to an empty SFC will still be clocked through to the output register based on RCLK, regardless of the state of RCS. For this reason the user must take care when a data word is written to an empty SFC in FWFT mode. If RCS is disabled when an empty SFC is written into, the first word will fall through to the output register, but will not be available on the Qn outputs which are in HIGH-Z. The user must take RCS active LOW to access this first word, place the output bus in LOW-Z. REN must remain disabled HIGH for at least one cycle after RCS has gone LOW. A rising edge of RCLK with RCS and REN active LOW, will read out the next word. Care must be taken so as not to lose the first word written to an empty SFC when RCS is HIGH. See Figure 15 for *Read Chip Select.* If asynchronous operation of the Read port has been selected, then RCS must be held active, (tied LOW). OE provides three-state control of Qn.

BUS-MATCHING (BM[3:0])

These pins are used to define the input and output bus widths. During Master Reset, the state of these pins is used to configure the device bus sizes. All flags will operate on the word/byte size boundary as defined by the selection of bus width. See Figures 22-25 for *Bus-Matching Configurations*. See Table 13, Bus-Matching Configurations for the available configurations.

TABLE 13 – BUS-MATCHINGS

FLAG SELECT (FSEL[1:0])

During master reset, these inputs will select one of four default values for the programmable flags PAE and PAF. The selected value (listed in Table 14 -MTYPE[1:0] Configurations) will apply to both PAE and PAF offset.

MEMORY CONFIGURATION (MIC[2:0])

These signals enable the EDC feature of the device. See Table 8, MIC[2:0] Configurations for more information.

MEMORY SPEED (MSPEED)

This pin is used to determine the memory interface clock speed (CK and CK) for the external memory used. If MSPEED is HIGH, external memory CK and CK will be operating at 166MHz. If MSPEED is LOW, then the external memory CK and CK will be operating at 133MHz.

MASTER CLOCK (MCLK)

33MHz reference clock used to generate CK and $\overline{\text{CK}}$ for external memory interface.

MEMORY TYPE (MTYPE[1:0])

These signals select the density configuration of the external DDR SDRAM used. See Table 14, for selection of the memory density configuration.

DEPTH EXPANSION MODE SELECT (IDEM)

This select pin is used for depth expansion configuration in IDT Standard mode. If this pin is tied HIGH, then the $\overline{\text{FF}}$ /*IR* signal will be inverted to provide a seamless depth expansion interface. If this pin is tied LOW, the depth expansion in IDT Standard mode will be deactivated. For details on depth expansion configuration, see Figure 34, *Depth Expansion Configuration in IDT Standard Mode* and Figure 35, *Depth Expansion Configuration in FWFT Mode*.

SERIAL READ ENABLE (SREN)

The serial read enable input is an enable used for reading the value of the programmable offset registers. By setting the JSEL pin to LOW, the serial data output (SO) and serial clock (SCLK) signals can be used with SREN to program the offset registers. When $\overline{\text{SREN}}$ is LOW, data at the SO can be read from the offset register, one bit for each LOW-to-HIGH transition of SCLK. When serial read enable is HIGH, the reading of the offset registers will stop. SREN must be kept LOW in order to read the entire contents of the scan out register. If at any point SREN is toggled HIGH, the read pointer of the offset registers will reset to the first location. The next time SREN is enabled the first contents in the offset register will be read back. Serial read enable functions the same way in both IDT Standard and FWFT modes. See Figure 30, *Reading of Programmable Flag Registers,* for the timing diagram.

SERIAL WRITE ENABLE (SWEN)

The serial write enable input is an enable used for serial programming of the programmable offset registers. By setting the JSEL pin to LOW, the serial input (SI) and serial clock (SCLK) signals can be used with SWEN to program the offset registers. When SWEN is LOW, data at the SI input are loaded into the offset register, one bit for each LOW-to-HIGH transition of SCLK. When SWEN is HIGH, the offset registers retain the previous settings and no offsets are loaded. Serial write enable functions the same way in both Standard IDT and FWFT

modes. See Figure 29, *Loading of Programmable Flag Registers,* for the timing diagram.

I/O VDDQ SELECT (IOSEL)

This input determines whether the inputs and outputs will tolerate a 2.5V or 3.3V voltage signals. If IOSEL is HIGH, then all I/Os will be 2.5V levels. If IOSEL is LOW, then all I/Os will be 3.3V levels. See Table 15 for a list of affected I/O signals.

TABLE 15 – PARAMETERS AFFECTED BY I/O SELECTION

NOTE:

1. I/O to DDR SDRAM is not affected by I/O voltage selection

JTAG SELECT (JSEL)

This input determines whether the JTAG port will be activated or deactivated. If JSEL is HIGH, then the JTAG port is activated and the associated JTAG pins (TCK, TDI, TDO, TMS) are used for the boundary-scan function. If JSEL is LOW, the JTAG port is disabled and the serial programming pins (SCLK, SI, SO) will be used to program and read the offset register values for $\overline{\mathsf{PAE}}$ and PAF. See Figure 29 and 30, *Serial Loading and Reading of Programmable Registers* for information on how to program the registers.

OUTPUTS

FULL FLAG/INPUT READY (FF/IR)

This is a dual purpose pin. In IDT Standard mode, the Full Flag (FF) function is selected. When the SFC is full, FF will go LOW, inhibiting further write operations. When FF is HIGH, the SFC is not full. If no reads are performed after a reset (either MRS or PRS), FF will go LOW See *Figure 12, Full Boundary - IDT Standard Mode*, for the relevant timing information.

In FWFT mode, the Input Ready $(\overline{\mathsf{IR}})$ function is selected. $\overline{\mathsf{IR}}$ goes LOW when memory space is available for writing in data. When there is no longer any free space left, \overline{IR} goes HIGH, inhibiting further write operations. If no reads are performed after a reset (either MRS or PRS), IR will go HIGH see Figure 9 *Write First Word Cycles - FWFT Mode*, for the relevant timing information.

The $\overline{\mathsf{IR}}$ status not only measures the contents of the SFC memory, but also counts the presence of a word in the output register. Thus, in FWFT mode, the total number of writes necessary to de-assert $\overline{\mathsf{IR}}$ is one greater than needed to assert FF in IDT Standard mode.

FF/IR is synchronous and updated on the rising edge of WCLK. FF/IR are double register-buffered outputs.

EMPTY FLAG (EF/OR)

This is a dual purpose pin. In the IDT Standard mode, the Empty Flag ($\overline{\text{EF}}$) function is selected. When the SFC is empty, EF will go LOW, inhibiting further read operations. When EF is HIGH, the SFC is not empty. *Figure 10, Empty Boundary – IDT Standard Mode* for the relevant timing information.

In FWFT mode, the Output Ready (OR) function is selected. OR goes LOW at the same time that the first word written to an empty SFC appears valid on the outputs. OR stays LOW after the RCLK LOW to HIGH transition that shifts the last word from the SFC to the outputs. \overline{OR} goes HIGH only with a true read (RCLK with \overline{REN} = LOW). The previous data stays at the outputs, indicating the last word was read. Further data reads are inhibited until \overline{OR} goes LOW again. See Figure 11, *Empty Boundary (FWFT Mode)*, for the relevant timing information.

EF/OR is synchronous and updated on the rising edge of RCLK.

In IDT Standard mode, EF is a double register-buffered output. In FWFT mode, OR is a triple register-buffered output.

PROGRAMMABLE ALMOST-FULL FLAG (PAF)

The Programmable Almost-Full flag (PAF) will go LOW when the SFC reaches the almost-full condition. In IDT Standard mode, if no reads are performed after reset (MRS), PAF will go LOW after (D - m) words are written to the SFC. See *Figure 22, Synchronous* PAF*Flag - IDT Standard Mode and FWFT Mode*, for the relevant timing information.

If asynchronous PAF configuration is selected, the PAF is asserted LOW on the LOW-to-HIGH transition of the Write Clock (WCLK). PAF is reset to HIGH on the LOW-to-HIGH transition of the Read Clock (RCLK). If synchronous PAF configuration is selected, the PAF is updated on the rising edge of WCLK.

PROGRAMMABLE ALMOST-EMPTY FLAG (PAE)

The Programmable Almost-Empty flag (PAE) will go LOW when the SFC reaches the almost-empty condition. In IDT Standard mode, PAE will go LOW when there are n words or less in the SFC. The offset "n" is the empty offset value. The default setting for this value is in Table 10, Device Configuration.

In FWFT mode, the $\overline{\mathsf{PAE}}$ will go LOW when there are $n+1$ words or less in the SFC. See *Figure 21, Synchronous* PAE *Flag - IDT Standard Mode and FWFT Mode*, for the relevant timing information.

If asynchronous PAE configuration is selected, the PAE is asserted LOW on the LOW-to-HIGH transition of the Read Clock (RCLK). PAE is reset to HIGH on the LOW-to-HIGH transition of the Write Clock (WCLK). If synchronous PAE configuration is selected, the PAE is updated on the rising edge of RCLK.

DATA OUTPUTS (Q0-Q35)

(Q0-Q35) are data outputs for 36-bit wide data, (Q0 - Q17) are data outputs for 18-bit wide data or (Q0-Q8) are data outputs for 9-bit wide data.

MEMORY CLOCK OUTPUT (CK)

These signals are to be connected to the external DDR SDRAM's clock input.

MEMORY CLOCK OUTPUT INVERTED (CK)

These signals are to be connected to the external DDR SDRAM's differential clock input.

MEMORY BANK ADDRESS INPUT BIT (BA[1:0])

These signals are to be connected to the external DDR SDRAM's bank address input bits.

MEMORY COLUMN ADDRESS STROBE (CAS)

These signals are to be connected to the external DDR SDRAM's column address strobe input.

MEMORY ADDRESS BUS (A[12:0])

These signals are to be connected to the external DDR SDRAM's address bus.

MEMORY WRITE ENABLE (WE)

These signals are to be connected to the external DDR SDRAM's write enable.

MEMORY ROW ADDRESS STROBE (RAS)

These signals are to be connected to the external DDR SDRAM's row address strobe input.

BI-DIRECTIONAL I/O

MEMORY DATA INPUTS/OUTPUTS DQ[63:0]

These signals are to be connected to the external DDR SDRAM's data input bus.

MEMORY DATA STROBE OUTPUT DQS[7:0]

These signals are to be connected to the external DDR SDRAM's data strobe inputs.

ABSOLUTE MAXIMUM RATINGS

NOTES:

1. Stresses greater than those listed under ABSOLUTE MAXIMUM RATINGS may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect reliability.

2. Compliant with JEDEC JESD8-5. VCC terminal only.

PACKAGE THERMAL DATA

RECOMMENDED DC OPERATING CONDITIONS

NOTE:

1. Typically the value of VREF is expected to be (0.49-0.51) x VCC.

CAPACITANCE(TA = +25°C, f = 1.0MHz)

NOTES:

1. With output deselected, $(\overline{OE} \geq V\text{H}).$

2. Characterized values, not currently tested.

3. CIN for Vref is 20pF.

DC ELECTRICAL CHARACTERISTICS

(Commercial: Vcc = $2.5V \pm 0.125V$, TA = 0° C to +70°C; Industrial: Vcc = $2.5V \pm 0.125V$, TA = -40° C to +85°C)

POWER CONSUMPTION

General DC Test Conditions

- Measurements taken with Vcc = 2.625V, \overline{OE} = HIGH, WCLK = RCLK = 16.7MHz, MCLK = 33.3MHz
- **•** Data toggles alternately at 1/2 WCLK and RCLK frequency
- $0.4 \leq$ Vin \leq Vcc, $0.4 \leq$ Vout \leq Vcc
- Outputs are unloaded (Iout = 0)

NOTES:

- 1. These parameters are compliant under JEDEC standard for SSTL_2 (JESD8-9A). These parameters are classified as SSTL_2 Class I output buffers under section 3.2.1 of JESD8-9A.
- 2. ICC (active current) is measured with MCLK = 33.3MHz, RCLK = WCLK = 16.7MHz, and alternate 101010 data pattern toggling on the outputs.
- 3. ISB (standby current) is measured with MCLK = RCLK = WCLK = 0MHz with no output data toggling.
- 4. VSDREF is the VREF of the DDR SDRAM. It is not to be confused with the VREF of the SFC.
- 5. The maximum value may not represent the maximum current dissipated from the SFC. ICC values are dependent upon various factors that include: VCC, temperature, capacitive load, frequency, bus-width, and output switching characteristics. For calculating ICC with specific parameters, please contact IDT technical support for assistance.

2.5V LVTTL AC TEST CONDITIONS $ATIONC$

2.5V SSTL AC TEST CONDITIONS

3.3V LVTTL AC TEST CONDITIONS

AC TEST LOADS

Figure 5b. Lumped Capacitive Load, Typical Derating

AC ELECTRICAL CHARACTERISTICS⁽¹⁾ - SYNCHRONOUS TIMING

(Commercial: Vcc = 2.5V \pm 5%, TA = 0°C to +70°C; Industrial: Vcc = 2.5V \pm 5%, TA = -40°C to +85°C)

NOTES:

1. All AC timings apply to both Standard IDT mode and First Word Fall Through mode.

2. Industrial temperature range product for the 7.5ns speed grade is available as a standard device. All other speed grades are available by special order.

AC ELECTRICAL CHARACTERISTICS-ASYNCHRONOUS TIMING

(Commercial: Vcc = 2.5V \pm 5%, TA = 0°C to +70°C; Industrial: Vcc = 2.5V \pm 5%, TA = -40°C to +85°C)

NOTES:

1. All AC timings apply to both Standard IDT mode and First Word Fall Through mode.

2. Industrial temperature range product for the 7.5ns speed grade is available as a standard device. All other speed grades are available by special order.

NOTE:

1. For other signals that are latched during master reset, refer to Master Reset and Device Configuration section.

Figure 6. Master Reset and Initialization

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Figure 7. Partial Reset

NOTES:

1. tSKEW1 is the minimum time between a rising WCLK edge and a rising RCLK edge to guarantee that EF will go HIGH after one RCLK cycle (plus tREFs). If tSKEW1 is not met, then EF de-assertion may be delayed one extra RCLK cycle.

2. Settings: \overline{OE} = LOW, \overline{RCS} = LOW, \overline{WCS} = LOW, $BM[3.0]$ = 1000, FWFT = LOW, \overline{ASYR} = HIGH, and \overline{ASYW} = HIGH.

NOTES:

1. tSKEW1 is the minimum time between a rising WCLK edge and a rising RCLK edge to guarantee that EF will go HIGH after one RCLK cycle (plus tREFs). If tSKEW1 is not met, then EF de-assertion may be delayed one extra RCLK cycle.

2. Settings: $\overline{\text{OE}}$ = LOW, $\overline{\text{RCS}}$ = LOW, $\overline{\text{WCS}}$ = LOW, BM[3:0] = 1000, FWFT = HIGH, $\overline{\text{ASYR}}$ = HIGH, and $\overline{\text{ASYW}}$ = HIGH.

Figure 9. Write First Word Cycles - FWFT Mode

NOTES:

1. tSKEW1 is the minimum time between a rising WCLK edge and a rising RCLK edge to guarantee that EF will go HIGH after one RCLK cycle (plus tREFs). If tSKEW1 is not met, then EF de-assertion may be delayed one extra RCLK cycle.

2. Settings: \overline{RCS} = LOW, \overline{WCS} = LOW, $BM[3:0]$ = 1000, $FWFT$ = LOW, \overline{ASYR} = HIGH, and \overline{ASYW} = HIGH.

Figure 10. Empty Boundary - IDT Standard Mode

NOTES:

1. tSKEW1 is the minimum time between a rising WCLK edge and a rising RCLK edge to guarantee that EF will go HIGH after one RCLK cycle (plus tREFs). If tSKEW1 is not met, then $\overline{\text{EF}}$ de-assertion may be delayed one extra RCLK cycle.

2. Settings: \overline{OE} = LOW, \overline{RCS} = LOW, \overline{WCS} = LOW, BM[3:0] = 1000, FWFT = HIGH, \overline{ASYR} = HIGH, and \overline{ASYW} = HIGH.

NOTES:

1. tSKEW1 is the minimum time between a rising RCLK edge and a rising WCLK edge to guarantee that FF will go HIGH after one WCLK cycle (plus tWFFs). If tSKEW1 is not met, then FF de-assertion may be delayed one extra WCLK cycle.

2. Settings: OE = LOW, RCS = LOW, WCS = LOW, BM[3:0] = 1000, FWFT = LOW, ASYR = HIGH, and ASYW = HIGH.

NOTES:

6357 drw27 1. tSKEW1 is the minimum time between a rising WCLK edge and a rising RCLK edge to guarantee that EF will go HIGH after one RCLK cycle (plus tREFs). If tSKEW1 is not met, then EF de-assertion may be delayed one extra RCLK cycle.

2. Settings: \overline{RCS} = LOW, \overline{WCS} = LOW, BM[3:0] = 1000, FWFT = HIGH, \overline{ASYR} = HIGH, and \overline{ASYW} = HIGH.

Figure 13. Full Boundary - FWFT Mode

NOTE:

1. Settings: \overline{RCS} = LOW, BM[3:0] = 1000, FWFT = LOW, \overline{ASYR} = HIGH, and \overline{ASYW} = HIGH.

Figure 14. Output Enable

Figure 15. Read Chip Select

NOTE:

1. Settings: BM[3:0] = 1000, FWFT = LOW, \overline{ASYR} = HIGH, and \overline{ASYW} = HIGH.

Figure 16. Write Chip Select

			6 _{ns}		$7-5ns$	
Symbol	Parameter	Min.	Max.	Min.	Max.	Unit
tos	Data Setup Time	2		2.5		ns
tон	Data Hold Time	0.5		0.5	-	ns
tENS	Enable Setup Time	2		2.5		ns
TENH	Enable Hold Time	0.5		0.5		ns
ta	Data Access Time		$\overline{4}$		5	ns
to _{Hz}	Output enable to High-Z		4		5	ns
toE	Output Enable Valid		4		5	ns
twcss	WCS Setup Time	2		2.5		ns
twcsH	WCS Hold Time	0.5		0.5		ns

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NOTES:

1. tSKEW1 is the minimum time between a rising WCLK edge and a rising RCLK edge to guarantee that EF will go HIGH after one RCLK cycle (plus tREFs). If tSKEW1 is not met, then EF de-assertion may be delayed one extra RCLK cycle.

2. Settings: $\overline{OE} = LOW$, $\overline{RCS} = LOW$, $\overline{WCS} = LOW$, $BM[3:0] = 1011$, $FWFT = LOW$, $\overline{ASYR} = HIGH$, and $\overline{ASYW} = HIGH$.

NOTES:

1. tSKEW1 is the minimum time between a rising WCLK edge and a rising RCLK edge to guarantee that EF will go HIGH after one RCLK cycle (plus tREFs). If tSKEW1 is not met, then EF de-assertion may be delayed one extra RCLK cycle.

2. Settings: \overline{OE} = LOW, \overline{RCS} = LOW, \overline{WCS} = LOW, BM[3:0] = 1111, FWFT = LOW, \overline{ASYR} = HIGH, and \overline{ASYW} = HIGH.

Figure 18. Bus-Matching Configuration - x36 In to x9 Out - IDT Standard Mode

6357 drw34

NOTES:

6357 drw33 1. tSKEW1 is the minimum time between a rising WCLK edge and a rising RCLK edge to guarantee that EF will go HIGH after one RCLK cycle (plus tREFs). If tSKEW1 is not met, then EF de-assertion may be delayed one extra RCLK cycle.

2. Settings: \overline{OE} = LOW, \overline{RCS} = LOW, \overline{WCS} = LOW, BM[3:0] = 1001, FWFT = LOW, \overline{ASYR} = HIGH, and \overline{ASYW} = HIGH.

NOTES:

1. tSKEW1 is the minimum time between a rising WCLK edge and a rising RCLK edge to guarantee that EF will go HIGH after one RCLK cycle (plus tREFs). If tSKEW1 is not met, then EF de-assertion may be delayed one extra RCLK cycle.

2. Settings: \overline{OE} = LOW, \overline{RCS} = LOW, \overline{WCS} = LOW, BM[3:0] = 1101, FWFT = LOW, \overline{ASYR} = HIGH, and \overline{ASYW} = HIGH.

Figure 20. Bus-Matching Configuration - x9 In to x36 Out - IDT Standard Mode

6357 drw36

NOTES:

- 1. tSKEW2 is the minimum time between a rising WCLK edge and a rising RCLK edge to guarantee that PAE will go HIGH after one RCLK cycle (plus tPAEs). If tSKEW2 is not met, then PAE de-assertion may be delayed one extra RCLK cycle.
- 2. $n = \overline{PAE}$ offset, see Table10 for information on setting \overline{PAE} offset values.
- 3. Settings: \overline{OE} = LOW, \overline{RCS} = LOW, BM[3:0] = 1000, \overline{ASVR} = HIGH, and \overline{ASYW} = HIGH.

Figure 21. Synchronous **PAE** *Flag - IDT Standard Mode and FWFT Mode*

NOTES:

1. tSKEW2 is the minimum time between a rising WCLK edge and a rising RCLK edge to guarantee that PAF will go HIGH after one RCLK cycle (plus tPAFs). If tSKEW2 is not met, then PAF de-assertion may be delayed one extra RCLK cycle.

- 2. $m = \overline{PAF}$ offset, $D =$ density of SFC, see Table10 for information on setting \overline{PAF} offset values.
- 3. Settings: \overline{OE} = LOW, \overline{RCS} = LOW, BM[3:0] = 1000, \overline{ASYR} = HIGH, and \overline{ASYW} = HIGH.

Figure 22. Synchronous **PAF** *Flag - IDT Standard Mode and FWFT Mode*

COMMERCIAL AND INDUSTRIAL TEMPERATURE RANGES

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1. $m = \overline{PAF}$ offset, see Table10 for information on \overline{PAF} offset values. D = density of SFC.

2. Settings: \overline{OE} = LOW, \overline{RCS} = LOW, BM[3:0] = 1000, FWFT = LOW, \overline{ASYR} = LOW, and \overline{ASYW} = LOW.

3. Asynchronous read is available in IDT standard mode only.

Figure 23. Asynchronous Read and **PAF** *Flag - IDT Standard Mode*

NOTES:

1. $n = \overline{PAE}$ offset, see Table10 for information on \overline{PAE} offset values.

2. Settings: \overline{WCS} = LOW, BM[3:0] = 1000, FWFT = LOW, \overline{ASYR} = LOW, and \overline{ASYW} = LOW.

3. Asynchronous read is available in IDT standard mode only.

Figure 24. Asynchronous Write and **PAE** *Flag - IDT Standard Mode*

1. $m = \overline{PAF}$ offset, see Table10 for information on \overline{PAF} offset values. D = density of SFC.

2. Settings: \overline{WCS} = LOW, BM[3:0] = 1000, FWFT = LOW, \overline{ASYR} = LOW, and \overline{ASYW} = LOW.

3. Asynchronous read is available in IDT standard mode only.

Figure 25. Asynchronous Write and **PAF** *Flag - IDT Standard Mode*

			6ns		$7-5ns$	
Symbol	Parameter	Min.	Max.	Min.	Max.	Unit
tos	Data Setup Time	2		2.5	_	ns
İОН	Data Hold Time	0.5		0.5		ns
tAa	Data Access Time	0.6	8	0.6	10	ns
t _{PAFa}	Rising Edge to PAF		8		10	ns

NOTES:

1. Settings: \overline{OE} = LOW, \overline{RCS} = LOW, \overline{WCS} = LOW, FWFT = LOW, \overline{ASYR} = LOW, and \overline{ASYW} = LOW.

2. Asynchronous read is available in IDT standard mode only.

Figure 26. Asynchronous Empty Boundary - IDT Standard Mode

1. Settings: \overline{OE} = LOW, \overline{RCS} = LOW, \overline{WCS} = LOW, FWFT = LOW, \overline{ASYR} = LOW, and \overline{ASYW} = LOW.

2. Asynchronous read is available in IDT standard mode only.

NOTES:

1. $n = \overline{PAE}$ offset, see Table10 for information on \overline{PAE} offset values.

2. Asynchronous read is available in IDT standard mode only.

Figure 28. Asynchronous Read and **PAE** *Flag - IDT Standard Mode*

NOTES:

1. Settings: JSEL = LOW.

2. x is the required number of bits to program the PAE and PAF offset registers. See Table 12 for the numbers based on the values external configurations.

Figure 29. Serial Loading of Programmable Flag Registers (IDT Standard and FWFT Modes)

NOTES:

1. Settings: JSEL = LOW.

2. x is the required number of bits to program the PAE and PAF offset registers. See Table 12 for the numbers based on the values external configurations.

Figure 30. Reading of Programmable Flag Registers (IDT Standard and FWFT Modes)

Figure 31. Standard JTAG Timing

SYSTEM INTERFACE PARAMETERS

NOTE:

1. 50pf loading on external output signals.

JTAG AC ELECTRICAL CHARACTERISTICS

 $(*Vcc* = 2.5*V* ± 5%$; Tambient (Industrial) = 0° C to +85 $^{\circ}$ C)

NOTE:

1. Guaranteed by design.

JTAG TIMING SPECIFICATIONS (IEEE 1149.1 COMPLIANT)

The JTAG test port in this device is fully compliant with the IEEE Standard Test Access Port (IEEE 1149.1) specifications. Four additional pins (TDI, TDO, TMS and TCK) are provided to support the JTAG boundary scan interface. Note that IDT provides appropriate Boundary Scan Description Language program files for these devices.

The Standard JTAG interface consists of seven basic elements:

- *Test Access Port (TAP)*
- *TAP controller*
- *Instruction Register (IR)*
- *Data Register Port (DR)*
- *Bypass Register (BYR)*
- *ID Code Register*

The following sections provide a brief description of each element. For a complete description refer to the IEEE Standard Test Access Port Specification (IEEE Std. 1149.1-1990).

The Figure below shows the standard Boundary-Scan Architecture

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TEST ACCESS PORT (TAP)

The TAP interface is a general-purpose port that provides access to the internal JTAG state machine. It consists of three input ports (TCLK, TMS, TDI) and one output port (TDO).

THE TAP CONTROLLER

The TAP controller is a synchronous finite state machine that responds to TMS and TCLK signals to generate clock and control signals to the Instruction and Data Registers for capture and updating of data passed through the TDI serial input.

NOTES:

1. Five consecutive 1's at TMS will reset the TAP.

2. TAP controller resets automatically upon power-up.

Refer to the IEEE Standard Test Access Port Specification (IEEE Std. 1149.1) for the full state diagram

All state transitions within the TAP controller occur at the rising edge of the TCLK pulse. The TMS signal level (0 or 1) determines the state progression that occurs on each TCLK rising edge.

Test-Logic-Reset All test logic is disabled in this controller state enabling the normal operation of the IC. The TAP controller state machine is designed in such a way that, no matter what the initial state of the controller is, the Test-Logic-Reset state can be entered by holding TMS at high and pulsing TCK five times.

Run-Test-Idle In this controller state, the test logic in the IC is active only if certain instructions are present. For example, if an instruction activates the self test, then it will be executed when the controller enters this state. The test logic in the IC is idle otherwise.

Select-DR-Scan This is a controller state where the decision to enter the Data Path or the Select-IR-Scan state is made.

Select-IR-Scan This is a controller state where the decision to enter the Instruction Path is made. The Controller can return to the Test-Logic-Reset state other wise.

Capture-IR In this controller state, the shift register bank in the Instruction Register parallel loads a pattern of fixed values on the rising edge of TCK. The last two significant bits are always required to be "01".

Shift-IR In this controller state, the instruction register gets connected between TDI and TDO, and the captured pattern gets shifted on each rising edge of TCK. The instruction available on the TDI pin is also shifted in to the instruction register. TDO changes on the falling edge of TCK.

Exit1-IR This is a controller state where a decision to enter either the Pause-IR state or Update-IR state is made.

Pause-IR This state is provided in order to allow the shifting of instruction register to be temporarily halted.

Exit2-DR This is a controller state where a decision to enter either the Shift-IR state or Update-IR state is made.

Update-IR In this controller state, the instruction in the instruction register scan chain is latched in to the register of the Instruction Register on every falling edge of TCK. This instruction also becomes the current instruction once it is latched.

Capture-DR In this controller state, the data is parallel loaded in to the data registers selected by the current instruction on the rising edge of TCK.

Shift-DR, Exit1-DR, Pause-DR, Exit2-DR and Update-DR These controller states are similar to the Shift-IR, Exit1-IR, Pause-IR, Exit2-IR and Update-IR states in the Instruction path.

THE INSTRUCTION REGISTER

The instruction register (IR) is eight bits long and tells the device what instruction is to be executed. Information contained in the instruction includes the mode of operation (either normal mode, in which the device performs its normal logic function, or test mode, in which the normal logic function is inhibited or altered), the test operation to be performed, which of the four data registers is to be selected for inclusion in the scan path during data-register scans, and the source of data to be captured into the selected data register during Capture-DR.

TEST DATA REGISTER

The Test Data register contains three test data registers: the Bypass, the Boundary Scan register and Device ID register.

These registers are connected in parallel between a common serial input and a common serial data output.

The following sections provide a brief description of each element. For a complete description, refer to the IEEE Standard Test Access Port Specification (IEEE Std. 1149.1-1990).

TEST BYPASS REGISTER

The register is used to allow test data to flow through the device from TDI to TDO. It contains a single stage shift register for a minimum length in the serial path. When the bypass register is selected by an instruction, the shift register stage is set to a logic zero on the rising edge of TCLK when the TAP controller is in the Capture-DR state.

The operation of the bypass register should not have any effect on the operation of the device in response to the BYPASS instruction.

THE BOUNDARY-SCAN REGISTER

The boundary-scan register (BSR) contains one boundary-scan cell (BSC) for each normal-function input pin and one BSC for each normal-function I/O pin (one single cell for both input data and output data). The BSR is used 1) to store test data that is to be applied externally to the device output pins, and/ or 2) to capture data that appears internally at the outputs of the normal on-chip logic and/or externally at the device input pins.

THE DEVICE IDENTIFICATION REGISTER

The Device Identification Register is a Read Only 32-bit register used to specify the manufacturer, part number and version of the device to be determined through the TAP in response to the IDCODE instruction.

IDT JEDEC ID number is 0xB3. This translates to 0x33 when the parity is dropped in the 11-bit Manufacturer ID field.

For the IDT72T6360, the Part Number field contains the following values:

IDT72T6360 JTAG Device Identification Register

JTAG INSTRUCTION REGISTER

The Instruction register allows an instruction to be serially input into the device when the TAP controller is in the Shift-IR state. The instruction is decoded to perform the following:

- Select test data registers that may operate while the instruction is current. The other test data registers should not interfere with chip operation and the selected data register.
- Define the serial test data register path that is used to shift data between TDI and TDO during data register scanning.

The Instruction Register is a 4 bit field (i.e. IR3, IR2, IR1, IR0) to decode 16 different possible instructions. Instructions are decoded as follows.

JTAG INSTRUCTION REGISTER DECODING

The following sections provide a brief description of each instruction. For a complete description refer to the IEEE Standard Test Access Port Specification (IEEE Std. 1149.1-1990).

EXTEST

The required EXTEST instruction places the device into an external boundary-test mode and selects the boundary-scan register to be connected between TDI and TDO. During this instruction, the boundary-scan register is accessed to drive test data off-chip via the boundary outputs and receive test data off-chip via the boundary inputs. As such, the EXTEST instruction is the workhorse of IEEE. Std 1149.1, providing for probe-less testing of solder-joint opens/shorts and of logic cluster function.

SAMPLE/PRELOAD

The required SAMPLE/PRELOAD instruction allows the device to remain in a normal functional mode and selects the boundary-scan register to be connected between TDI and TDO. During this instruction, the boundary-scan register can be accessed via a data scan operation, to take a sample of the functional data entering and leaving the device. This instruction is also used to preload test data into the boundary-scan register before loading an EXTEST instruction.

IDCODE

The optional IDCODE instruction allows the device to remain in its functional mode and selects the optional device identification register to be connected between TDI and TDO. The device identification register is a 32-bit shift register containing information regarding the device manufacturer, device type, and version code. Accessing the device identification register does not interfere with the operation of the device. Also, access to the device identification register should be immediately available, via a TAP data-scan operation, after powerup of the device or by otherwise moving to the Test-Logic-Reset state.

CLAMP

The optional CLAMP instruction sets the outputs of an device to logic levels determined by the contents of the boundary-scan register and selects the onebit bypass register to be connected between TDI and TDO. Before loading this instruction, the contents of the boundary-scan register can be preset with the SAMPLE/PRELOAD instruction. During this instruction, data can be shifted through the bypass register from TDI to TDO without affecting the condition of the outputs.

HIGH-IMPEDANCE

The optional High-Impedance instruction sets all outputs (including two-state as well as three-state types) of an device to a disabled (high-impedance) state and selects the one-bit bypass register to be connected between TDI and TDO. During this instruction, data can be shifted through the bypass register from TDI to TDO without affecting the condition of the device outputs.

BYPASS

The required BYPASS instruction allows the device to remain in a normal functional mode and selects the one-bit bypass register to be connected between TDI and TDO. The BYPASS instruction allows serial data to be transferred through the IC from TDI to TDO without affecting the operation of the device.

DEPTH EXPANSION CONFIGURATION

The sequential flow-control (SFC) device can be connected with multiple SFCs in depth expansion to provide additional storage density that's greater than 1Gb. In depth expansion mode, two or mode devices are connected through a common transfer interface, as shown in Figure 34. The transfer clock can be a separate free-running clock or driven from the same system write or read clock.

In depth expansion configuration, the first word written to an empty configuration will pass from the first SFC to the next until it appears on the second (or last) SFC in the chain. If no reads are performed, data will begin accumulating in the second SFC until it is full. Once the second SFC is full it will disable the REN to the first SFC. At this point data will begin accumulating in the first SFC. Once both devices are full, the entire configuration is full and the full flag indicator will go LOW.

For an empty configuration, the amount of time it takes for the empty flag of the second (or last) SFC in the chain to go LOW (i.e. valid data available to be read out of the device) after a word has been written into the first FIFO is the sum of the delays for each individual SFC:

 $(N - 1)$ x (4 x transfer clock) + 3 x RCLK

Where N is the number of SFCs in the chain and RCLK is the RCLK period in ns. This latency is only noticeable for the first word written to an empty configuration. There will be no delay evident for subsequent words written into the chain.

In the full configuration, the amount of time it takes for the FF of the first SFC to go from LOW to HIGH after reading one word from the chain is the sum of the delays for each individual SFC:

 $(N - 1)$ x $(3 \times \text{transfer clock}) + 2 \times \text{WCLK}$

Depth expansion is available in both IDT Standard mode and First Word Fall Through (FWFT) mode. If IDT Standard mode is selected, the IDEM signal needs to be HIGH. If FWFT mode is selected, the IDEM signal needs to be LOW.

Figure 34. Depth Expansion Configuration in IDT Standard Mode

COMMERCIAL AND INDUSTRIAL TEMPERATURE RANGES

WIDTH EXPANSION CONFIGURATION

The sequential flow-control (SFC) device can be connected with another SFCs in width expansion to support bus-widths greater than 36-bits. This configuration connects the input and output bus of two devices together to create a wider bus. The read and write clocks for each device are driven with a clock driver. The empty and full flags of both devices are connected to a logic gate (AND/OR) depending on whether IDT Standard mode or FWFT mode is selected. Because of the variation in skew between the read clock and write clock, it is possible for EF/FF deassertion and IR/OR assertion to vary from one cycle between the devices. The logic gate connected to the status flags will create a composite flag that will update the status of both SFC devices to represent a more accurate status of the configuration. To minimize the skew between the two write and read clocks, a clock driver (IDT5T905 recommended) is used to drive the input clocks for both SFC devices. Figure 36 illustrates the width expansion configuration.

NOTES:

1. Use an AND gate in IDT Standard mode, an OR gate in FWFT mode.

2. Do not connect any output signals directly together.

ORDERING INFORMATION

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DATASHEET DOCUMENT HISTORY

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